

6.2 Pulse Shaping for Zero ISI in PAM

6.2.1
P+S 8.2

- We have seen in Section 6.1 that zero ISI is desirable. Achieving it, even for the simple AWGN channel, requires care — and a compromise with the other goal of low bandwidth occupancy.
- This section addresses some of the issues in zero-ISI pulse design for PAM systems. Our model is

$$v(t) = \sum_k a_k g_T(t - kT) \quad \text{and our topic is } g_T(t).$$

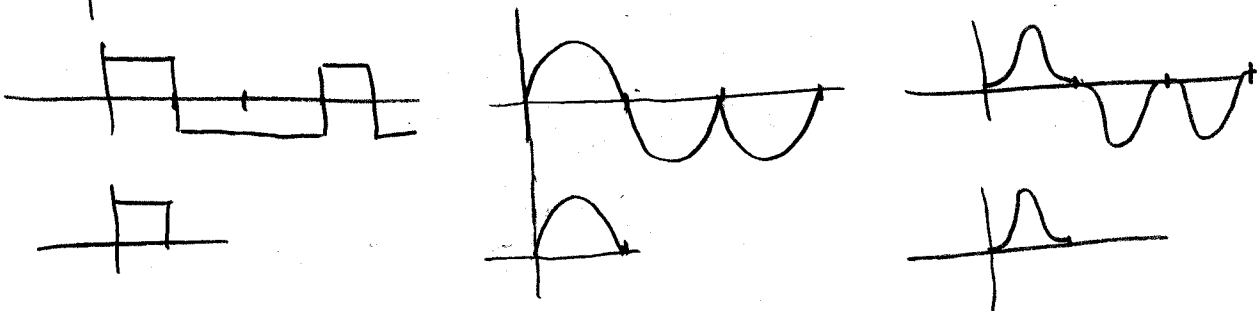
- First, bandwidth occupancy, as determined by the power spectrum $S_v(f)$. For zero mean, iid symbols a_k , we have seen that (p. 2.4.6)

$$S_v(f) = \frac{\sigma_a^2}{T} |G_T(f)|^2$$

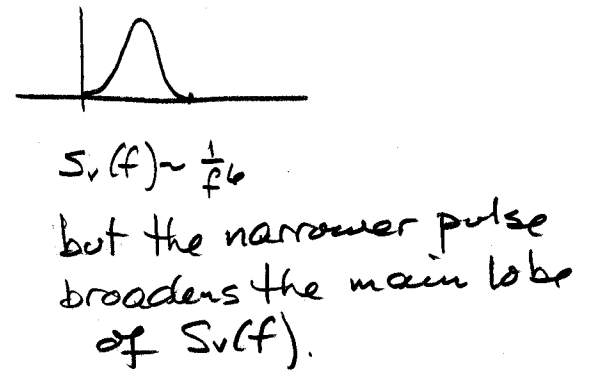
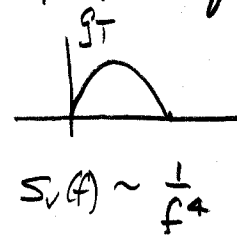
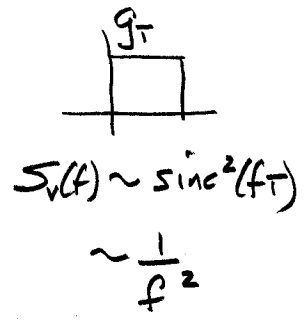
Read P+S 8.1.2 for the more general version with non zero mean. We'll do correlation of a_k later.

