

Motivation :

Why should we learn about circuits ?

- Integrated circuits :
 - digital ICs
 - analog ICs

- Software CAD tools :
 - process simulators
 - device
 - diodes
 - transistors
 - MOS
 - BJT
 - circuits : SPICE
 - Pspice
 - Hspice
 - systems and interconnects
 - synthesis tools

- Control
- instrumentation
- power systems
- bioengineering

The fundamental laws :

- energy
- information

their

- generation
- conversion
- transmission
- utilization

Variables: charge
current
voltage
power

Model

Theory

Scientific method:

observations
postulate a model
establish relationship
among variables
< Laws >

Basic circuit laws: Ohm's
Kirchhoff's } Laws
Coulomb's

Most fundamental: conservation of energy
atomic theory of matter

Systems of units: Systeme international
SI

Basic quantities: length
mass
time
electric current
temperature
luminance

Basic units: meter
kilogram
second
ampere

Electric current:

→ Charge: • electron $\times 6.25 \times 10^{18}$ = coulomb
 \downarrow 1.6×10^{-19} coulomb

Charles Augustin de Coulomb: 1736-1806
 two "Coulomb's laws"

• Law of $F = k \cdot \frac{q_1 \cdot q_2}{d^2}$ • $r_1 \cdot r_2$
 q_1 q_2

→ Average current = $\frac{\Delta q}{\Delta t}$
 ampere (A) = $\frac{1C}{1sec}$

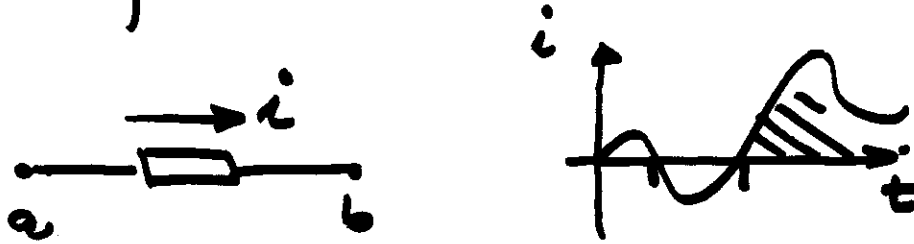
André Marie Ampère: 1775-1836

Ampère's Law (electrodynamics)

$$i = \lim_{\Delta t \rightarrow 0} \frac{\Delta q}{\Delta t}$$

$$i = \frac{dq}{dt} \Rightarrow q(t) = \int_0^t i(s) ds$$

Current reference direction:

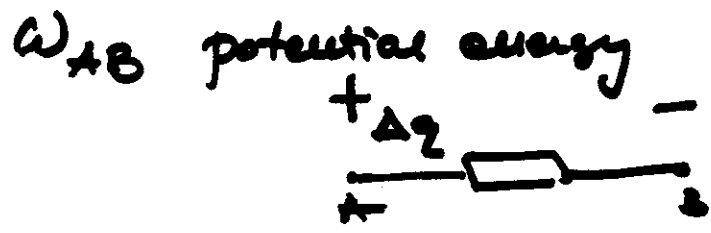


orientation vs. direction

Choose a reference orientation, and only then calculate the value!

Voltage: q_1^+ \leftarrow Coulomb forces \rightarrow q_2^-
 \downarrow
 Stored energy
 \equiv electric potential energy



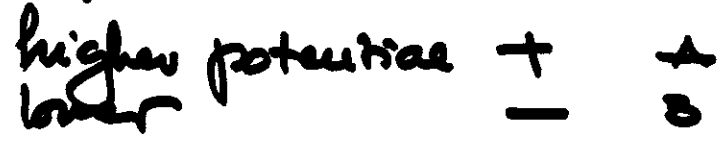


$$V_{AB} = \frac{dW_{AB}}{dq}$$

potential drop
or voltage

Volts: Alessandro Volta: 1745-1827

Voltage reference:

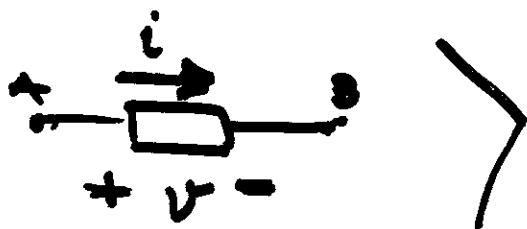


Polarity: = orientation

< voltage across two points
current through an element >

Energy and Power:

Ability to do work: kinetic (motion)
potential (position)



$$\Delta W_{AB} = V \cdot \Delta q$$

$$\frac{\Delta W_{AB}}{\Delta t} = V \cdot \frac{\Delta q}{\Delta t}$$

$$\frac{\Delta W_{AB}}{\Delta t} = V \cdot i$$

← average current

The rate at which energy has been expended by other parts of the circuit?

Unit: joule (=) newton·meter

mechanical energy = force · distance delivered

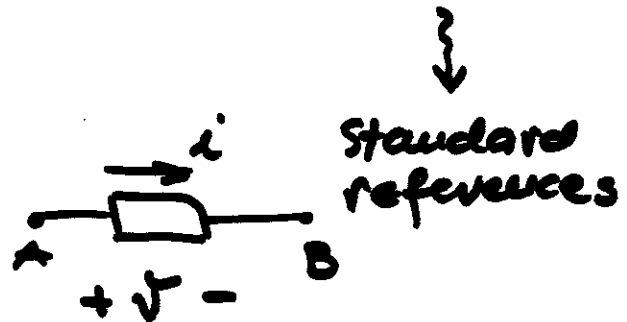
Power:

delivered to a device (element part of a circuit)

$$\rightarrow p(t) = \frac{dw(t)}{dt}$$

$$w(t) = \int p(x) dx$$

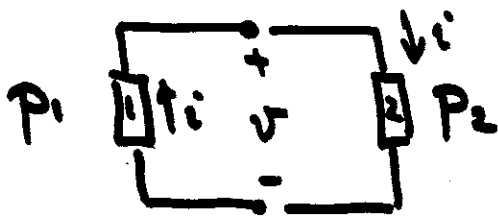
$$\rightarrow p = v \cdot i$$



James Watt, 1736 - 1819

$$1 \text{ Watt} = \frac{1 \text{ Joule}}{1 \text{ sec}}$$

References.



$$P_1 = -v i$$

$$P_2 = v i$$

power delivered to a branch

Delivered power = absorbed power

Electric Circuits and Models:

Physical electrical devices:

wires resistors
 diodes capacitors
 transistors inductors
 batteries, generators
 transformers, relays, motors
 :

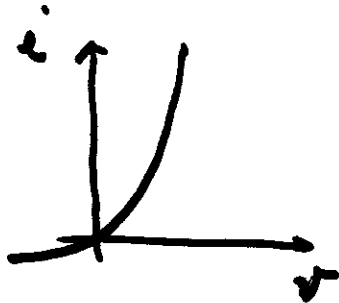
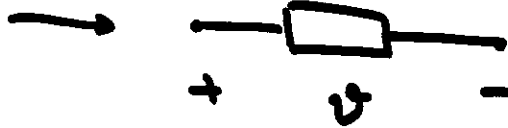
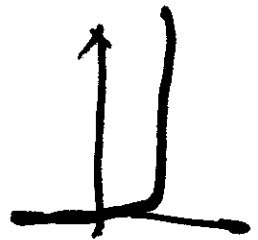
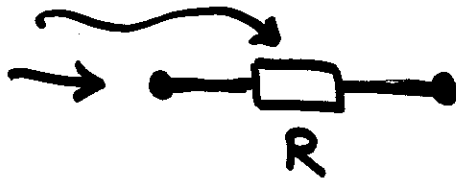
are connected into physical circuits

↓
ideal models

↓
connected into circuits.



$$R = \rho \cdot \frac{l}{S}$$



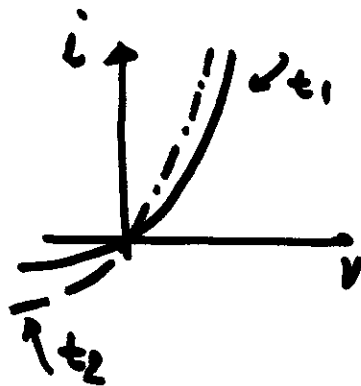
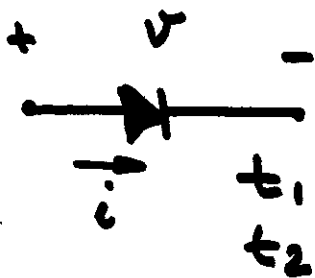
Various conditions require various models!

Ex:

temperature

aging

charge cause variation models for transistors



If:

Physical properties are localized:

Geometry of the device does not matter

↳ lumped elements
(circuits)

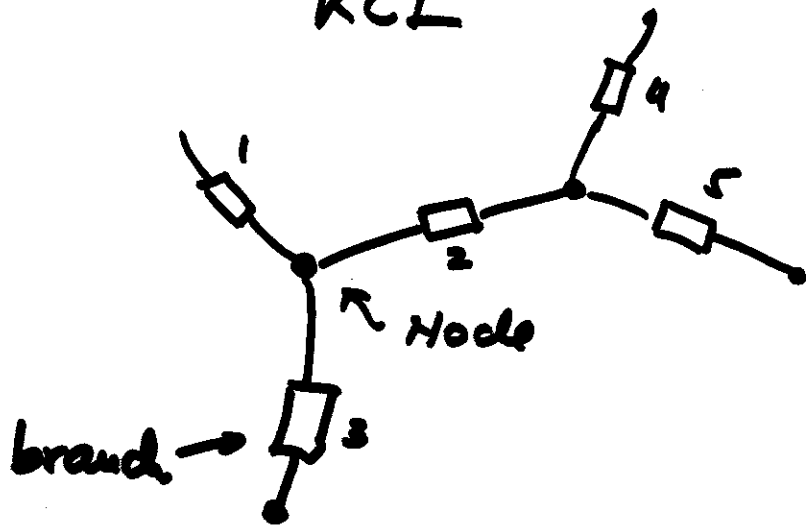
Otherwise:

Distributed (important when:

high frequencies

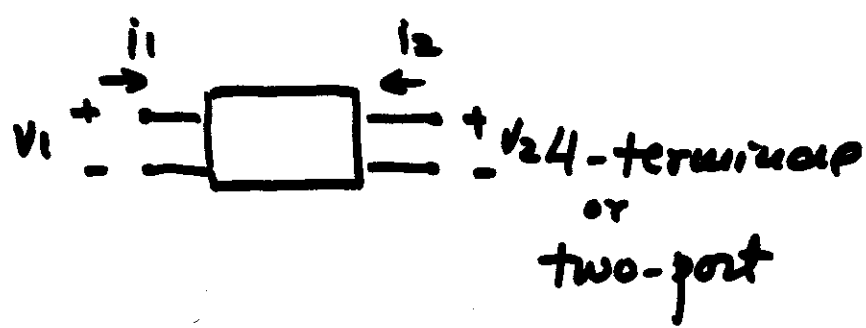
Small geometries)
(size)

Kirchhoff's Current Law KCL

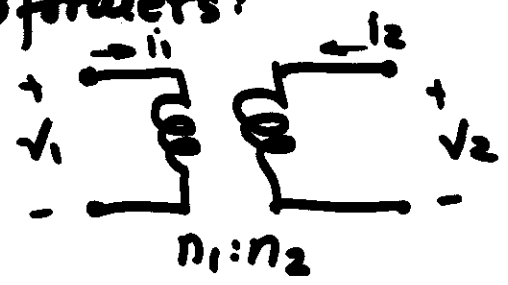


Elements:

- Two-terminal
- Three-terminal

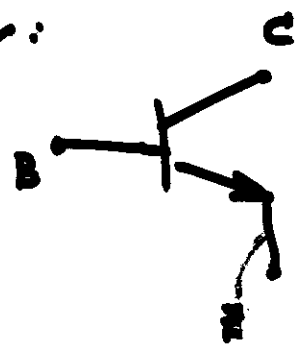


Transformers:



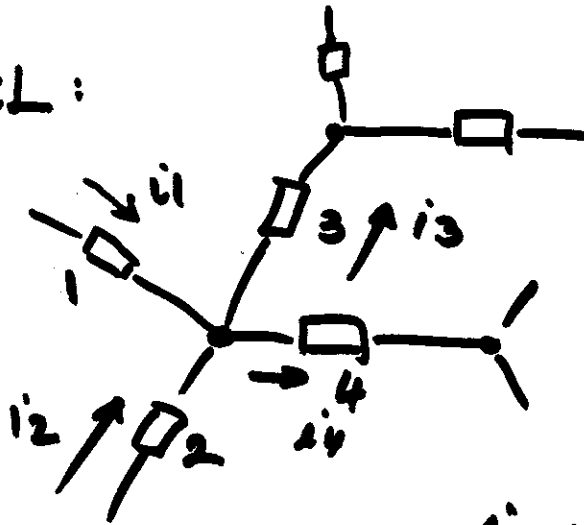
Transistor:

BJT



Three-terminal
(Two-port)

KCL:



- Circuit vs
- Network

$$i_1 + i_2 - i_3 - i_4 = 0$$

At each node in any electrical network and at each instant of time, the algebraic sum of all currents leaving a node is zero

↑
(entering)

Conservation of charge:

$$\int i_1 dt + \int i_2 dt - \int i_3 dt - \int i_4 dt = 0$$

$$q_1 + q_2 - q_3 - q_4 = 0$$

Principle of conservation!

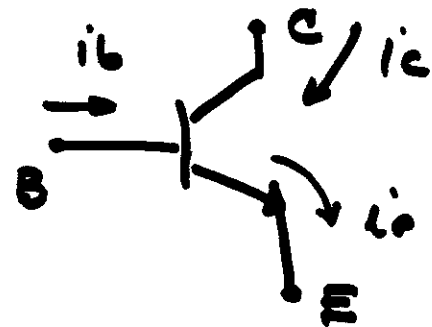
⇓
KCL

KCL (2nd form):

13

At any instant of time, the net current leaving (or entering) an electrical element having any number of terminals must be zero

BJT
Bipolar Junction Transistor



$$i_b + i_c - i_e = 0$$

$$-i_b - i_c + i_e = 0$$

\Downarrow

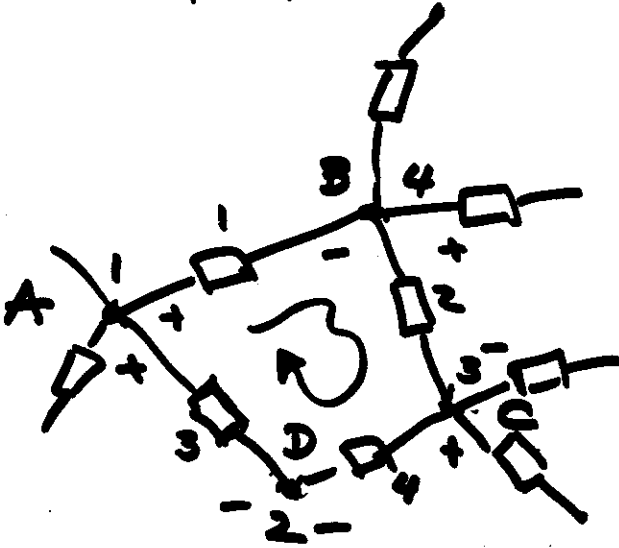
$$i_b + i_c = i_e$$

KCL (3rd form):

At each node and at all times, Σ all currents with reference, oriented away from a node
 $= \Sigma$ all currents with reference, oriented toward the node.

Kirchhoff's Voltage Law

KVL



$$V_{AB} - V_{BC} + V_{CD} + V_{DA} = 0$$

$$V_{AB} = V_1$$

$$V_{BC} = V_2$$

$$V_{CD} = V_3$$

$$V_{DA} = -V_4$$

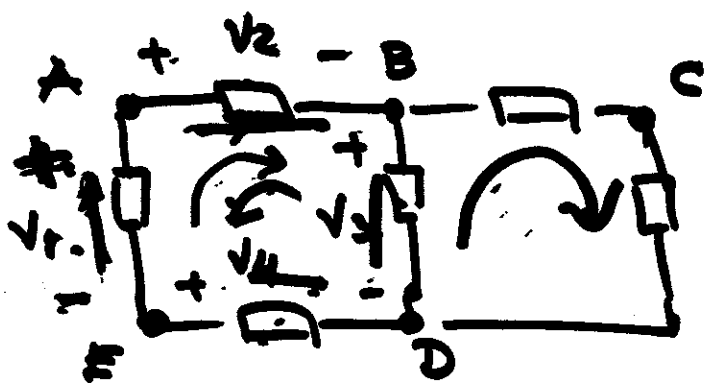
$$V_1 + V_2 + V_3 - V_4 = 0 \quad \checkmark$$

KVL:

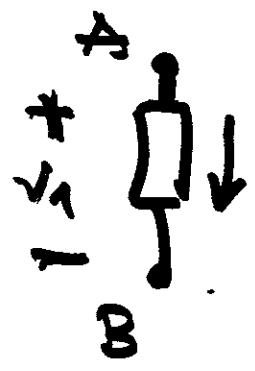
The algebraic sum of all voltages encountered in traversing any closed path in a lumped connected circuit is zero at any instant of time.

