

7.8 Constrained ML Detection

7.8.1

- Another example of more formal investigation of nonlinearities for tentative decisions is [Tan'0]. The problem investigated is ML

$$\hat{\underline{b}} = \underset{\underline{b} \in \mathcal{C}}{\operatorname{argmin}} \quad \underline{b}^{\dagger} \mathbf{G} \underline{b} - 2 \operatorname{Re}[\underline{\Sigma}^{\dagger} \underline{b}]$$

where \mathcal{C} is a closed convex set. Examples include

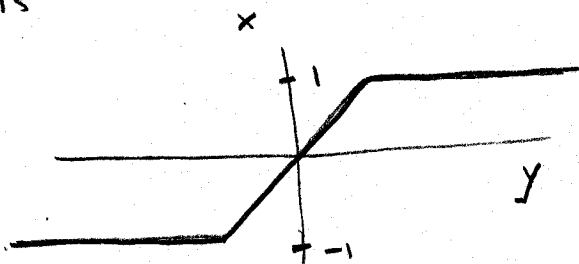
\mathbb{F}^{NK} , a sphere $\|\underline{b}\| \leq NK$ and a box $|b_{k(n)}| \leq 1, \forall k, n$.

This is one way to approximate the true constraint in the ML problem, $\underline{b} \in \{-1, +1\}^{NK}$.

- Central to the method is the notion of projection of a vector \underline{y} in \mathbb{F}^{NK} onto \mathcal{C} . It's the point \underline{x} in \mathcal{C} that's closest to the vector \underline{y} in Euclidean norm.

$$\underline{x} = \mathcal{P}_{\mathcal{C}}(\underline{y}) = \underset{\underline{z} \in \mathcal{C}}{\operatorname{argmin}} \|\underline{y} - \underline{z}\|$$

For the sphere constraint, the projection works on the whole vector. ($\underline{x} = NK \underline{y} / \|\underline{y}\|$). For the box constraint, we can apply it element by element. If real it's



a clipper

- [Tan 0] present an iteration for solution of this constrained ML problem. In its general form:

$$\underline{b}^{(j+1)} = \mu P_c \left[\underline{b}^{(j)} - \omega E_j (G \underline{b}^{(j)} - \underline{y} + H(\underline{b}^{(j+1)} - \underline{b}^{(j)})) \right] + (1-\mu) \underline{b}^{(j)}$$

where $\left\{ \begin{array}{l} 0 < \mu \leq 1 \\ \omega > 0 \end{array} \right\}$ are parameters

and for element-separable projections (like box)

H is strictly lower triangular, strictly upper or zero

E_j is positive diagonal

but if not element separable

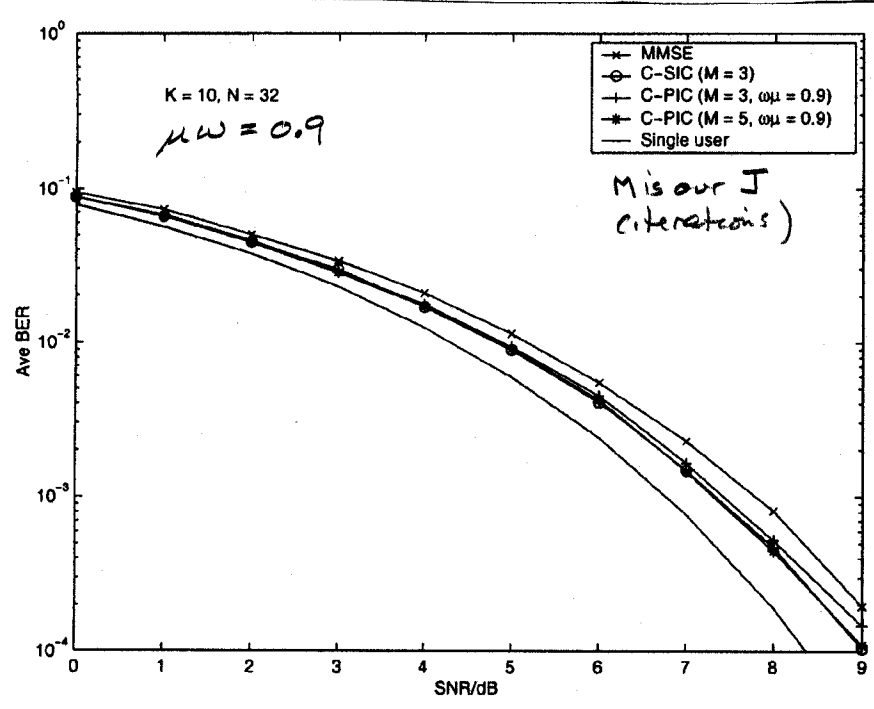
H is zero

$E_j = I$

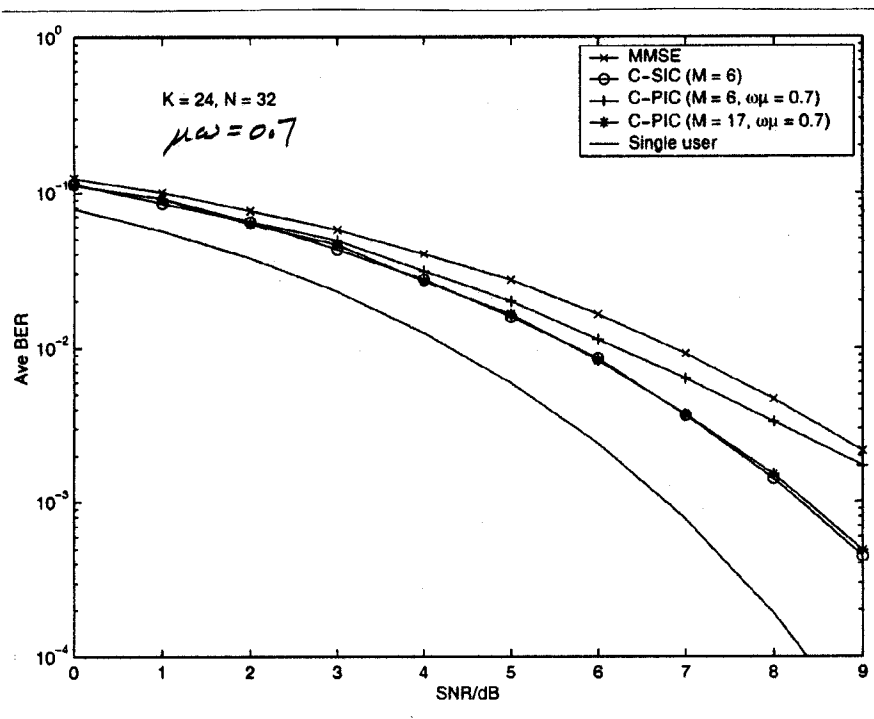
- If $H=0$, then $\underline{b}^{(j+1)}$ depends only on $\underline{b}^{(j)}$, reminiscent of Jacobi. This is a PIC

- If $H=U$ or $H=L$ then it's a SIC, since $\underline{b}^{(j+1)}$ depends on newly determined elements of $\underline{b}^{(j+1)}$ in addition to past values: use $H=L$, $E_j = D^{-1}$, $\mu=\omega=1$.

The performance of box constrained (clipped) ML in AWGN, equipower, $N_c = 32$ chips.



- Lightly loaded
- SIC, PIC similar performance
- PIC requires a few more iterations



- Heavy loading
- PIC needs 17 iterations for the same performance as SIC with 6
- significantly better than MMSE

Adaptable to pipeline in asynch conditions.