Single-Interval Pulses

- The easiest way to guarantee zero ISI (in absence of channel filter) is a pulse limited to a single interval:

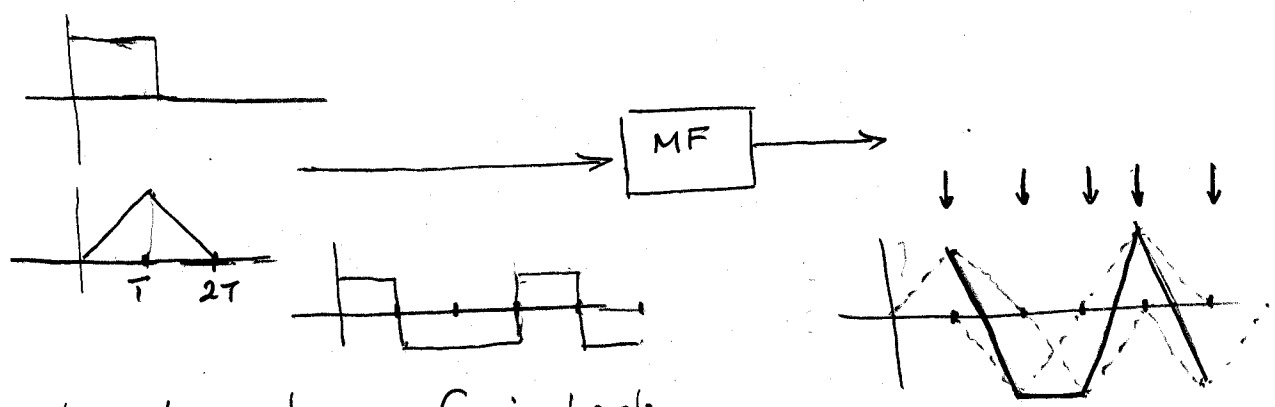


- Pay a bandwidth price for this method.
 - the order of derivative containing the first discontinuity determines decay of frequency sidelobes:



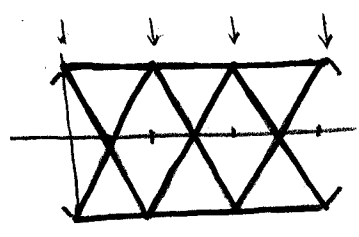
• Why is the ISI zero?

Consider the MF output $R_{g_T}(t)$ (pulse autocorr fn)



The pulse autocorr fn is back to zero for the next sample.

On a scope with trigger set properly:



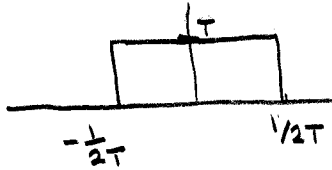
an "eye diagram"

Sinc Pulses

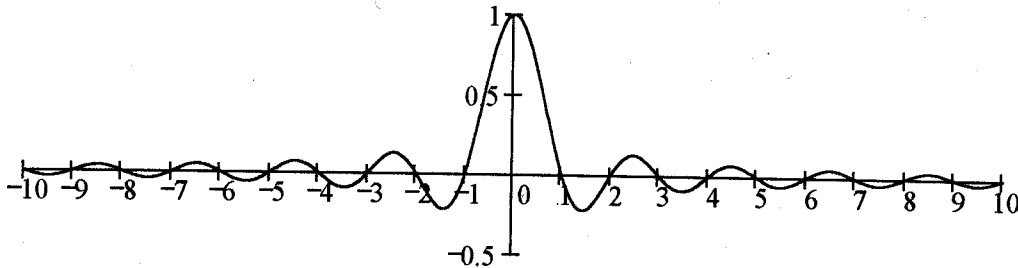
- An inspiration — sinc pulses have regular zero crossings and are bandlimited! Looks like we can have it all!

$$v(t) = \sum_k a_k \operatorname{sinc}\left(\frac{t}{T} - k\right) = \sum_k a_k \operatorname{sinc}\left(\frac{t}{T} - k\right)$$