KVL (2nd form)

In a lumped connected circuit, the sum of all voltages along a closed path with references that agree with a clockwise traversal of the path equals the sum of all voltages whose references agree with a counterclockwise traversal of the path.



$$v_1 - v_2 - v_3 + v_4 = 0$$

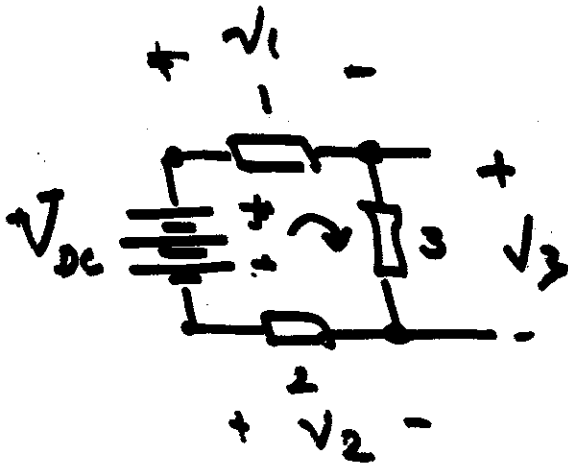
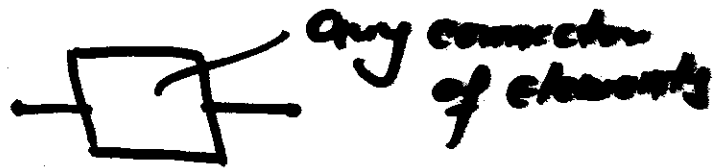
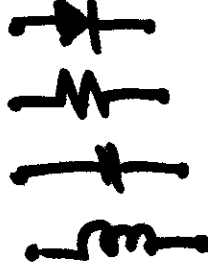
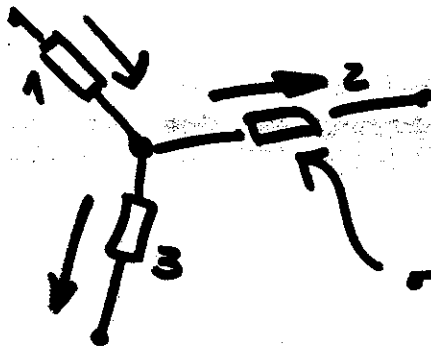


$$v_{AB} = v_1$$

$$v_3 + v_2 - v_1 - v_4 = 0 \quad (-1)$$

More on KCL and KVL:

- Topological Laws



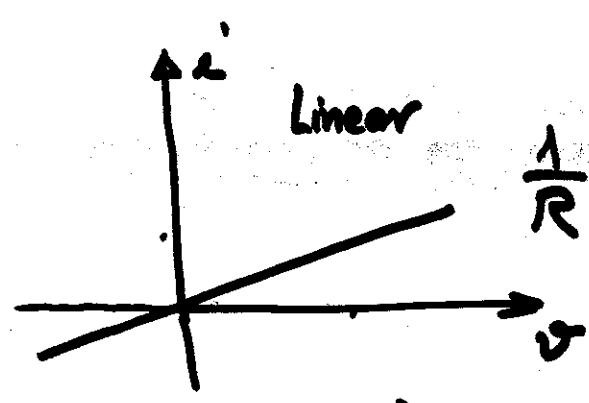
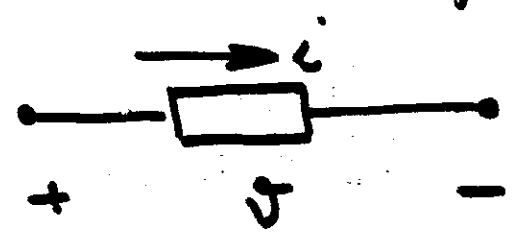
Used to calculate voltages and currents in a circuit

Equation: Sets of linear equations
 All coefficients +1 or -1!
 Are they independent?

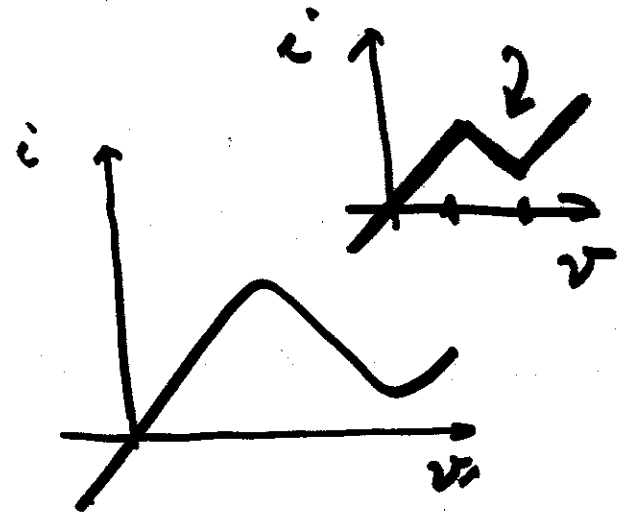
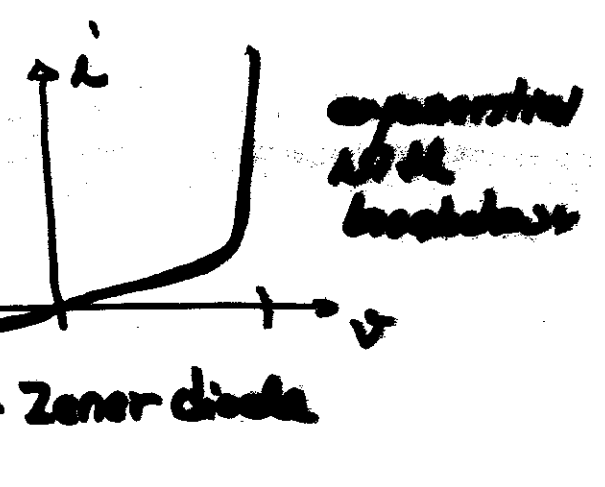
$$V_{DC} - v_1 - v_3$$

$$\uparrow \quad \nearrow v_2 = 0$$

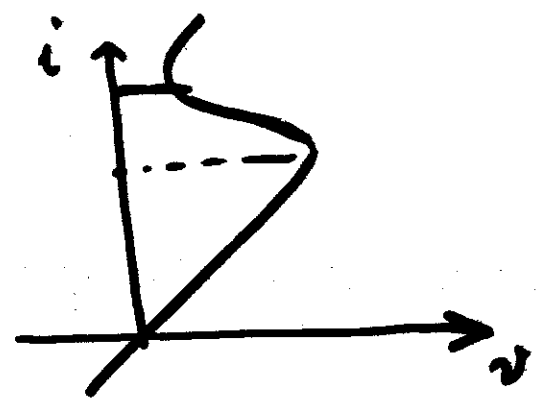
Two-terminal components



$$\frac{1}{R} = G$$



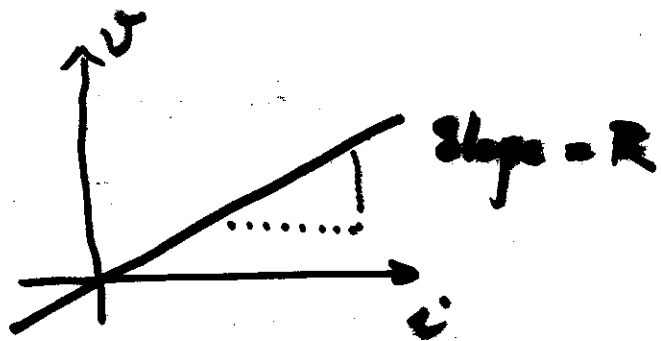
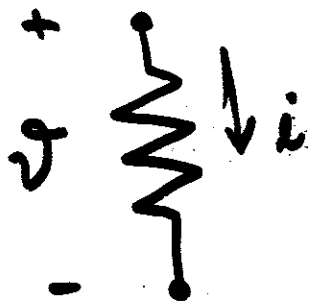
Nonlinear
N-type



Nonlinear
S-type

(Mode of Transistors)
and resistors

Linear Resistor:



$$V = R \cdot i$$

↑ constant
≠ f(V, i)

Ohm's Law: $V = R \cdot i$ $\langle *t \rangle$

Georg Simon Ohm (1789-1854)

R = resistance

$$1\Omega = \frac{1V}{1A}$$

Range: 1Ω $1k\Omega$ $1M\Omega$

$R = 0$: Short circuit ---

$R = \infty$: open circuit ---o---

$$i = \frac{1}{R} \cdot v$$

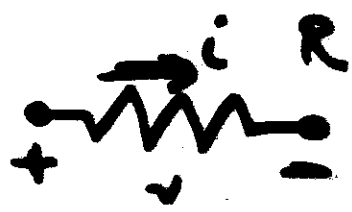
↑ conductance
(Siemens; mho
reverse of Ohm)

Power and Energy:

$$p = v \cdot i$$

$$\rightarrow p = R i^2$$

$$\rightarrow = G \cdot v^2 \quad \uparrow \text{instantaneous!}$$



$$W_R = \int R i^2(s) ds$$

$$\int G \cdot v^2(s) ds$$

Always absorbed by R
Never delivered to the rest of the circuit

R: power ratings (max power they can dissipate)
tolerance

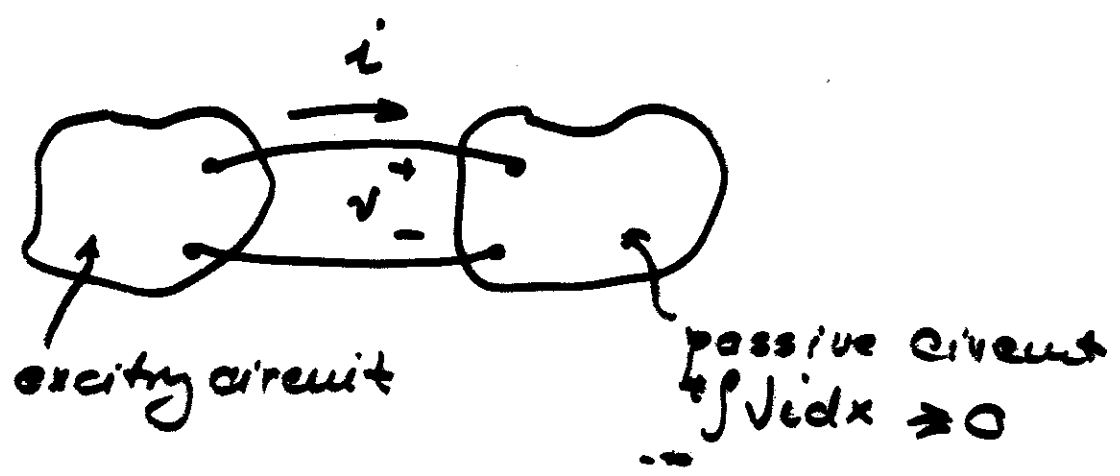
Passive vs. Active components:

$$W(t) = \int_{-\infty}^t v(x) \cdot i(x) dx \quad \forall t$$

$$W(t) = W(0) + \int_0^t v(x) \cdot i(x) dx$$

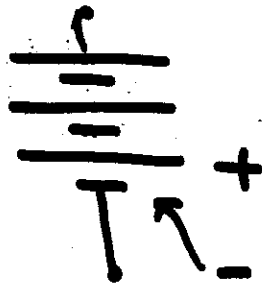
Passive components: $W(t) \geq 0 \quad \forall t$

If $W(t) < 0$ for some t
 \downarrow Active components

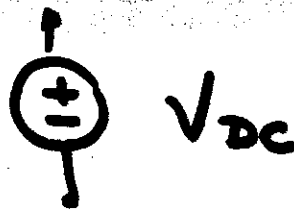


Sources:

Batteries



voltage sources



phase



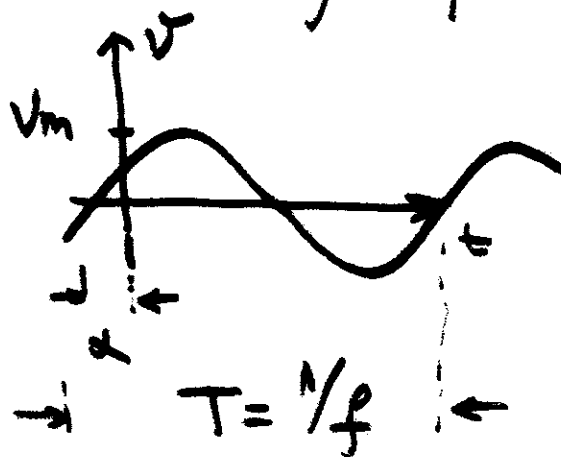
$$v = V_m \sin(\omega t + \phi)$$

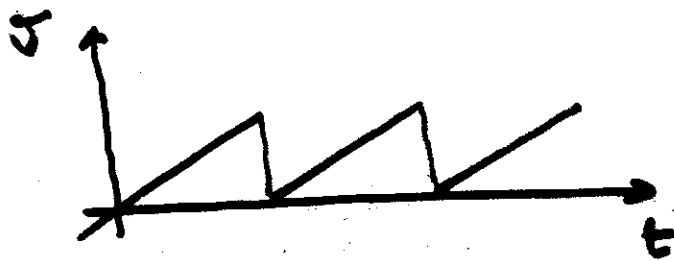
↑
max

↑
frequency

$$\omega = 2\pi f$$

$$f = \frac{1}{T}$$



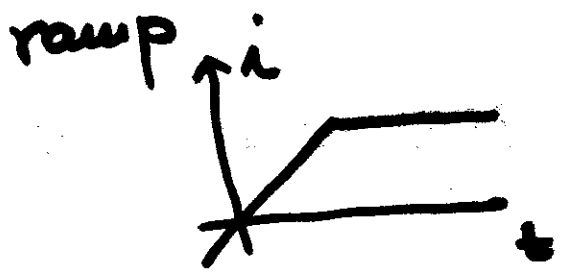


Time dependent

Current sources:



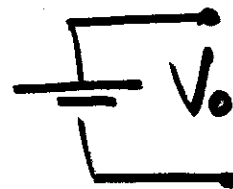
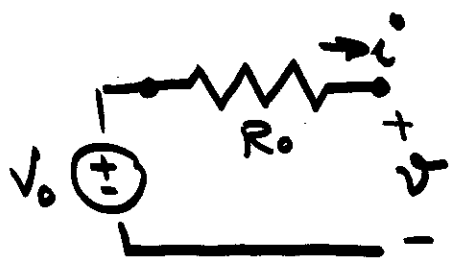
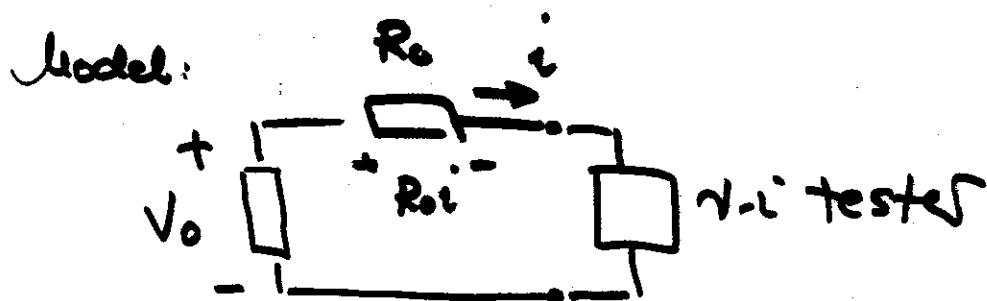
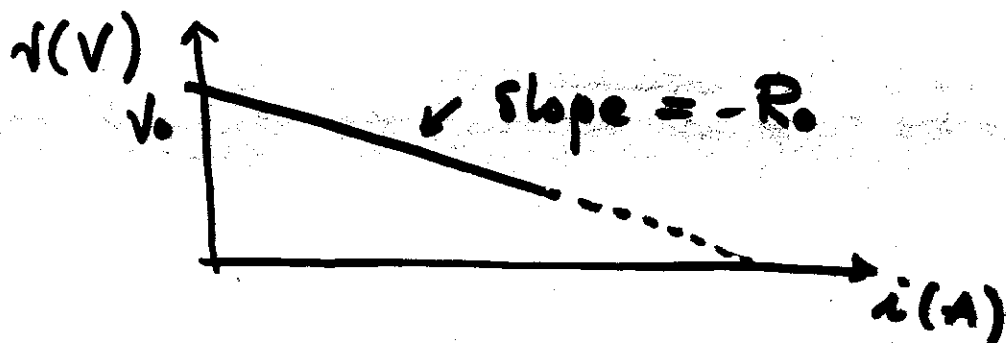
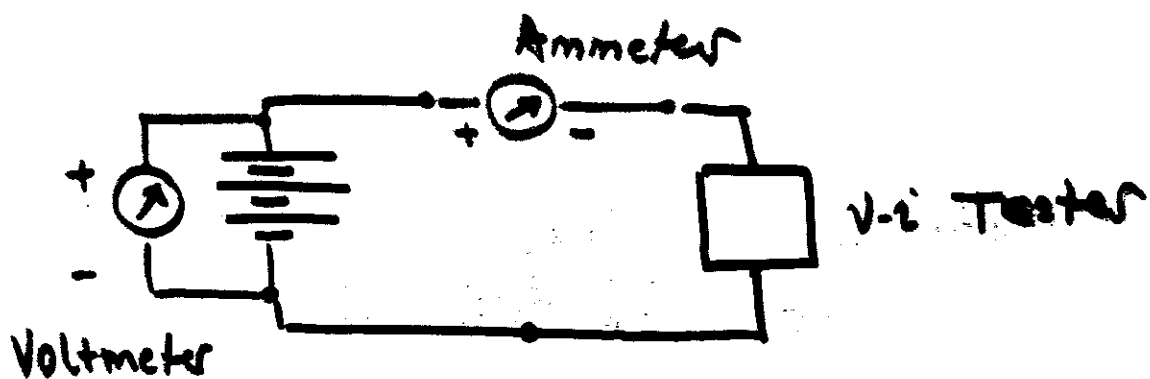
DC
 $\text{Im} \sin(\omega t + \phi)$
 Saw-tooth



Active elements:

$$\omega(t) = \int_0^+ p(s) ds > 0$$

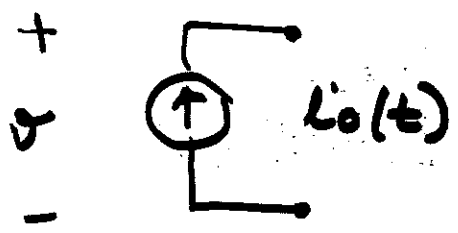
↑
generated



$$v = V_0 - R_0 i$$

if small $\Rightarrow v = V_0$
Not dependent on i

The current source:

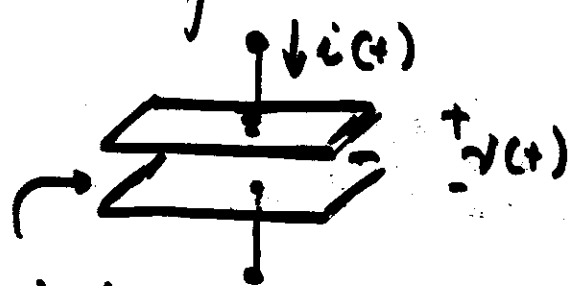


Does not depend on voltage V

Ideal!

< Current sources are often built from voltage sources and nonlinear resistive elements (transistors) to provide current that does not depend on voltage across the sources' terminals >

The Capacitor :



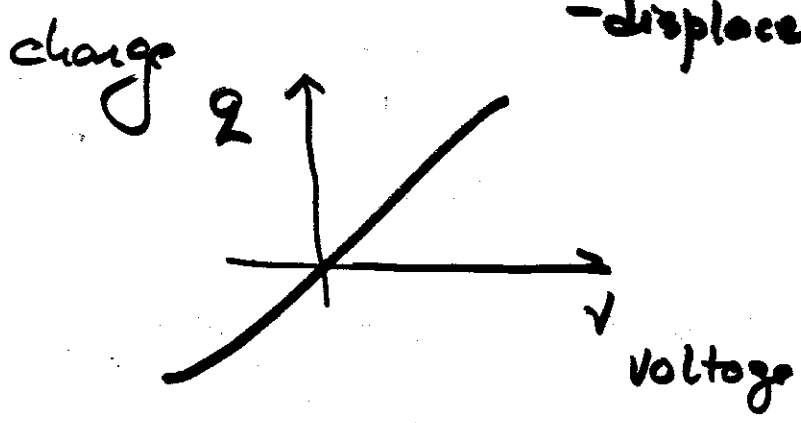
- dielectric
- air
 - paper
 - cloth
 - ...

Electromagnetic field:

James Maxwell (1831-1879)

Maxwell equations:

- displacement current -



$$q = \text{function}(v)$$

$$q(t) = \text{function}(v(t))$$

↑ time
↑ time

Current: $i = \frac{dq}{dt}$; $i = \frac{dq}{dv} \cdot \frac{dv}{dt}$

$$C = \frac{dq}{dv}$$

↑ capacitance

(farad : F)

↘ $\frac{\text{Coulomb}}{\text{volt}}$

Afr: Michael Faraday (1791-1867).

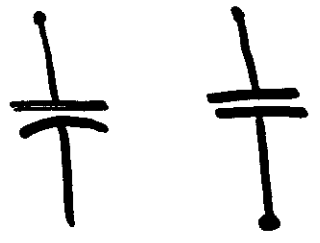
in general: $C = \text{function}(r)$

↑ nonlinear capacitor

If $C = \text{constant}$

$$\text{then } q = C \cdot v$$

$$i = C \frac{dv}{dt}$$



$$i(t) = C \cdot \frac{dV(t)}{dt}$$

$$\Rightarrow V(t) = \frac{1}{C} \int_{t_0}^t i(x) dx$$

or

$$V(t) = \frac{1}{C} \int i(x) dx + \underline{V(t_0)}$$

Constant!

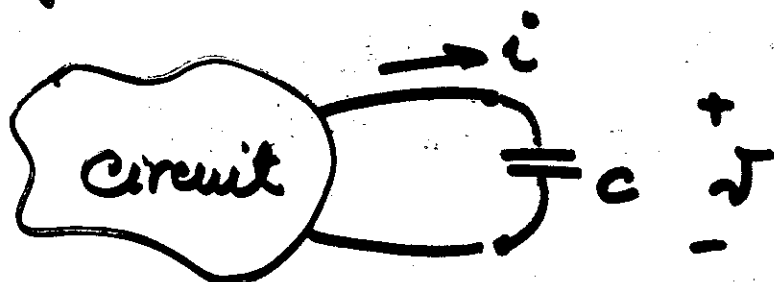
\equiv initial value
of V at $t = t_0$

Manufactured: slopes
sizes
dielectric > C
power limits

Dielectric strength: = $\frac{\text{Voltage}}{\text{Thickness}}$

Voltage rating = Dielectric strength
x thickness

Capacitor Energy:



Power: $P_c = v i$

$$P_c = v \cdot C \frac{dv}{dt}$$

Energy:

$$W_c = \int_{-v}^{+v} C \cdot v \cdot \frac{dv}{dx} \cdot dx$$

$$W_c = \int_{-v}^{+v} C \cdot v \cdot dv$$

$$= \frac{1}{2} \cdot C \cdot [v^2(+)-v^2(0)]$$

$$\boxed{W_c(+)-W_c(0)} = \frac{1}{2} C v^2(+)$$

or. proportional $\sim q^2(+)$

$$C \geq 0$$

$$v^2(+)\geq 0$$

Capacitor is a passive element

$$W_c(t) \geq 0 \quad \forall t$$

↑ For any t !

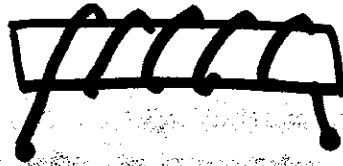
Energy is stored! (Unlike resistors where it is dissipated into heat!)

In a non-ideal case:

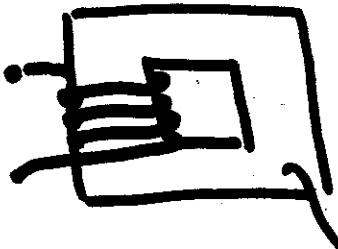
Some energy will be lost due to "leakage". i.e., a resistance present in the dielectric material

The inductor

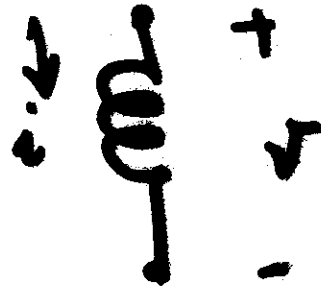
Also a two-terminal element



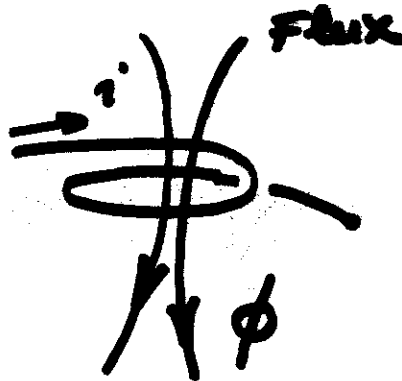
Solenoid



iron core



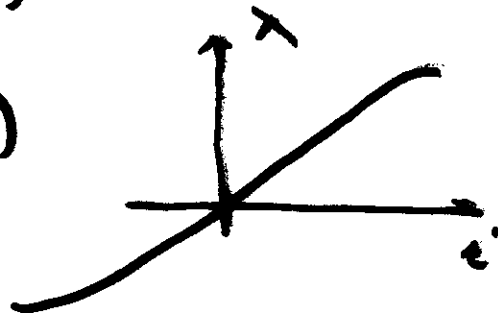
Magnetic flux
Faraday



Theory of electromagnetic fields:

Self-flux:

$$\lambda = f(i)$$



If the dependence is linear:

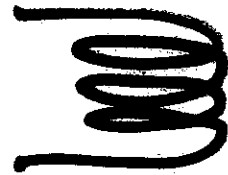
$$\lambda = L \cdot i$$

↑ inductance
Henry = $\frac{\text{Weber}}{\text{Ampere}}$

L depends on: medium (permeability)
geometry

$$L = k \cdot N^2$$

↗ Number of turns



$N=3$

Faraday: Discovered induction:

$$v = \frac{d\lambda}{dt}$$

$$v = \frac{d}{dt}(Li)$$

Linear:

$$v = L \cdot \frac{di}{dt} \leftarrow$$

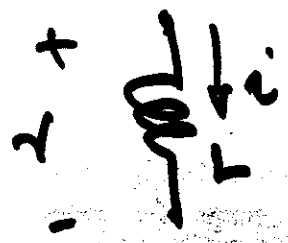
L: may be a
function of i
 $\frac{1}{t}$

Hence:

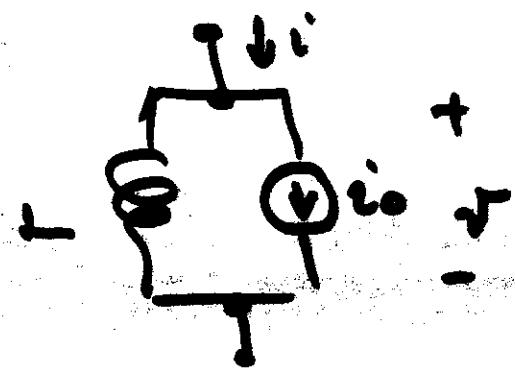
$$i(t) = \int_{t_0}^+ v(x) dx + i(t_0) \leftarrow \text{initial value}$$

Joseph Henry (1797-1878)

Contemporary to Faraday.



No initial energy



With initial energy

Energy:

← Power

$$p = vi$$

$$p = Li \cdot \frac{di}{dt}$$

$$W_L(t) = \int_0^t Li \cdot \frac{di}{dt} \cdot dt$$

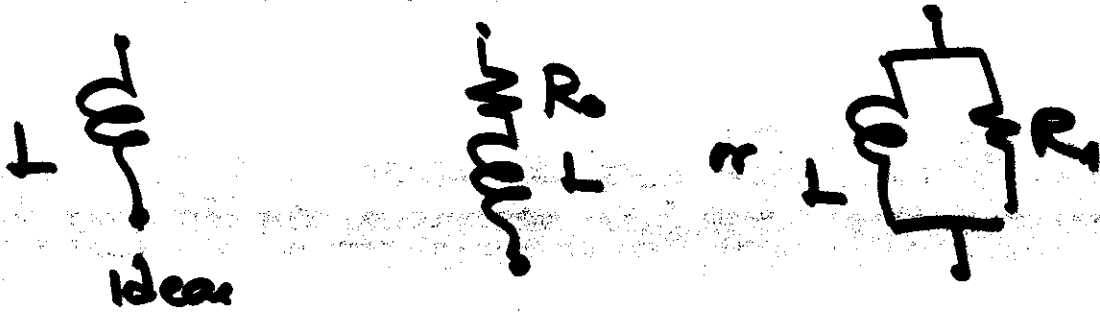
$$W_L(t) = \int_0^t L \cdot i \cdot di$$

$$= \frac{1}{2} L \{ i^2(t) - i^2(t_0) \}$$

$$W_L(t) - W_L(t_0) = \frac{1}{2} L \cdot i^2(t)$$

Energy is stored!

in case of leakage - some will be transformed into heat.



Conservation of: charge
flux

Hence: Capacitor: $i = C \cdot \frac{dv}{dt}$
 ↗ continuous

inductor: $v = L \frac{di}{dt}$

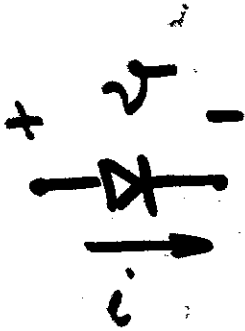
Linear: $C > 0$
 $L > 0$ > Passive!
 ↗ continuous.

The Diode

pn-junction : semiconductor device

p: material with
"dopants" that add
+ charges (holes)

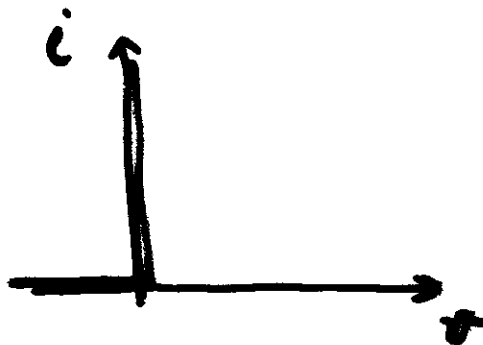
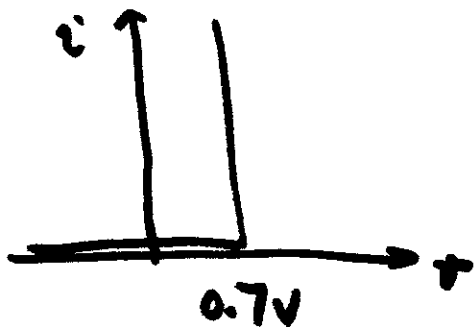
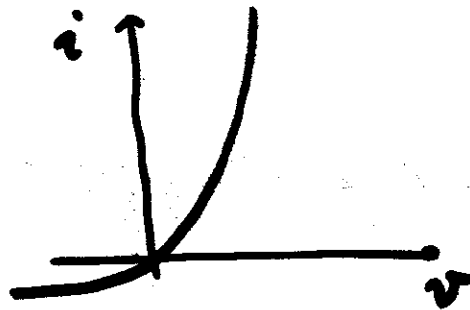
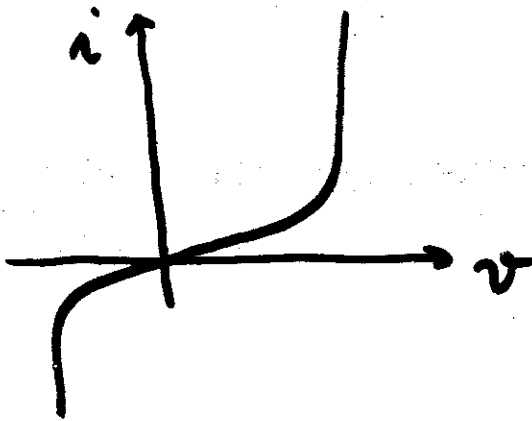
n: - charges (electrons)

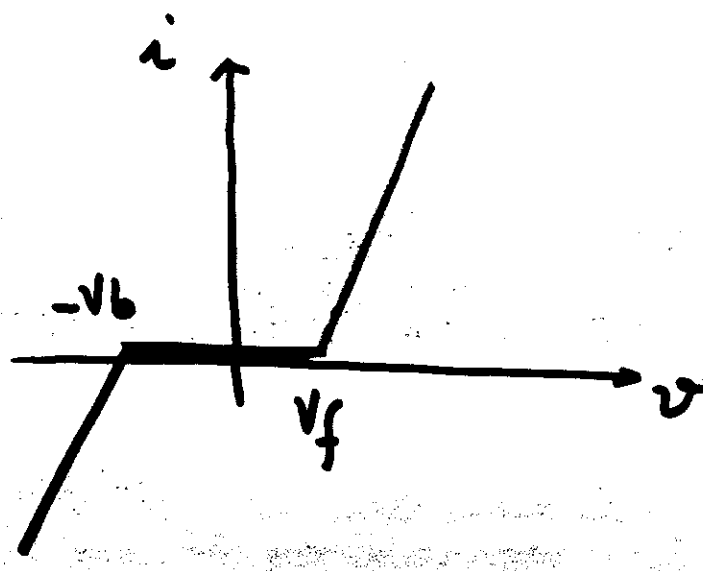


diode

nonlinear element

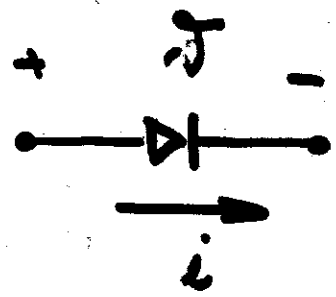
two-terminal





V_f : forward offset
0.7 V

V_b : reverse breakdown

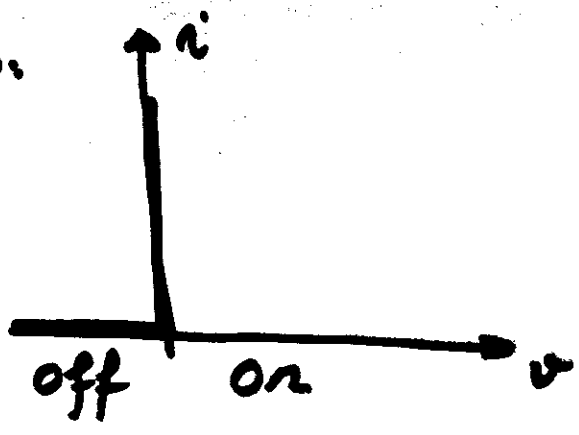


$v < -V_b$: resistor

$-V_b < v < V_f$: $i = 0$

$v > V_f$: resistor

Ideal diode:



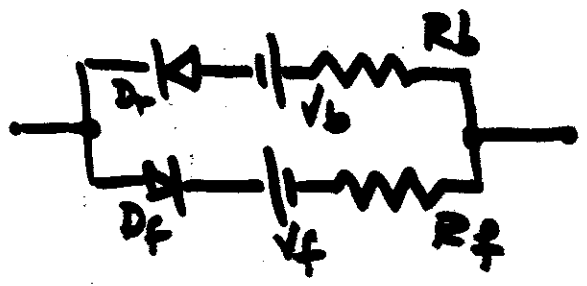
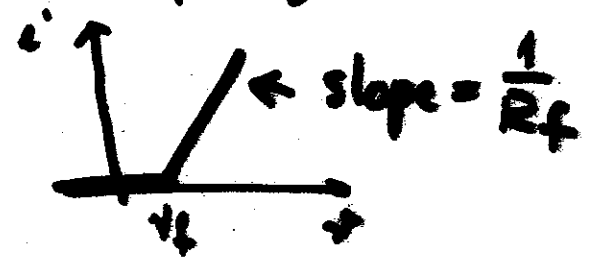
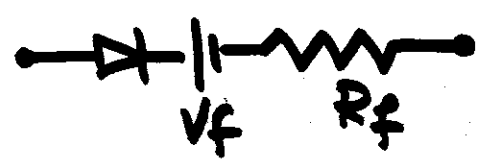
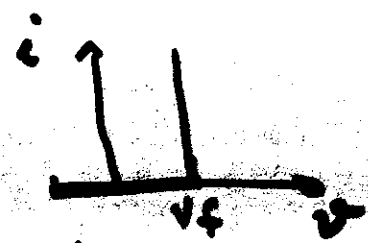
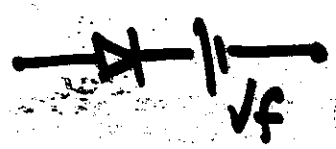
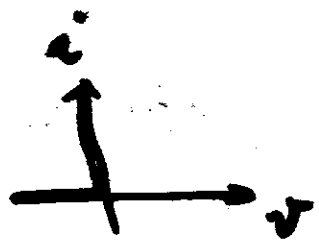
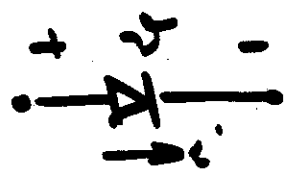
$v < 0$ $i = 0$

$v > 0$ short

< Switch >

No power dissipation in a diode (ideal) $\rightarrow p = 0$: Passive Lossless device

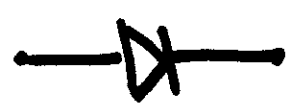
Models:



← ?



physical



model

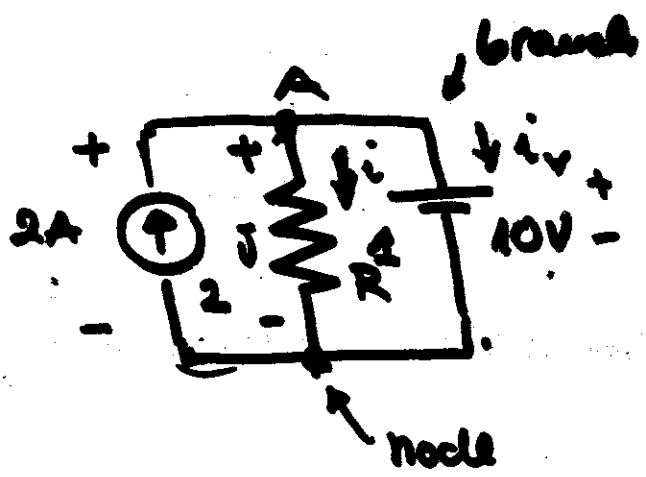
KCL

KVL

Elements: Sources
 R, C, L, diodes (many more)

Q: What are the values of voltages and currents established in a specific circuit?