- But... it's hard to implement

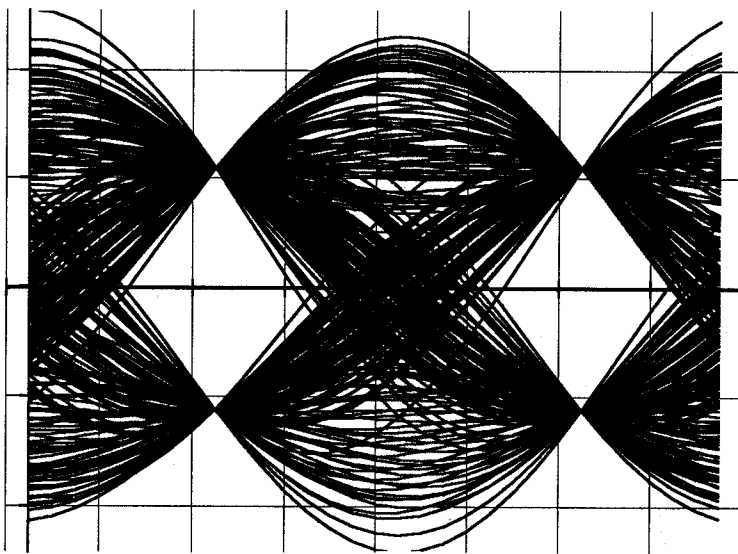


same shape, T_x and R_x



dies out slowly

and the signal can be large between the sample points.



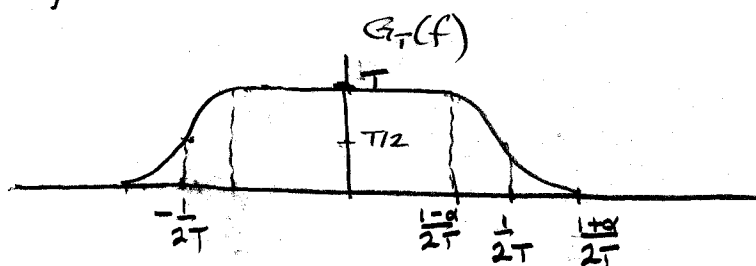
eye diagram for sinc pulses

$$y_m = a_m x_0 + v_m$$

and it's hard to synchronize to sinc pulses,
and a little synch error costs a lot of noise margin

The Spectral Raised Cosine Family

- This is the most widely-used method in signalling today. DSP made use of it possible.
- Compromise — use a little extra bandwidth to obtain a smooth $G_T(f)$ and a $g_T(t)$ that dies out more quickly.



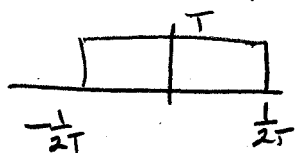
Raised cosine
rolloff factor α
 $0 \leq \alpha \leq 1$.

$$G_T(f) = T \begin{cases} 1 & |f| \leq \frac{1-\alpha}{2T} \\ \frac{1}{2} \left(1 - \sin \left(\frac{\pi T}{\alpha} \left(|f| - \frac{1-\alpha}{2T} \right) \right) \right) & \frac{1-\alpha}{2T} \leq |f| \leq \frac{1+\alpha}{2T} \\ 0 & |f| \geq \frac{1+\alpha}{2T} \end{cases}$$

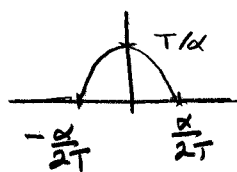
The corresponding $g_T(t)$ can be obtained by inverse transforming to obtain

$$g_T(t) = \text{sinc}(t/T) \frac{\cos(\pi \alpha t/T)}{1 - 4(\alpha t/T)^2}$$

Alternatively, note that $G_T(f)$ is convolution of



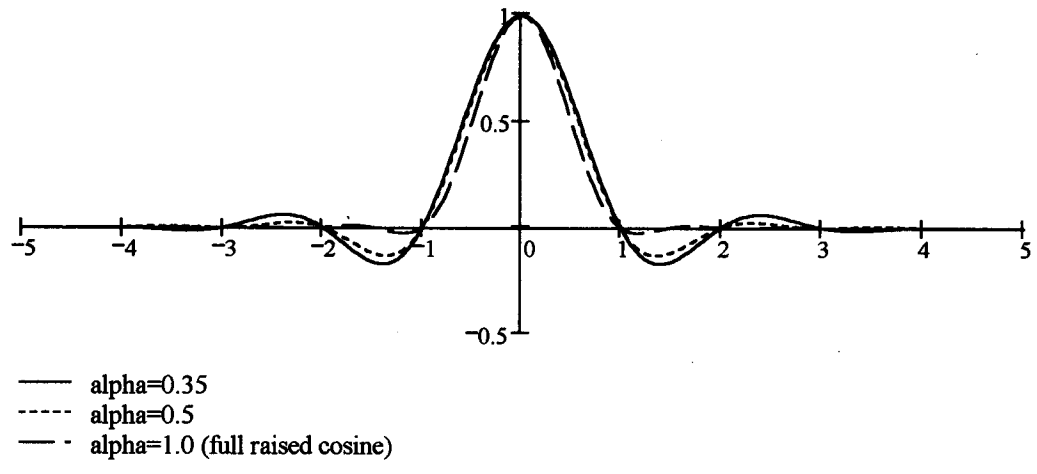
and



$$\frac{T}{\alpha} \cos\left(\pi \alpha \frac{t}{T}\right)$$

giving

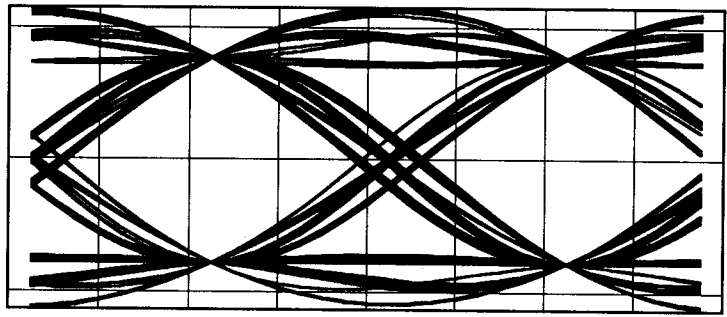
$$g_T(t) = \frac{\pi}{4} \text{sinc}\left(\frac{t}{T}\right) \left(\text{sinc}\left(\alpha \frac{t}{T} + \frac{1}{2}\right) + \text{sinc}\left(\alpha \frac{t}{T} - \frac{1}{2}\right) \right)$$



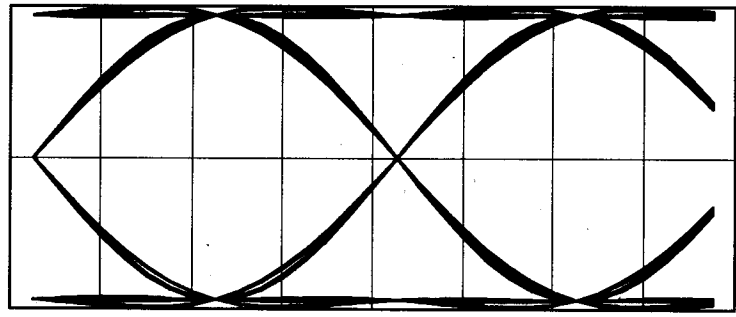
Raised Cosine Pulses, Different Rolloffs

- regular, zero crossings
- dies out quickly especially for $d=1$, so easier to implement than $\alpha=0$ (sinc function).

• The eye diagram is cleaner than for sinc pulses:



Rolloff Factor
 $\alpha = 0.5$

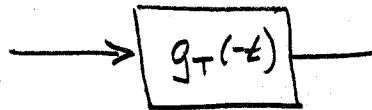


Rolloff Factor
 $\alpha = 1$

Less dynamic range required,
less sensitivity to timing errors.

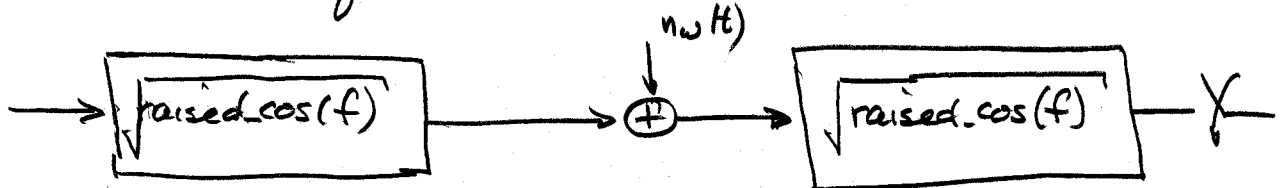
• Wait a minute! We still have to put the pulse through a matched filter