Q: What is the power dissipated in an element?



$R = 1\text{ k}\Omega$
 $V = ?$
 $i = ?$

KCL: $2 = i + i_v$

KVL: $V - 10 = 0$

Ohm(R): $V = 10^3 \cdot i$

No of eqns: 3
 unknown: 3

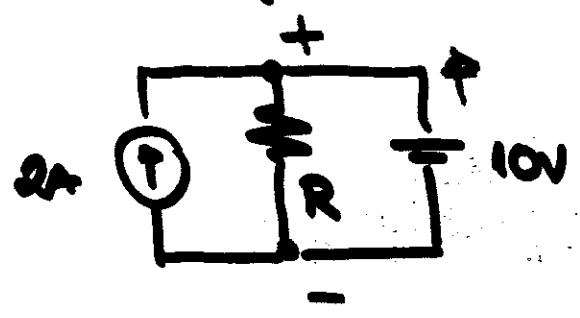
$V = 10\text{ V}$

$i = 10\text{ mA}$

$i_v = 1.99\text{ A}$

*N-1

Problem 10: p. 58 (text)



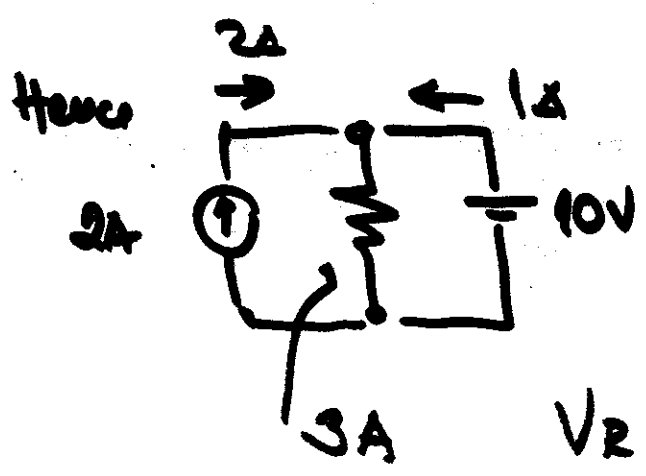
$P_V = \frac{1}{2} P_i$: both sources deliver power

$V_R = 10V$

$P_i = 2 \times 10$, $P_i = 20W$

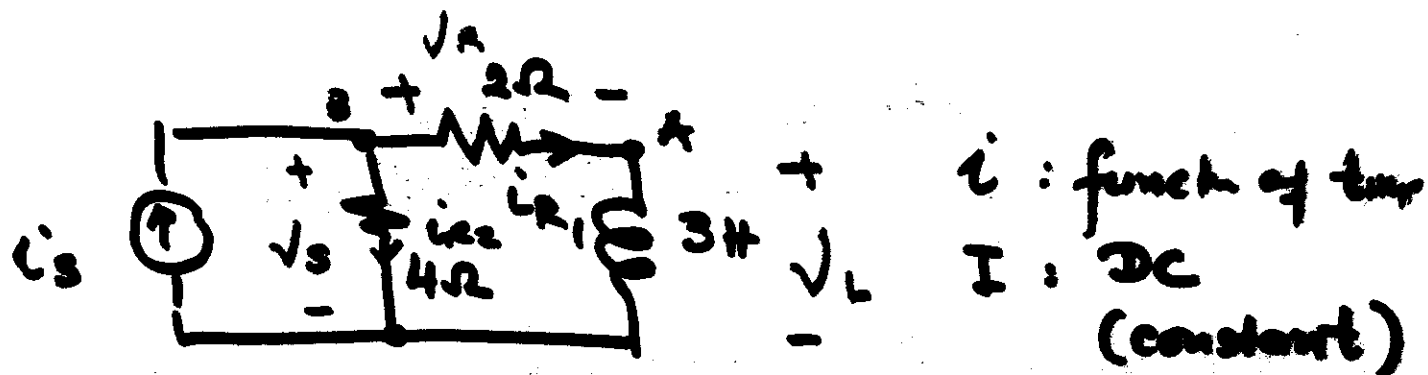
$P_V = \frac{1}{2} P_i \Rightarrow P_V = 10W$

$V_V = 10V \Rightarrow P_V = V_V \cdot I_V$
 $I_V = 1A$



$V_R = R \cdot I_R$
 $10 = R \cdot 3 \Rightarrow R = \frac{10}{3} \Omega$

We can also solve some simple circuits with L's and C's:



$$v_R(t) = -20e^{-2t} \text{ V}$$

Ohm's Law: $v_R = 2 \cdot i_R$

$$i_{R_1} = \frac{1}{2} \cdot v_R \Rightarrow i_{R_1} = -10e^{-2t} \text{ A}$$

$$v_L = L \frac{di_L}{dt}$$

$$i_L = i_{R_1} \text{ (KCL for node A)}$$

$$v_L = 3 \cdot \frac{di_{R_1}}{dt}; \quad v_L = 60e^{-2t} \text{ V}$$

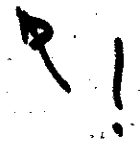
$$\text{KVL: } v_s = v_R + v_L; \quad v_s = (-20e^{-2t} + 60e^{-2t}) \text{ V}$$

$$v_s = 40e^{-2t}$$

$$i_{R_2} = \frac{v_s}{4} \text{ (A)} \quad i_{R_2} = 10e^{-2t} \text{ A}$$

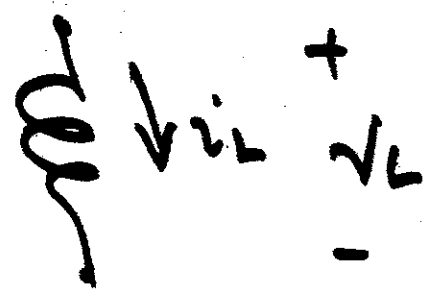
KCL: $i_s = i_{R1} + i_{R2}$

(B) $i_s = 0$



How is this possible?

There is current in a circuit with supply current $i_s = 0$!



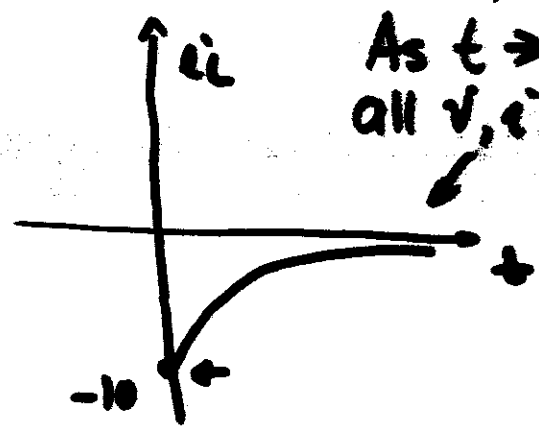
$i_L = -10e^{-2t}$ A

$i_L(0+) = -10$ A

$i_L(0-) = -10$ A

As expected:

As $t \rightarrow \infty$
all $v, i \rightarrow 0$

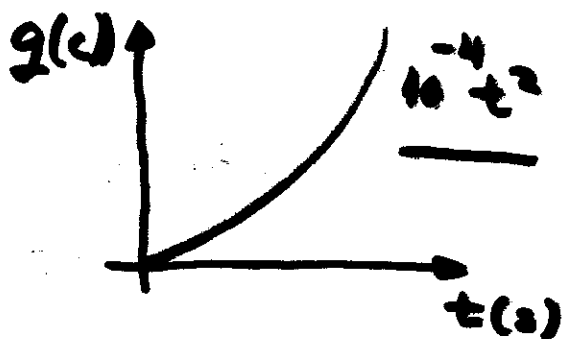
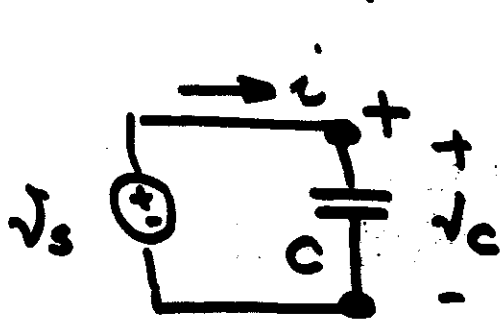


(Law of conservation of electromagnetic flux)

There was electromagnetic energy stored in the inductor that produces currents and voltages in the circuit.

Problem 18: p. 59 (text)

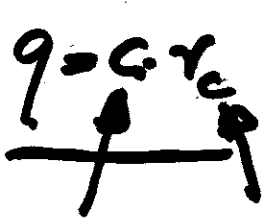
40



$$C = 0.5 \mu F$$

a. Power delivered to the capacitor:

$$\rightarrow i = \frac{dq}{dt} ; \underline{i = 2 \cdot 10^{-4} t \text{ (A)}}$$



$$q = C \cdot V_c \Rightarrow V_c = \frac{1}{C} \cdot q$$

$$V_c = \frac{1}{0.5 \times 10^{-6}} \times 10^{-4} t^2 \text{ (V)}$$

$$\rightarrow \underline{V_c = 200 t^2 \text{ (V)}}$$

$$V_s = V_c \leftarrow$$

$$P = V_c \cdot i$$

$$P = 200 t^2 \cdot 2 \cdot 10^{-4} t \text{ (W)}$$

$$P = 4 \times 10^{-2} t^3 \text{ (W)}$$

41

b. Energy stored in the capacitor
at $t = 5\text{ s}$

$$W(t) = \int_{-\infty}^t p(s) ds$$

$$= \int_{-\infty}^t v_c \cdot i_c ds$$

$$W(t) = \int_{-\infty}^t 4 \times 10^{-2} s^3 ds$$

$$W(5) = 4 \times 10^{-2} \cdot \frac{s^4}{4} \Big|_0^5$$

$$W(5) = 4 \times 10^{-2} \cdot \frac{625}{4}$$

$$= 6.25 \text{ W}$$

$$v_c = 0 \quad t \leq 0$$

$$i_c = 0 \quad t \leq 0$$

$$p = 0 \quad t \leq 0$$

$$W = 0 \quad t \leq 0$$

c. $v_c(t)$ at $t=2s$

$$v_c(t) = 200t^2 \text{ (V)}$$

$$v_c(2) = 200 \times 2^2 \text{ (V)}$$

$$v_c(2) = 800 \text{ V}$$

Resistive circuit: Voltage sources
 Current sources
 R linear
 R non-linear
 diodes
 transistors.

L, C circuits: voltage sources
 current sources
 R (all kinds and types)
 → L, C

Active elements: sources

Passive elements: R linear
 ↓
 L
 C (R, L, C ≥ 0)

Dissipative: $v \cdot i \geq 0$

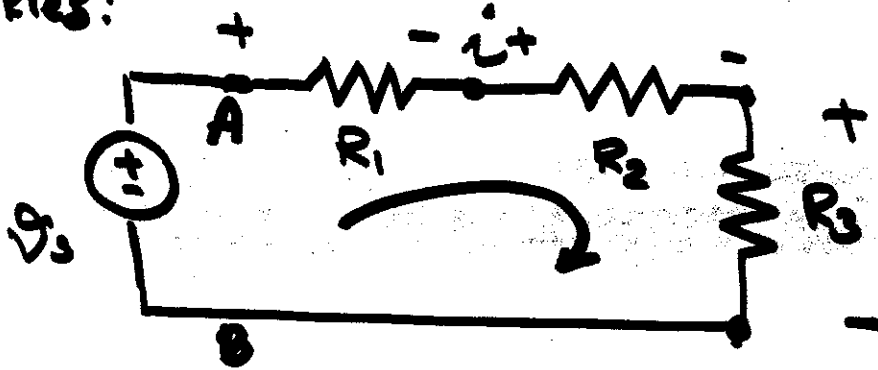
non-dissipative: $v \cdot i = 0$

↑ ideal transformers
 shorts, open-circuits

3 Simple Dissipative Structures

Parallel and Series Circuits:

Series:



$$v_{R_1} + v_{R_2} + v_{R_3} = v_s \quad \text{KVL}$$

Ohm's Law:

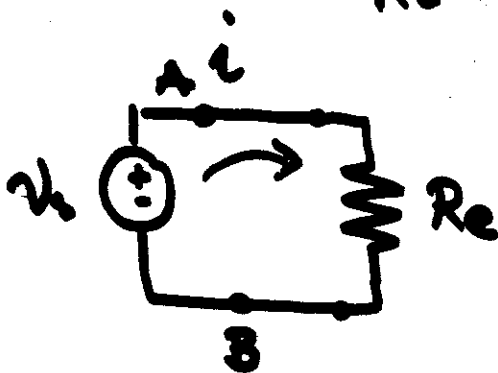
$$i \cdot R_1 + i \cdot R_2 + i \cdot R_3 = v_s$$

$$i \cdot (R_1 + R_2 + R_3) = v_s$$

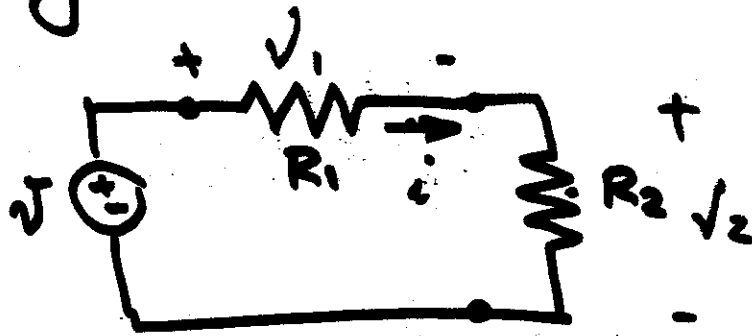
$$R_e = R_1 + R_2 + R_3$$

KCL:

$$i_{R_1} = i_{R_2} = i_{R_3}$$



Voltage divider:



$$V_1 = R_1 \cdot i$$

$$V_2 = R_2 \cdot i$$

$$V = V_1 + V_2 \Rightarrow V = R_1 i + R_2 i$$

$$V = (R_1 + R_2) \cdot i$$

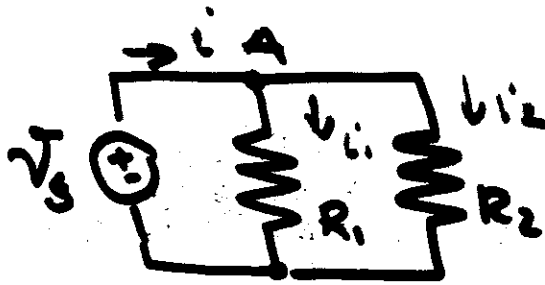
$$i = \frac{V}{R_1 + R_2}$$

$$V_1 = R_1 i \Rightarrow V_1 = \frac{R_1}{R_1 + R_2} \cdot V$$

$$V_2 = \frac{R_2}{R_1 + R_2} \cdot V$$

$$\frac{V_1}{V_2} = \frac{R_1}{R_2}$$

Parallel



$$V_{R_1} = V_{R_2} = V_s$$

$$i_1 R_1 = i_2 R_2$$

$$i = i_1 + i_2$$

$$i_1 = \frac{V_s R_1}{R_1} \quad \text{or} \quad i_1 = G_1 \cdot V_s$$

$$i_2 = G_2 \cdot V_s$$

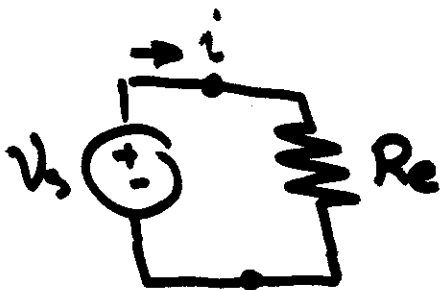
$$i = (G_1 + G_2) \cdot V_s$$

$$G_e = G_1 + G_2$$

$$\Rightarrow i = G \cdot V_s \leftarrow$$

$$\frac{1}{R_e} = \frac{1}{R_1} + \frac{1}{R_2}$$

$$; R_e = \frac{R_1 \cdot R_2}{R_1 + R_2}$$

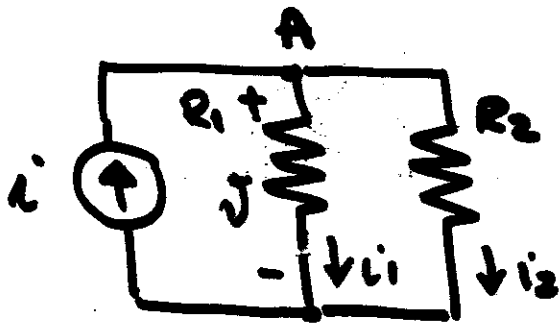


$$G = \frac{1}{R} \quad \Omega$$

Conductance

Siemens, A/V

Current divider:



$$i = i_1 + i_2$$

$$i_1 = G_1 \cdot v$$

$$i_2 = G_2 \cdot v$$

$$i = (G_1 + G_2) \cdot v \quad \Rightarrow \quad v = \frac{i}{G_1 + G_2}$$

$$i_1 = \frac{G_1}{G_1 + G_2} \cdot i$$

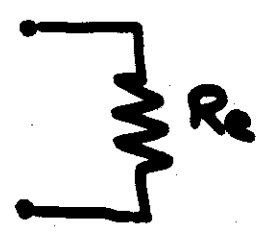
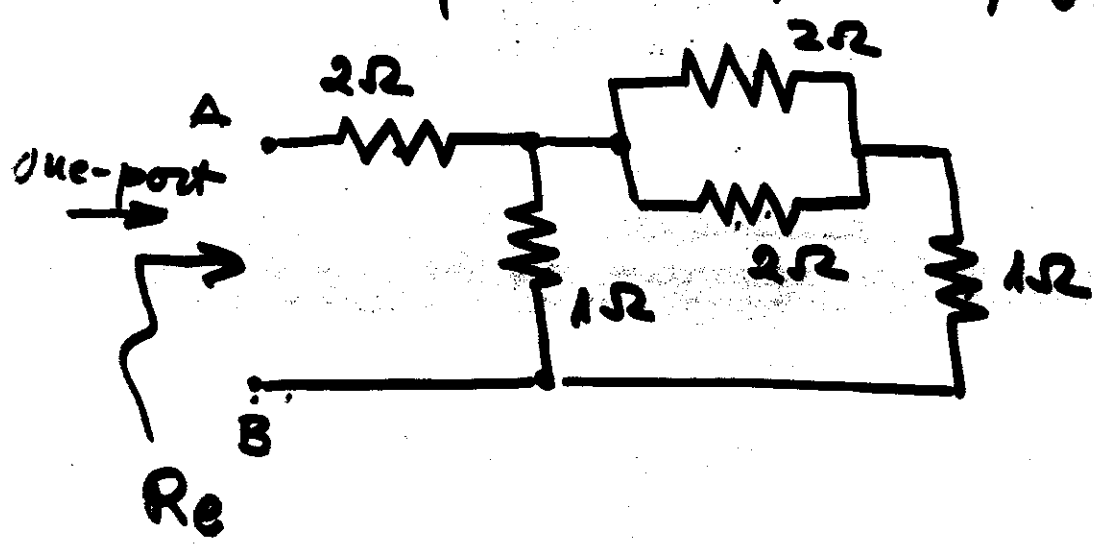
$$i_2 = \frac{G_2}{G_1 + G_2} \cdot i$$

$$\frac{i_1}{i_2} = \frac{G_1}{G_2} \quad \text{or} \quad \frac{i_1}{i_2} = \frac{R_2}{R_1}$$