6.26

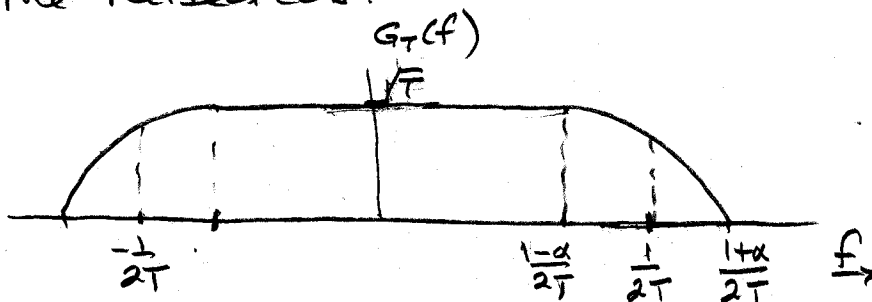


and $g_T(t) \otimes g_T(-t)$ loses its zero-ISI property.

Solution: the square root raised cosine pulse shape



This is matched, for good noise performance, and has a composite pulse shape that equals the raised cos.

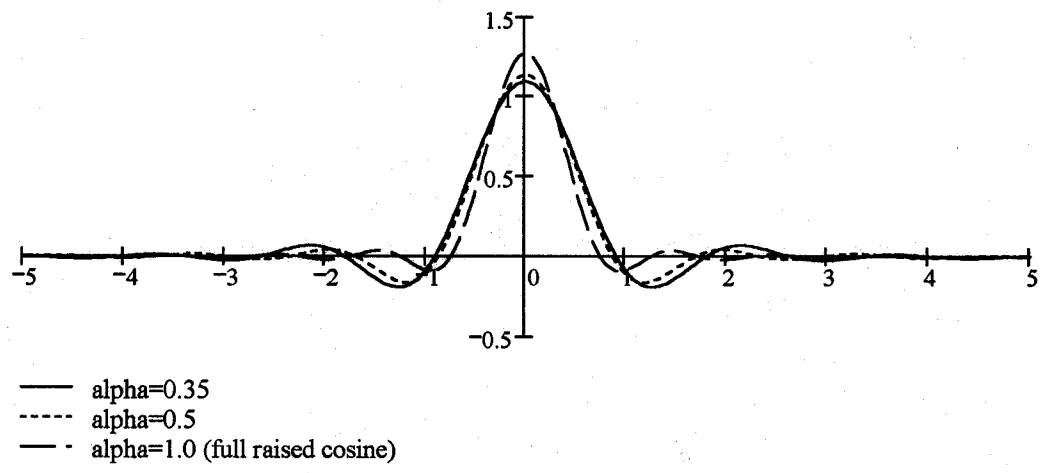


$$G_T(f) = \sqrt{T} \begin{cases} 1, & |f| \leq (1-\alpha)/2T \\ \cos\left(\frac{\pi T}{2\alpha} \left(|f| - \frac{1-\alpha}{2T}\right)\right), & \frac{1-\alpha}{2T} \leq |f| \leq \frac{1+\alpha}{2T} \\ 0, & |f| \geq (1+\alpha)/2T \end{cases}$$

for which [SChennakeshu, VTC'91]

$$g_T(t) = \frac{1}{\sqrt{T}} \begin{cases} 1 - \alpha + \frac{4}{\pi} \alpha, & t = 0 \\ \frac{\alpha}{\sqrt{2}} \left[\left(1 + \frac{2}{\pi}\right) \sin\left(\frac{\pi}{4\alpha}\right) + \left(1 - \frac{2}{\pi}\right) \cos\left(\frac{\pi}{4\alpha}\right) \right], & |t| = \frac{1}{4\alpha} \\ \frac{\sin(\pi(1-\alpha)|t|) + 4\alpha|t| \cos(\pi(1+\alpha)|t|)}{\pi|t|(1-(4\alpha t)^2)}, & \text{elsewhere} \end{cases}$$