(Recall: $R = \frac{1}{G}$)

Finding equivalent resistance:

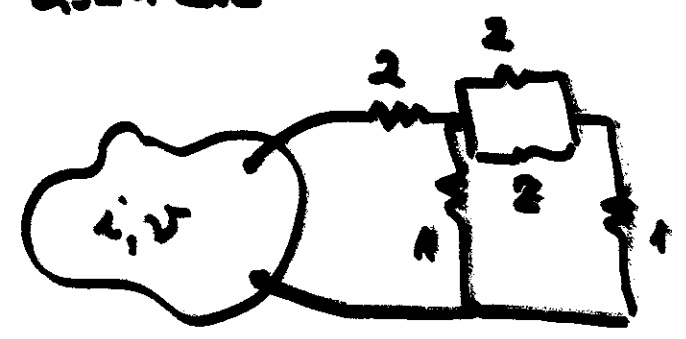
Common procedure for simplifying circuits:



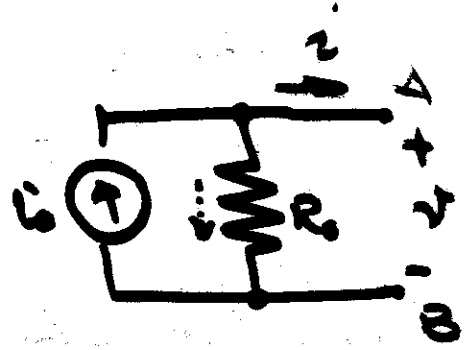
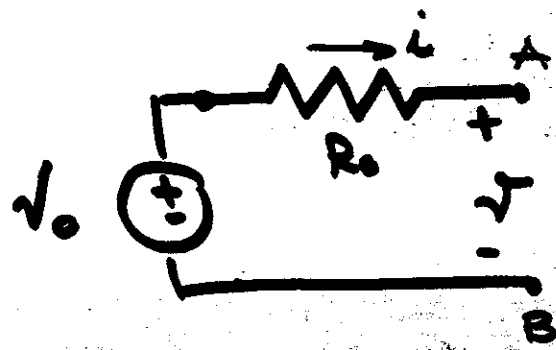
$$R_e = 2\Omega + \frac{1\Omega \times \left(\frac{2\Omega \cdot 2\Omega}{2\Omega + 2\Omega} + 1\Omega \right)}{1\Omega + \frac{2\Omega \cdot 2\Omega}{2\Omega + 2\Omega} + 1\Omega}$$

$$R_e = 2 + \frac{2}{3}$$

$$R_e = \frac{8}{3}\Omega$$



2. Source transformation



$$V = V_0 - R_0 \cdot i$$

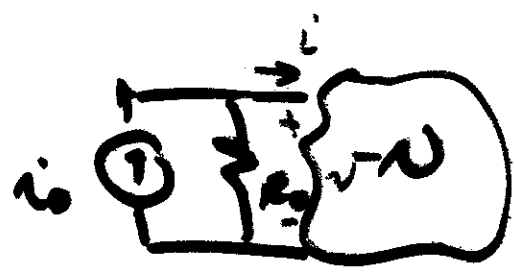
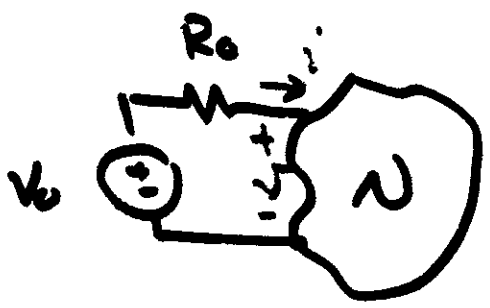
$$i = i_0 - \frac{V}{R_0}$$

$$i = \frac{V_0}{R_0} - \frac{V}{R_0}$$

$$i = i_0 - \frac{V}{R_0}$$

Equivalent if

$$i_0 = \frac{V_0}{R_0} \quad \text{or} \quad V_0 = R_0 \cdot i_0$$

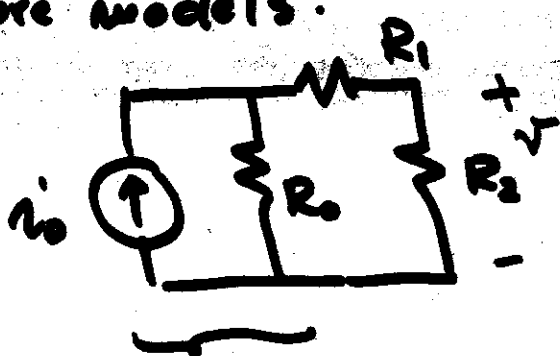


$$i_0 = \frac{V_0}{R_0}$$

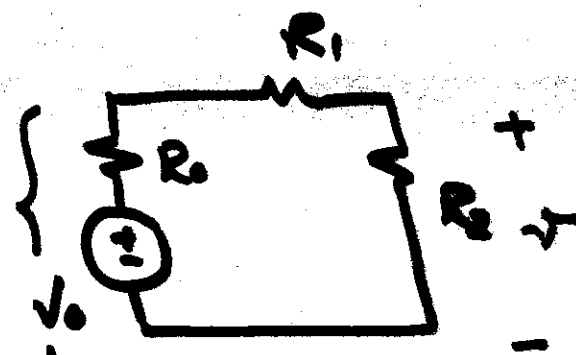
$V_o = R_o i_o$ is not Ohm's Law

V_o and i_o are in different circuits!

Source models:



accompanying sources



$$V_o = R_o i_o$$

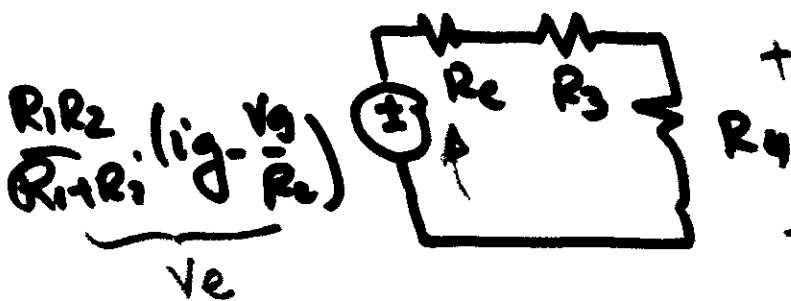
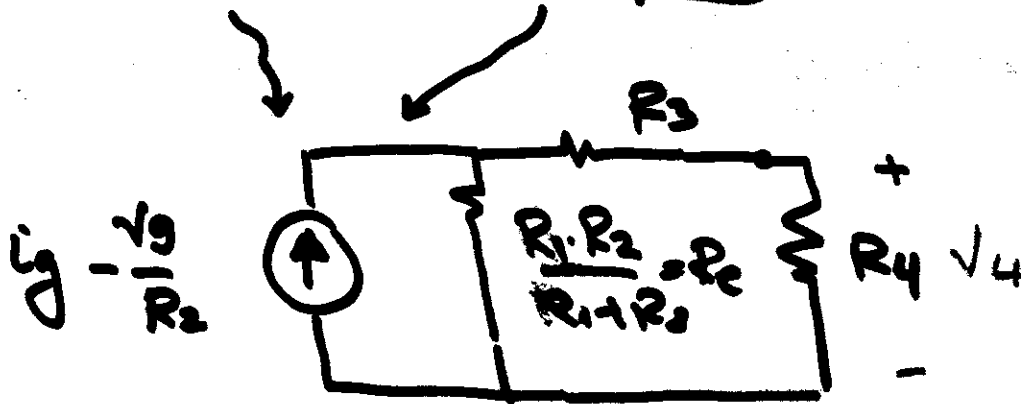
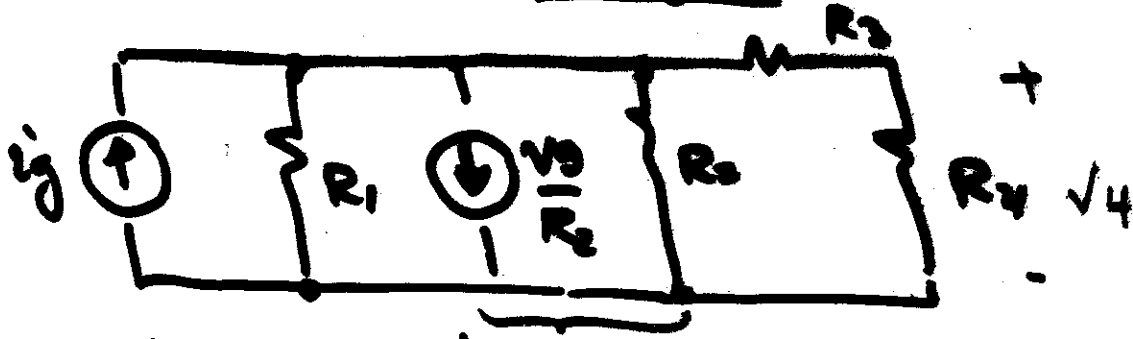
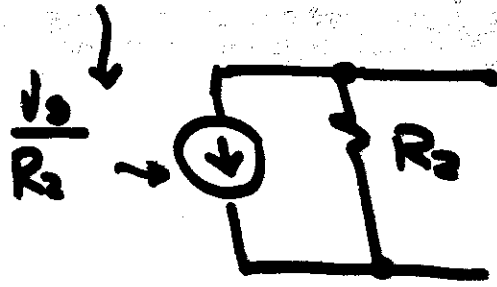
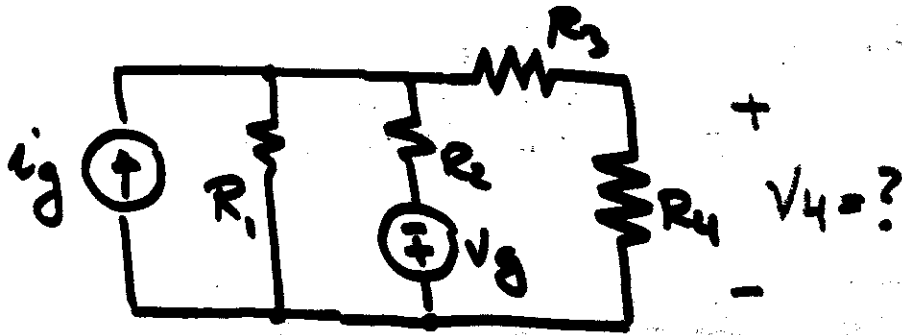
current
voltage

$$V = \frac{R_2}{R_o + R_1 + R_2} \cdot R_o i_o$$

voltage divider

Useful when solving and simplifying circuits.

"Solving" circuits: simplification helps



$$I_4 = \frac{V_e}{R_e + R_3 + R_4}$$

$$V_4 = R_4 \cdot I_4$$

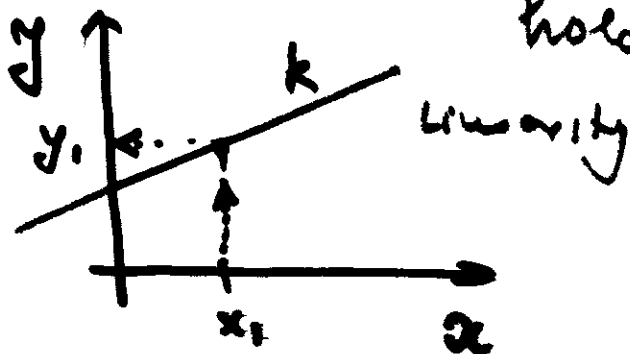
3. Basic Principles

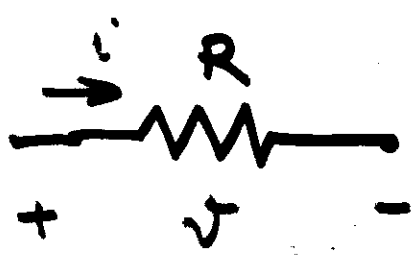
Linearity and Superposition:

$$\begin{array}{l} \text{input} = x_1 \qquad \text{output} = y_1 \\ \qquad \qquad \qquad = x_2 \qquad \qquad \qquad = y_2 \end{array}$$

$$\begin{array}{l} \text{input} = k_1 x_1 + k_2 x_2 \\ \text{--- output} = k_1 y_1 + k_2 y_2 \end{array} \begin{array}{l} \longleftarrow \text{Linearity} \\ \uparrow \text{superposition} \end{array}$$

Linear system: output is proportional to the input and the principle of superposition holds





$$V = R \cdot i$$

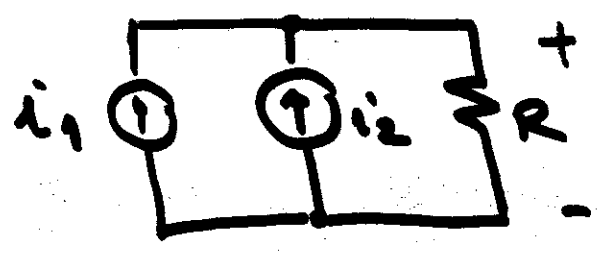
↑ ↙ ↘
 output (y) input (x)

Linearity holds:

$$y = k \cdot x$$

↓
R
constant

How about superposition?

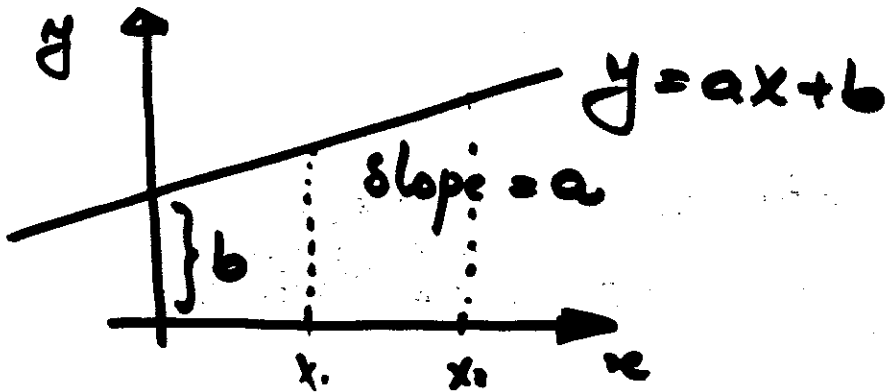


$$V = R \cdot (i_1 + i_2)$$

$$V = \underbrace{R \cdot i_1}_{V_1} + \underbrace{R \cdot i_2}_{V_2}$$

$$V = V_1 + V_2$$

↖
superposition



$$x_1 : y_1 = ax_1 + b$$

$$x_2 : y_2 = ax_2 + b$$

$$x_1 + x_2 : y_3 = a(x_1 + x_2) + b \\ = ax_1 + ax_2 + b$$

fine

$b=0$

$$\neq y_1 + y_2 \\ \downarrow \quad \searrow \\ ax_1 + b \quad ax_2 + b$$

$$x_1 : y_1 = ax_1 + b$$

$$kx_1 : y_2 = a \cdot (kx_1) + b$$

$$y_2 = k \cdot \left(ax_1 + \frac{b}{k} \right)$$

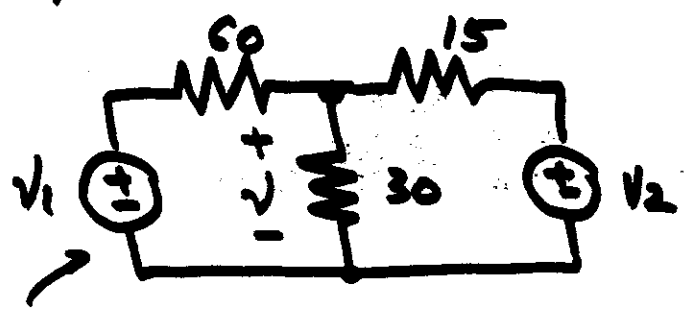
$$\neq k \cdot y_1$$

Input : $k \cdot x_1$

output $\neq k \cdot y_1$

Not linear!

How can we use superposition to solve simple circuits?



$$V_1 = 21 \sin 400t$$

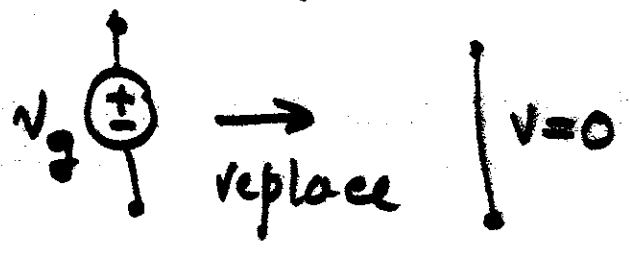
$$V_2 = 14 \cos 400t$$

Superposition:

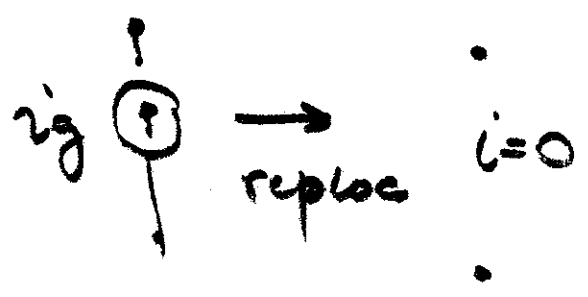
Let V_1 be present, disconnect V_2

< How to disconnect a voltage source! >

$$V_1 \left\{ \begin{aligned} \frac{30 \times 15}{45} &= 10 \\ V_1 &= \frac{10}{70} \cdot 21 \sin 400t \end{aligned} \right.$$



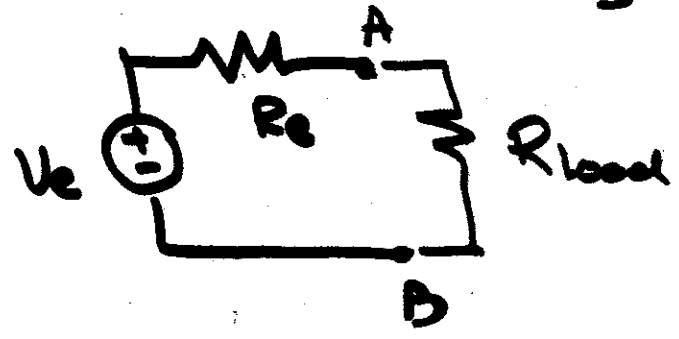
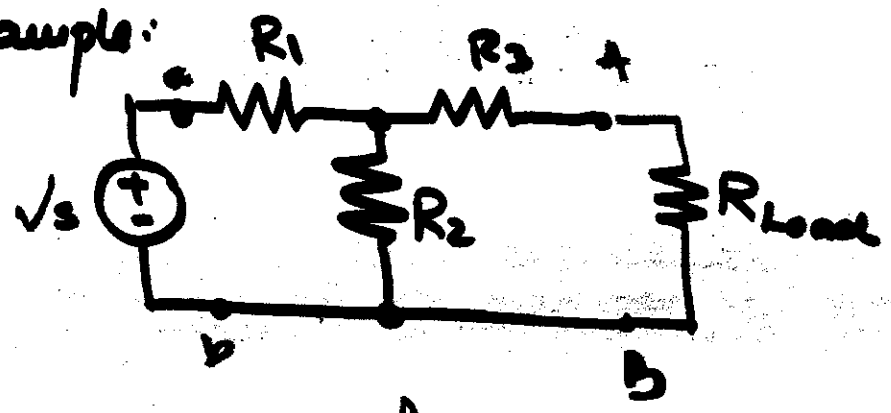
$$V_2 \left\{ \begin{aligned} \frac{60 \times 30}{90} &= 20 \\ V_2 &= \frac{20}{35} \cdot 14 \cos 400t \end{aligned} \right.$$



$$v = 3 \sin 400t + 8 \cos 400t \leftarrow$$

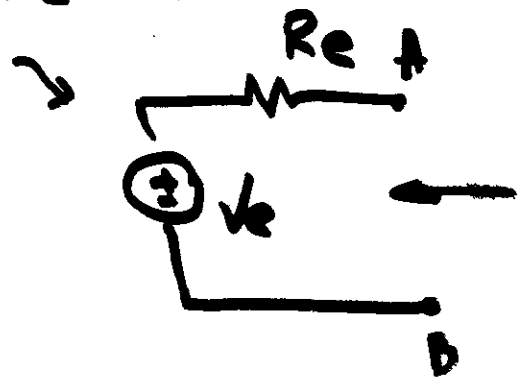
Thévenin Theorem:

Example:



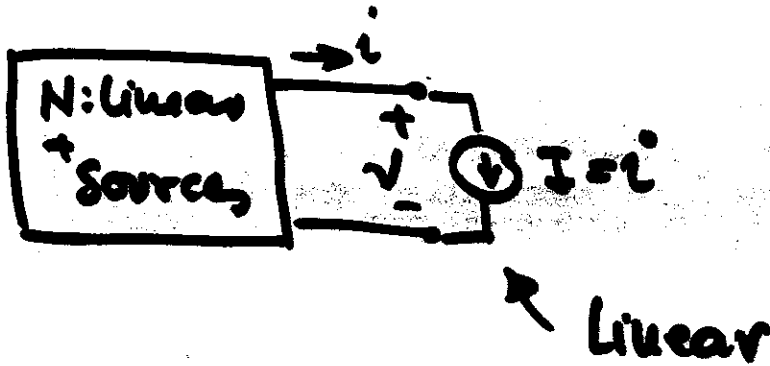
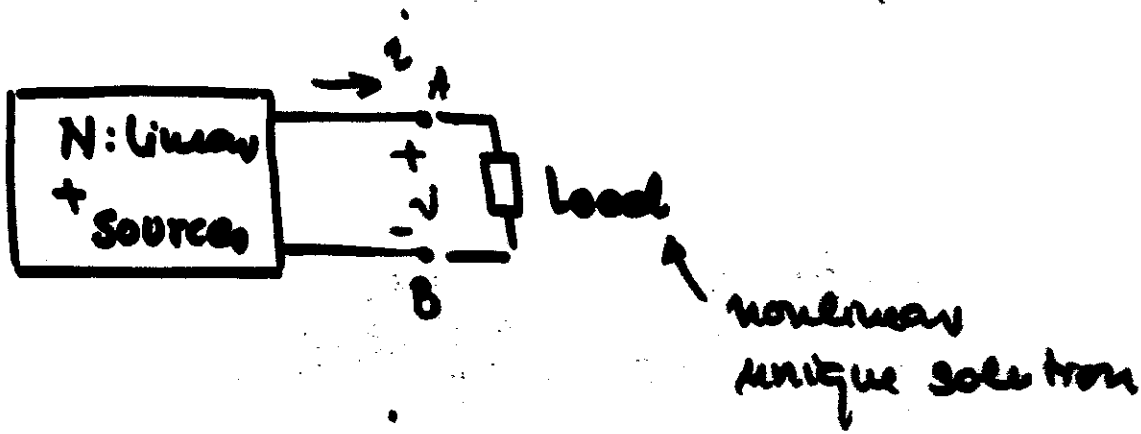
$$V_e = V_s \cdot \frac{R_1}{R_1 + R_2}$$

$$R_e = \frac{R_1 R_2}{R_1 + R_2} + R_3$$

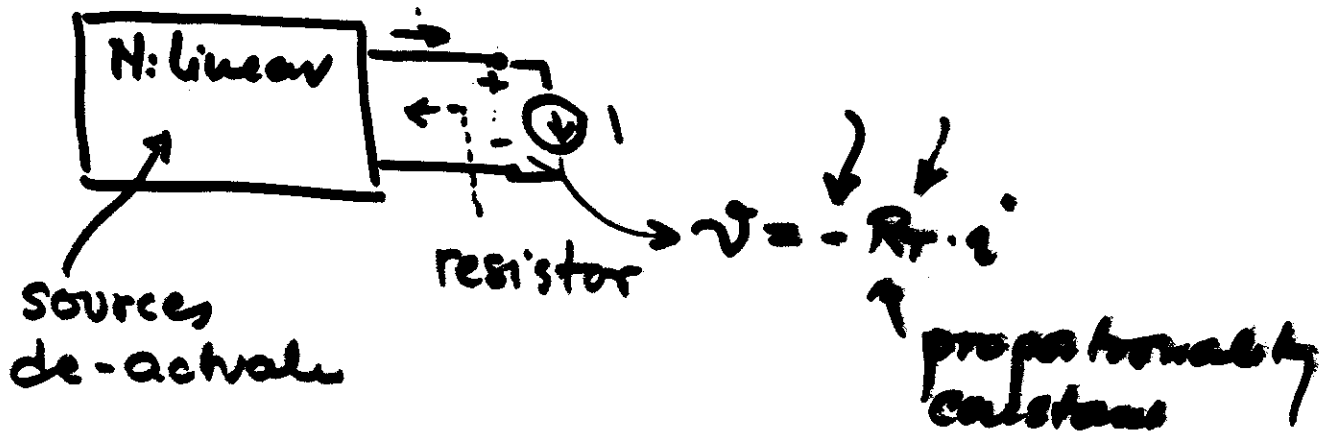
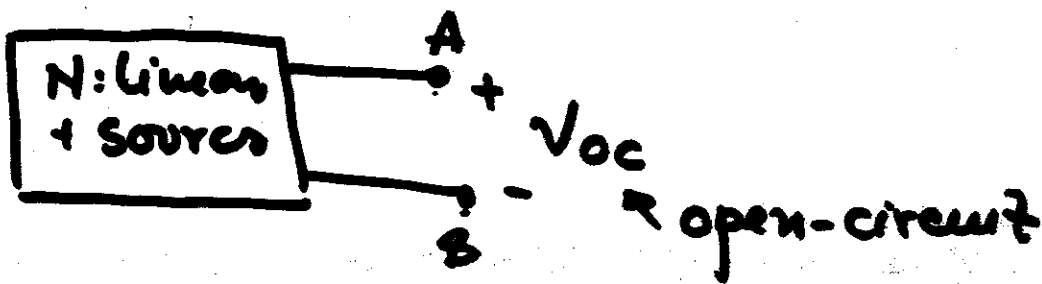


R_e
 V_e

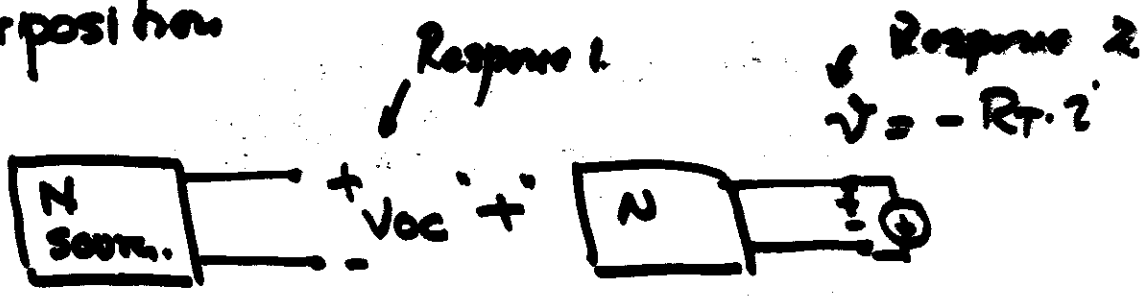
If R_L is removed
(open-circuited)



De-activate source I ($I = 0$)



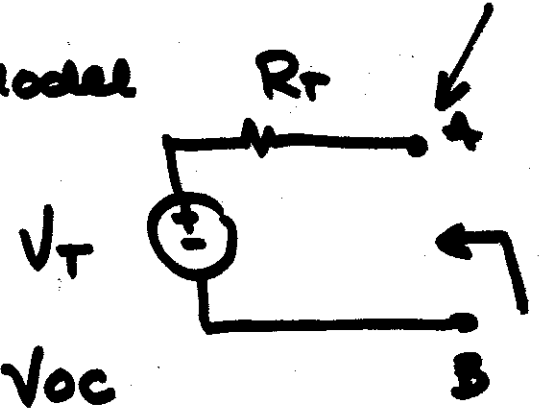
Superposition



Total response

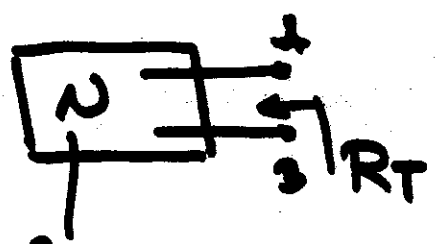
$$V_{oc} - R_T \cdot i$$

Model

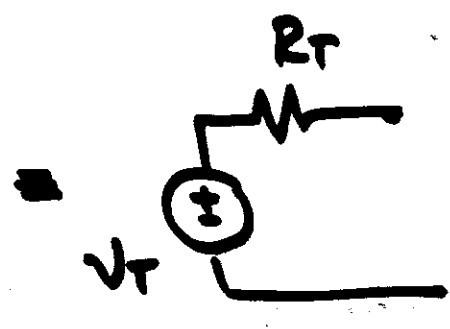
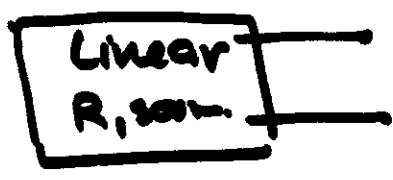


$$V_T = V_{oc}$$

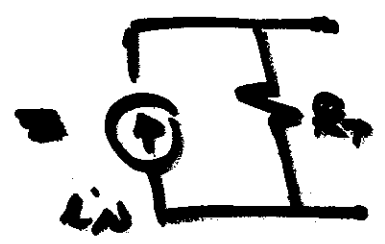
R_T :



Sources de-activated



Thevenin
(1825)



Norton

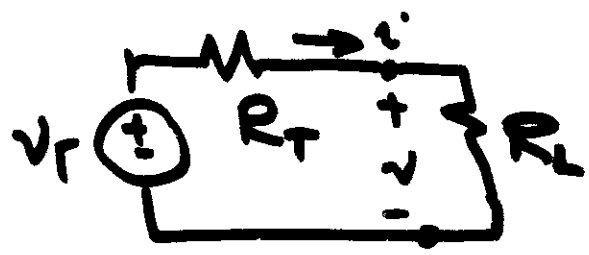
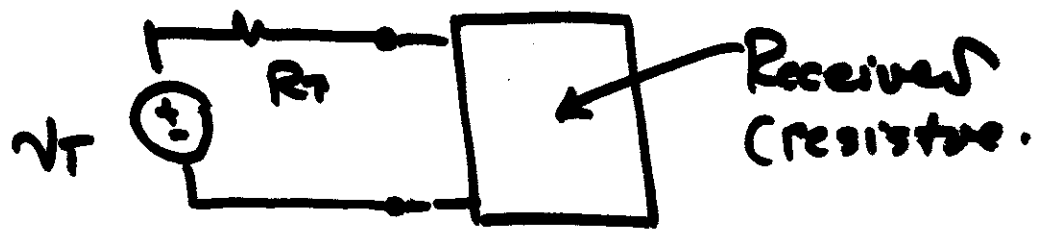
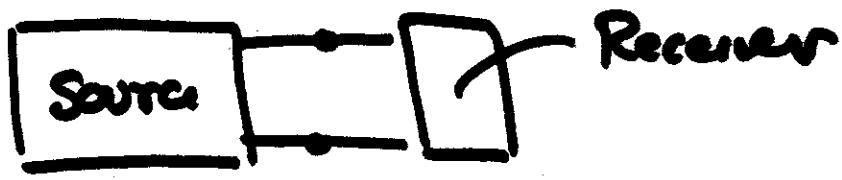
equivalent circuits
(1935)

$$V_T = R_T \cdot I_N$$

Not Ohm's Law!

V_T and I_N are in different circuits

Maximum power transfer to a load:



$$i = \frac{V_T}{R_T + R_L}$$

$$v = \frac{R_L}{R_T + R_L} \cdot V_T$$

$P_{\text{delivered to the receiver}} = i \cdot v$

$$P = \frac{v_T \cdot R_L}{(R_T + R_L)^2}$$

What is the value of R_L so that the power delivered to the receiver is maximal:

$$P(x) = \frac{x}{(R_T + x)^2} \cdot v_T^2 R_L$$

$$\frac{dP}{dx} = \frac{(R_T + x)^2 - 2 \cdot (R_T + x) \cdot x}{(R_T + x)^4} v_T^2 R_L$$

$$\frac{dP}{dx} = 0 \quad \text{if} \quad (R_T + x)^2 - 2(R_T + x) \cdot x = 0$$

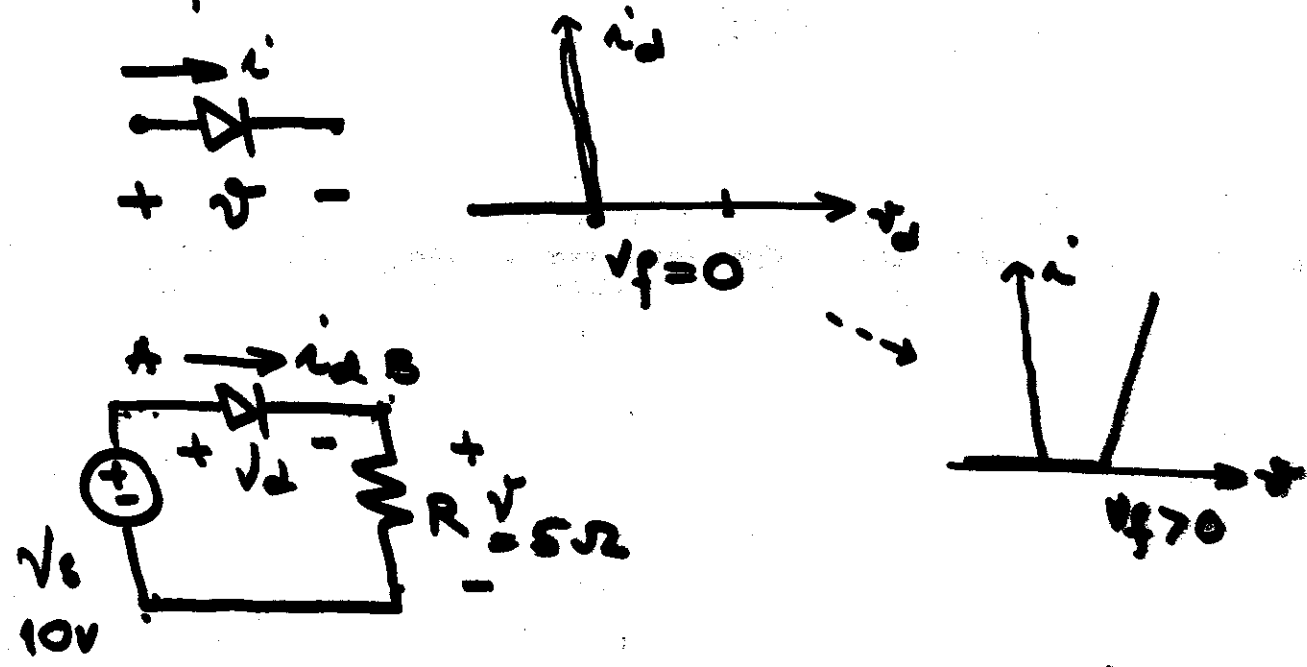
$$(R_T + x) \cdot (R_T + x - 2x) = 0$$

\downarrow
 $\neq 0$

\downarrow
 $x = R_T$ or $R_L = R_T$
"matching"

Diode Circuits

- Simplest Nonlinear circuits:

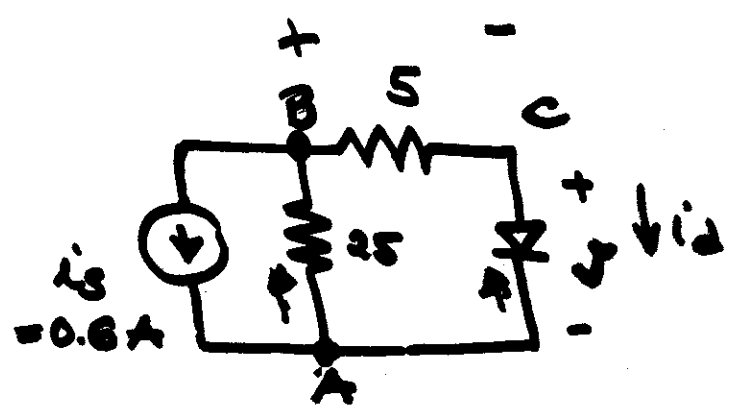


$$\rightarrow v_s > 0 \Rightarrow v_d = 0 \Rightarrow i = \frac{v_s}{R} \quad \text{ON}$$

$$v_s < 0 \Rightarrow i_d = 0 \Rightarrow i = 0 \quad \text{OFF switch}$$

We can solve simple diode circuits by assuming their state and then checking the circuit for consistency:

Above: $v_s > 0$ OFF $\Rightarrow i_d = 0 \Rightarrow v = 0$
 KVL $\Rightarrow v_d = v_s = 10V$
 \downarrow
 ?!?
 <OFF>!