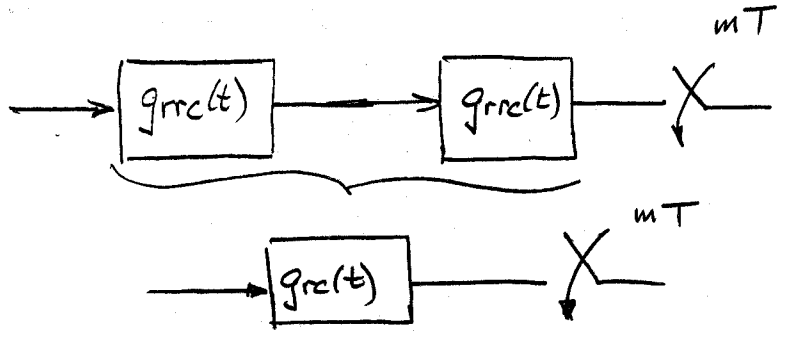
and here it is, the most widely used pulse shape in communications.



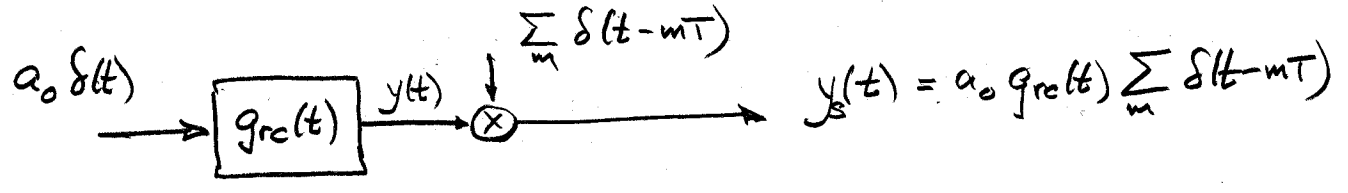
Square Root Raised Cosine Pulses

Nyquist's Criterion

- What was it about the raised cos pulse that gave zero ISI?

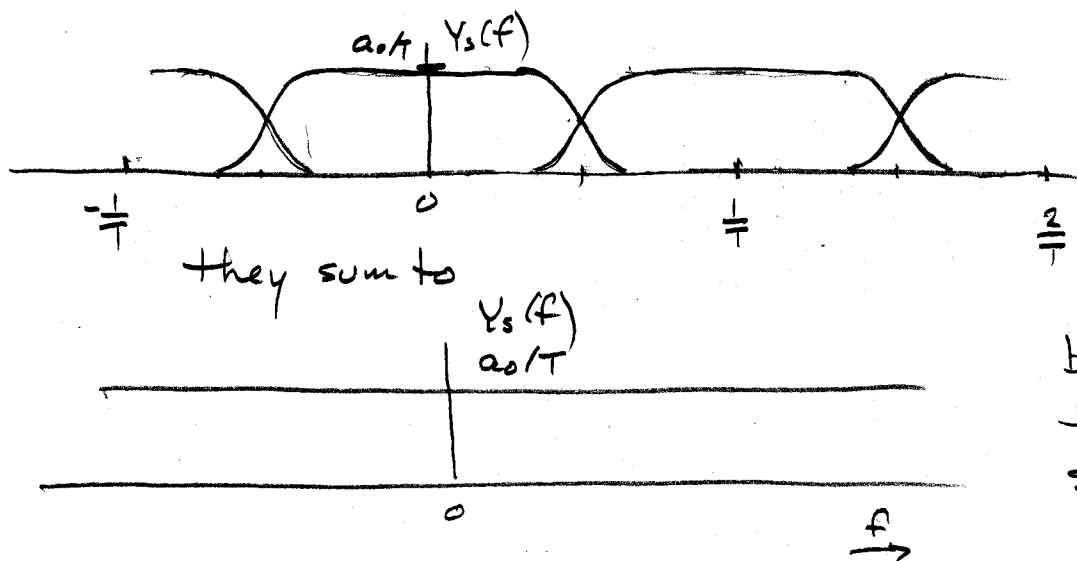


- Model as impulse weighted data, impulse sampling



From sampling theory,

$$Y_s(f) = \frac{a_0}{T} \sum_k G_{rc}(f - k/T)$$



so $y_s(t) = \frac{a_0}{T} \delta(t)$ and no ISI

Read P+S 8.2.1