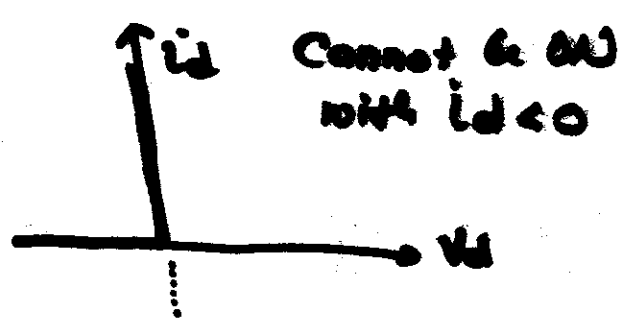


Assume diode ON: $R_e = \frac{5 \cdot 25}{30} \Omega$;

$$i_d = \frac{-25}{25+5} \cdot i_s$$

$$i_d = -\frac{25}{30} \cdot 0.6$$

$$i_d = -0.5A !!$$

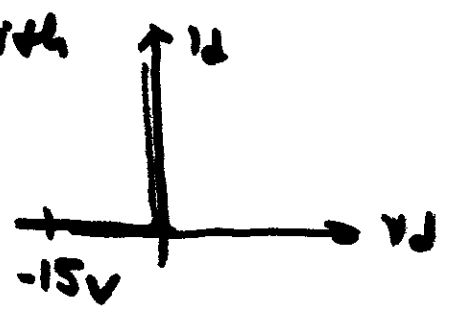


Here, Assume diode is OFF:

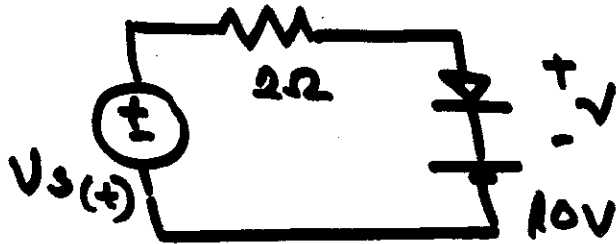
$$i_d = 0$$

$$V_d = -15V$$

which is consistent with

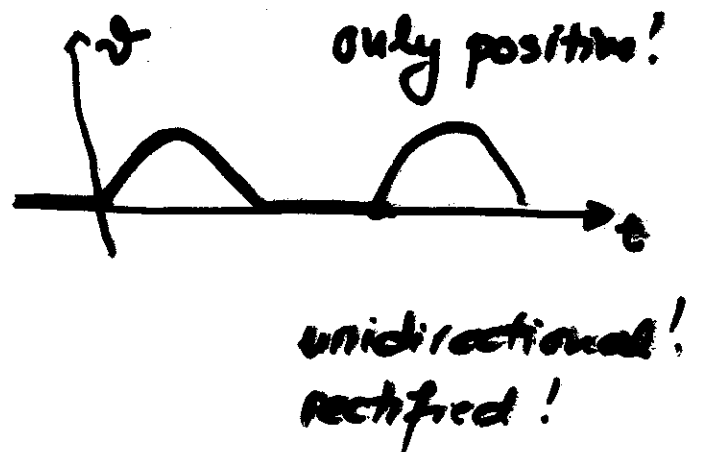
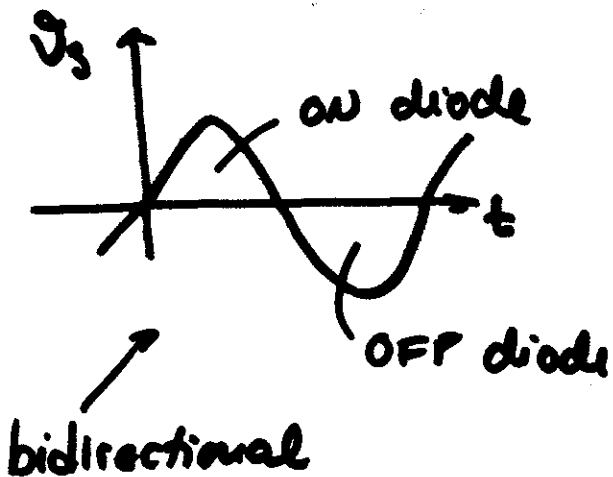
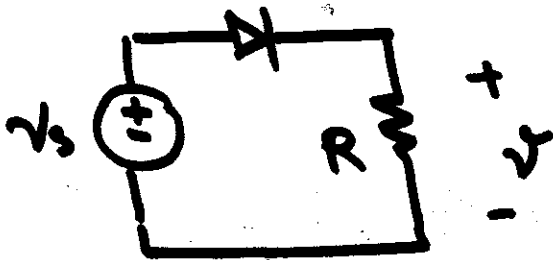


How about time-varying sources:

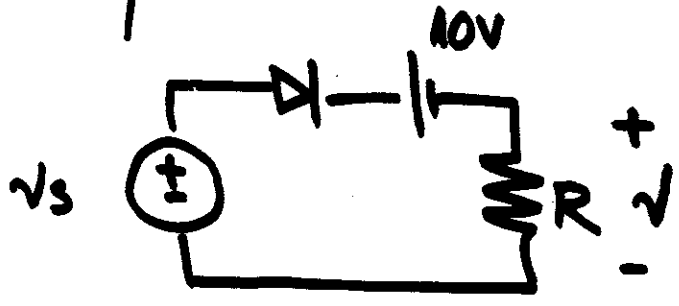


if $V_s > 10V$ \rightarrow Diode is ON $i = \frac{V_s - 10}{2}$
 $V_s < 10V$ OFF $i = 0$

Rectifiers:



Comparators:

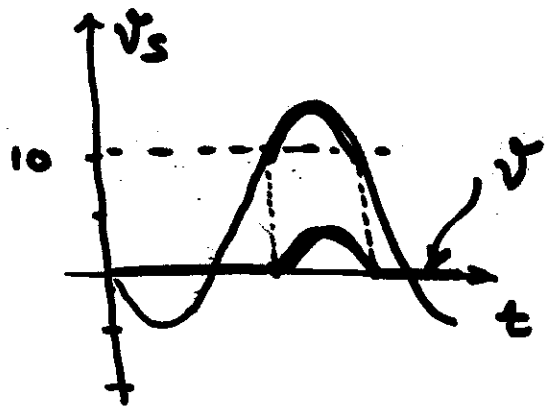


$$v = v_s - 10 \quad \text{if } v_s > 10V$$

$$v = 0 \quad \text{if } v_s < 10V$$

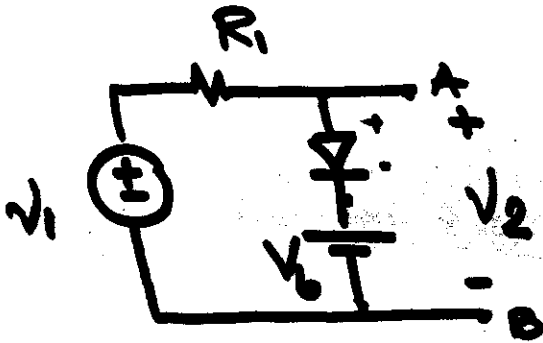
Hence: 10V is critical:

if input $> 10V$ \rightarrow there is $v_{across R} > 0$
 < 0 no voltage

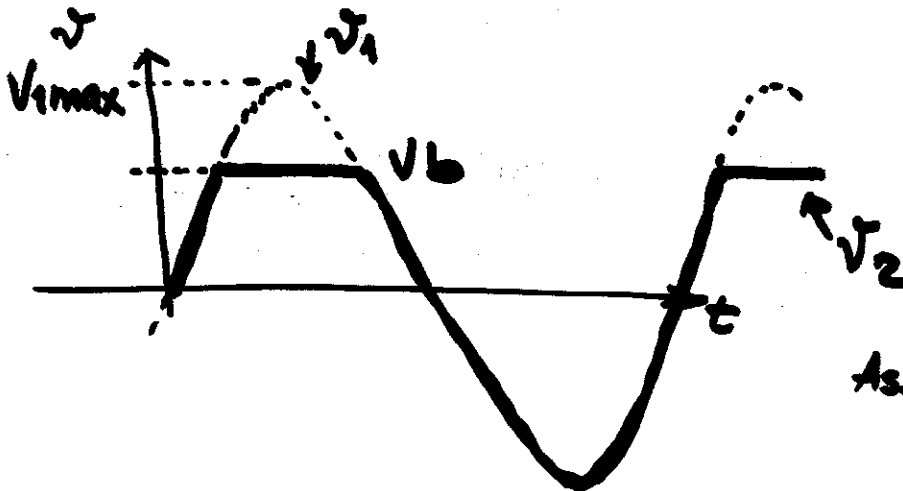


Voltage Limiters:

prevents voltage from becoming too large

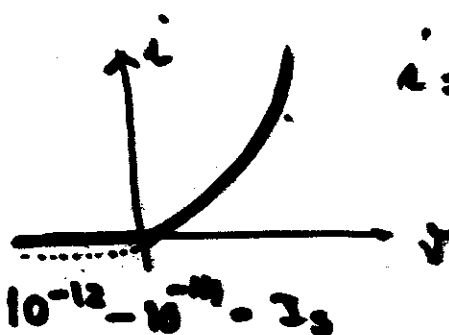
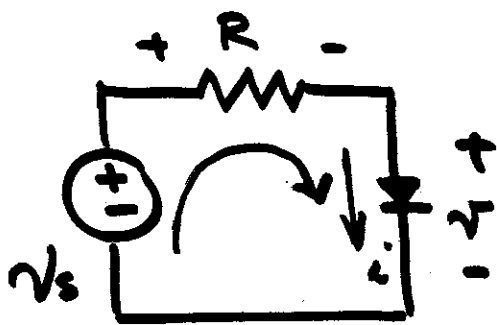


if diode is OFF: $v_2 = v_1$
 ON: $v_2 = V_b$ (fixed)
 DC



Assume
 $V_b < V_{max}$

Exponential Diodes:

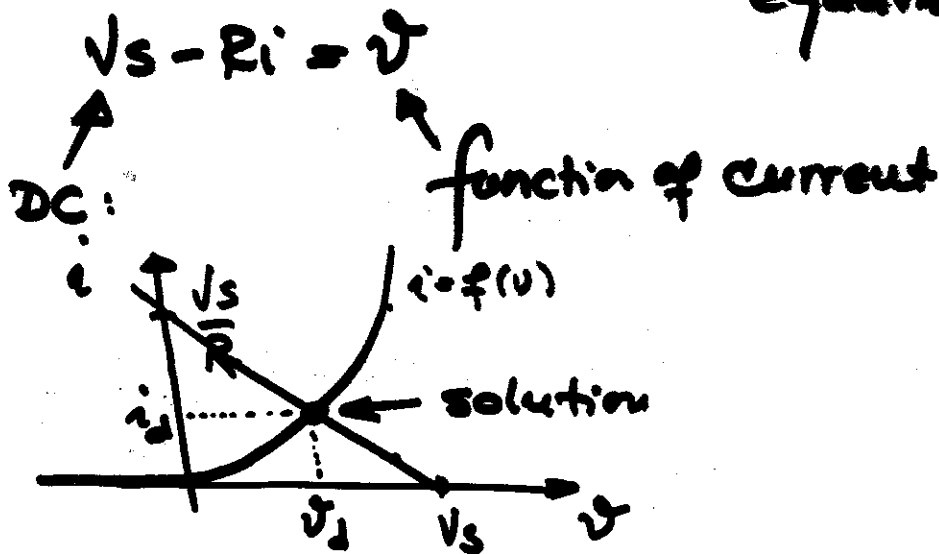


$$i = (e^{\frac{qv}{kT}} - 1) I_s$$

How can we solve circuits with diodes that are not modeled with ideal switches:

KVL: $V_s - Ri - v = 0$

Nonlinear equation.



$$V_s - Ri = v$$

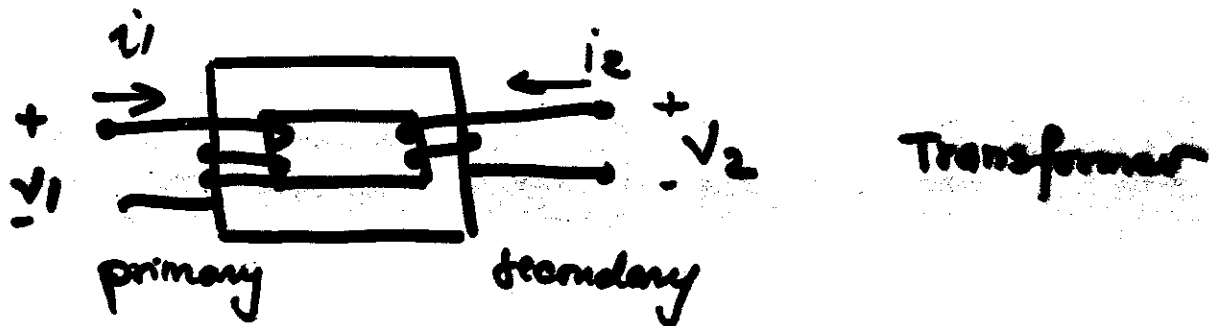
$$i = \frac{V_s - v}{R}$$

$$i = f(v)$$

Also $i = f(v)$
diode characteristics

Chapter 4 : Multiterminal Components ⁰⁷

1. Ideal transformer



4-terminals arranged into
2-ports

$$\frac{v_1}{v_2} = \frac{N_1}{N_2} \quad \text{Faraday's law}$$

$n \leftarrow$ turns ratio

$$\rightarrow v_1 = n v_2$$

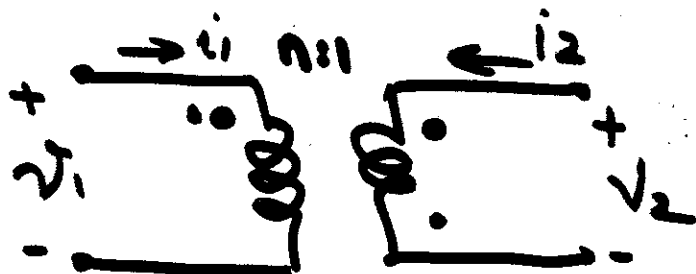
$$i_2 = - \frac{N_1}{N_2} i_1$$

$$\begin{pmatrix} v_1 \\ i_2 \end{pmatrix} = \begin{pmatrix} 0 & n \\ -n & 0 \end{pmatrix} \begin{pmatrix} i_1 \\ v_2 \end{pmatrix}$$

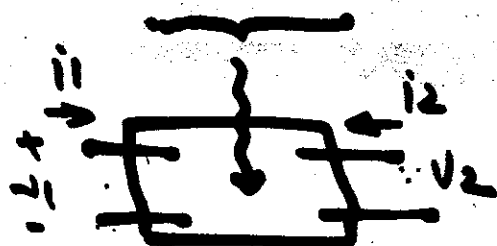
$$\rightarrow i_2 = -n \cdot i_1$$

Ampere's law

Circuit symbol:



$$\left\langle \begin{array}{l} v_1 = -n v_2 \\ i_2 = n i_1 \end{array} \right\rangle$$



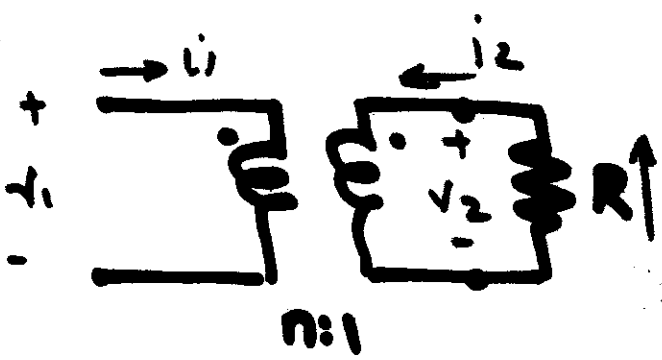
$$\begin{pmatrix} v_1 \\ i_2 \end{pmatrix} = \begin{pmatrix} 0 & n \\ -n & 0 \end{pmatrix} \begin{pmatrix} i_1 \\ v_2 \end{pmatrix}$$

$$p = v_1 i_1 + v_2 i_2$$

$$p = (n v_2) \cdot i_1 + v_2 (-n i_1)$$

$$\underline{p = 0}$$

passive
→ lossless device



$$\begin{cases} v_1 = n v_2 \\ i_2 = -n i_1 \end{cases}$$

$$v_2 = -R \cdot i_2 \quad (\text{Ohm's law})$$

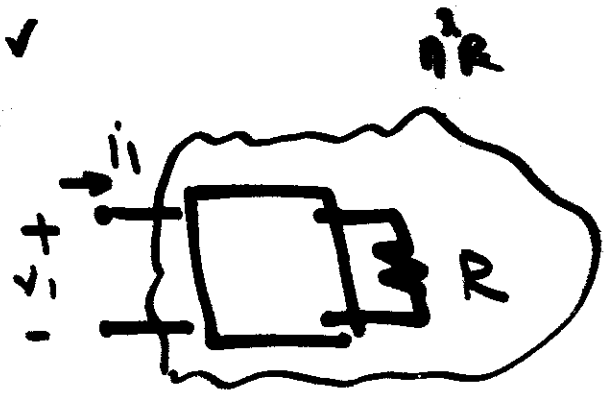
Then:

$$v_1 = n \cdot (-R \cdot i_2)$$

$$v_1 = -n \cdot R \cdot i_2 \checkmark$$

$$v_1 = -nR (-n i_1) \checkmark$$

$$v_1 = \underline{n^2 R \cdot i_1}$$



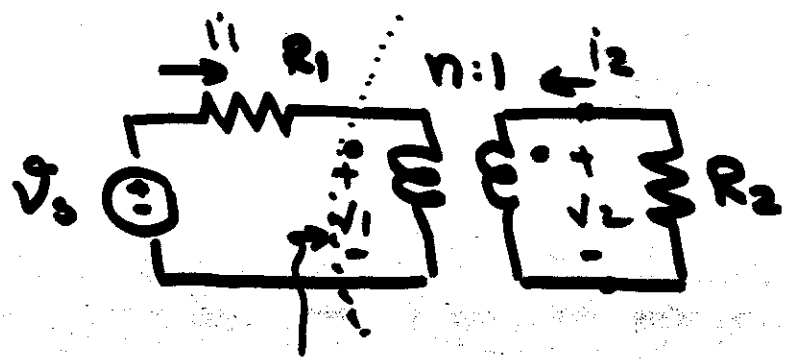
$$v_1 = (n^2 R) \cdot i_1$$

$$v_1 = \text{Resistance} \cdot i_1$$

$$\text{Resistance} = n^2 R$$

Transformer!

Ideal transformer : used for matching!



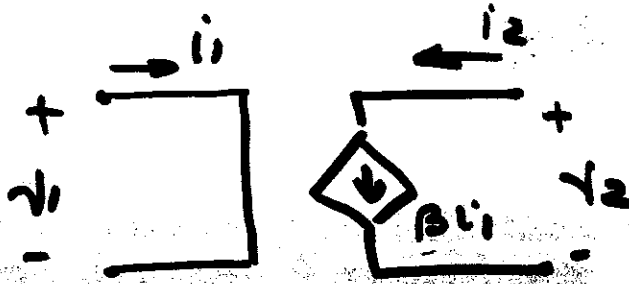
$$R_0 = n^2 \cdot R_2 \quad \checkmark$$

Matching : $R_1 = n^2 R_2 \Rightarrow n = \sqrt{\frac{R_1}{R_2}}$



Controlled Sources:

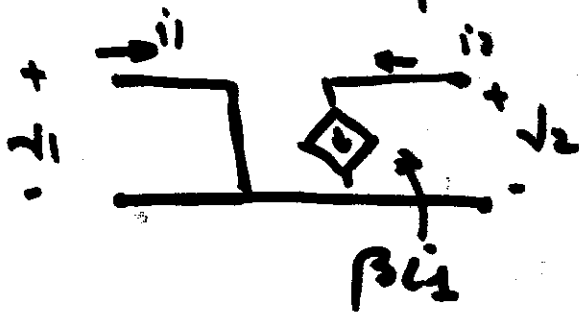
<Dependent>



$$v_1 = 0$$

$$i_2 = \beta i_1$$

Linear
 $\beta = \text{constant}$



$$v_1 = 0$$

$$i_2 = \beta i_1$$

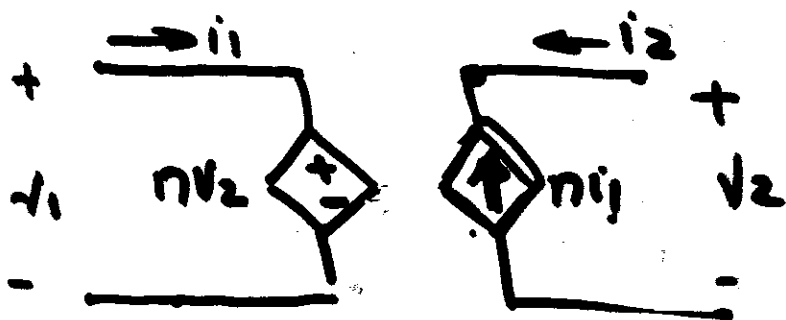
$$\begin{pmatrix} v_1 \\ i_2 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ \beta & 0 \end{pmatrix} \begin{pmatrix} i_1 \\ v_2 \end{pmatrix}$$

Current controlled current source
 <CCCS>

4-types of controlled sources:

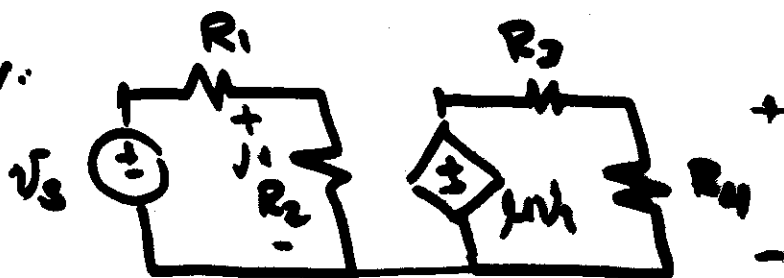
Controlled sources are used to model other circuit elements:

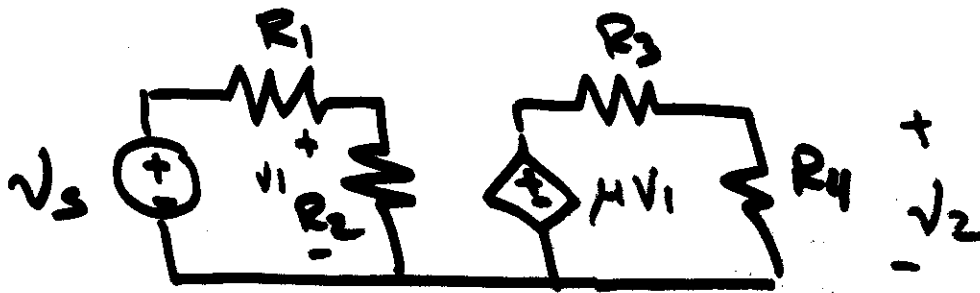
ideal transformers
transistors
op-amps
⋮



$$\begin{aligned} \rightarrow v_1 &= nV_2 \\ \rightarrow i_2 &= -ni_1 \end{aligned} \quad \text{ideal transformer}$$

Amplifier:





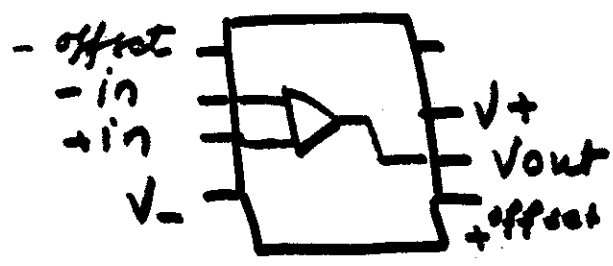
KCL, KVL, Ohm's Law

$$v_1 = \frac{R_2}{R_1 + R_2} \cdot v_s \quad \text{Voltage divider}$$

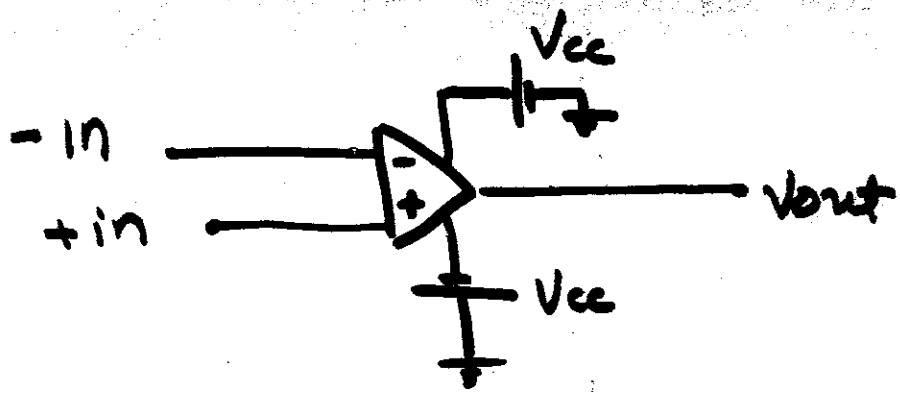
$$v_2 = \frac{R_4}{R_3 + R_4} \cdot \mu \cdot v_1 \quad \text{---}$$

$$v_2 = \frac{R_4}{R_3 + R_4} \cdot \frac{R_2}{R_1 + R_2} \cdot \mu \cdot v_s \quad \text{Amplifier}$$

Operational Amplifiers

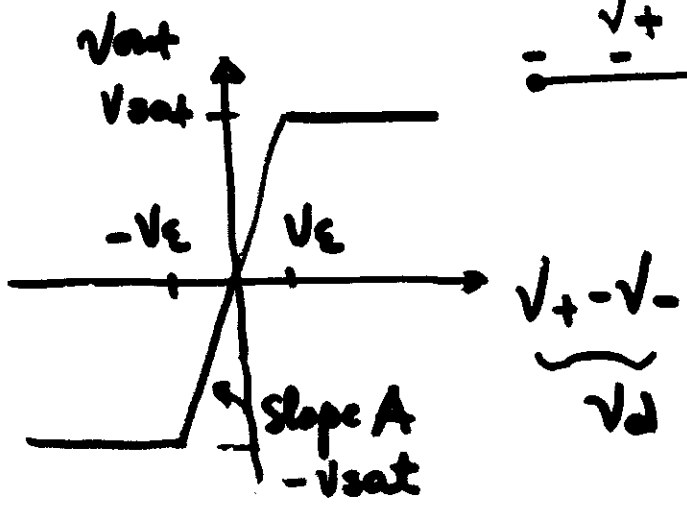
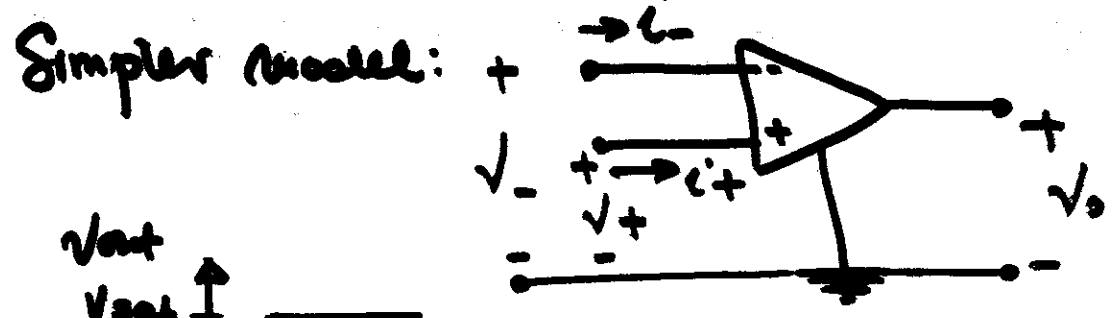


Dual in line package
integrator circuit
chip

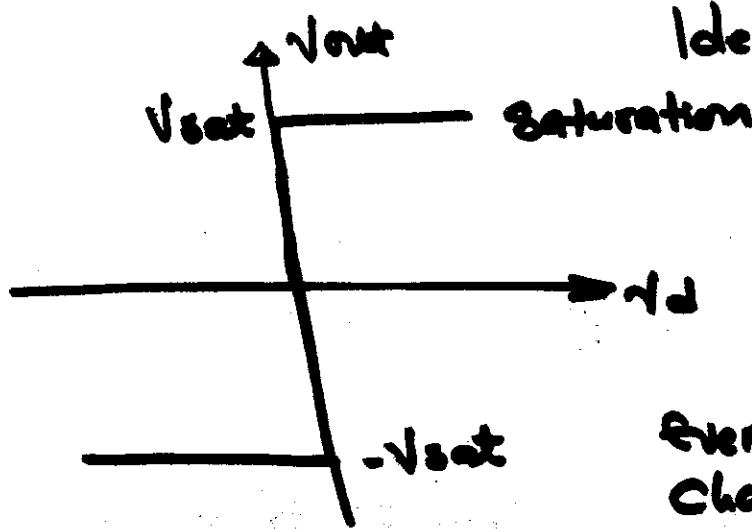


$V_{cc} = 15V$
usually

Built from transistors



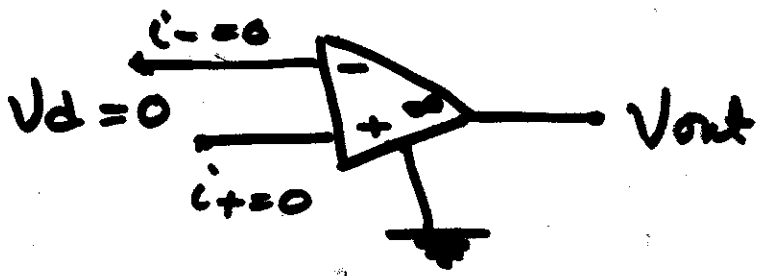
Nonlinear circuit
 $V_{out} = A \cdot V_d$
 $-V_E < V_d < V_E$



Ideal op-amp:

Even more "ideal" characteristics

A: very large "gain".

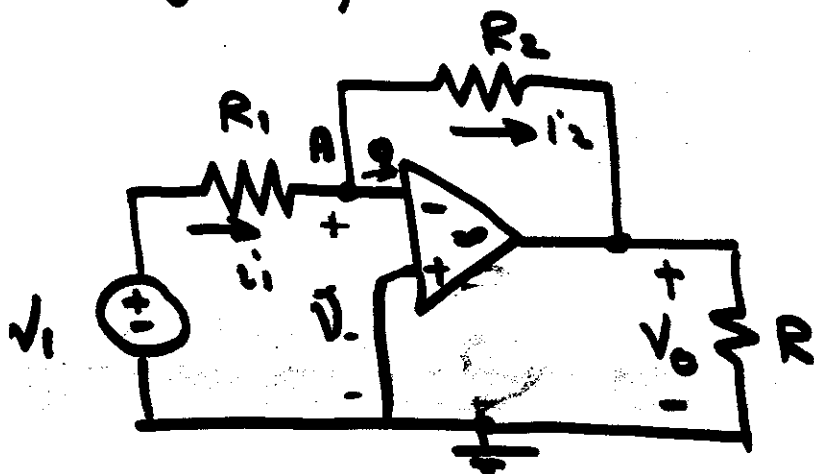


if $A \rightarrow \infty$
 $V_{out} = A \cdot V_d \rightarrow 0$
 ↑ finite ↑ infinite

$$V_+ - V_- = 0$$

$$\rightarrow -V_{sat} < V_o < V_{sat}$$

Inverting Amplifier



$$i_- = 0 \Rightarrow i_1 = i_2 \quad \text{KCL}$$

$$v_+ - v_- = 0 \Rightarrow v_- = 0 \quad (\text{because } v_+ = 0)$$

$$\text{KVL: } v_1 - R_1 \cdot i_1 - v_- = 0 \Rightarrow i_1 = \frac{v_1}{R_1}$$

$$v_- - R_2 \cdot i_2 - v_0 = 0 \Rightarrow v_0 = -R_2 \cdot i_2$$

$$\text{But, } i_1 = i_2 \quad (\text{KCL}) \Rightarrow v_0 = -R_2 \cdot \frac{v_1}{R_1}$$

$$v_0 = -\frac{R_2}{R_1} \cdot v_1$$

$$v_0 = A \cdot v_1 \quad \leftarrow$$

$$\text{Voltage gain: } A = -R_2/R_1$$

$$|v_0| < v_{\text{sat}} \Rightarrow |v_1| < \frac{R_1}{R_2} \cdot v_{\text{sat}} \quad \leftarrow$$

only true if $|V_o| < V_{sat}$

$$\left| -\frac{R_2}{R_1} v_i \right| < V_{sat}$$

If: $|v_i| < \frac{R_1}{R_2} \cdot V_{sat}$

then: $v_o = -\frac{R_2}{R_1} \cdot v_i$

otherwise: $|v_o| = V_{sat}$

$-\frac{R_2}{R_1}$ = voltage gain
closed loop gain

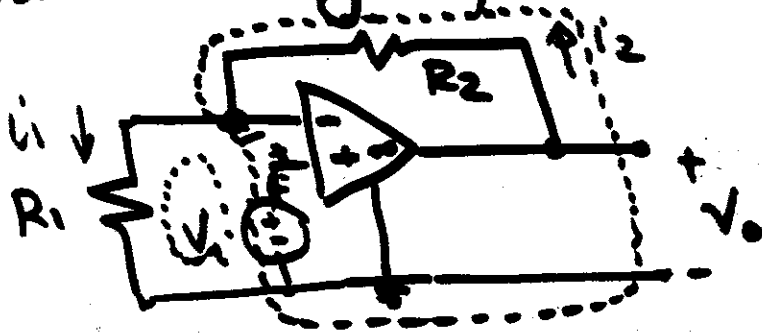
Recall: A = open loop gain

$$v_o = -\frac{R_2}{R_1} \cdot v_i$$

↑ inverting op-amp



Non-inverting amplifier



$$i_- = 0 \Rightarrow i_1 = i_2$$

$$v_- - v_+ = 0 \Rightarrow v_- = v_+ = v_i$$

$$v_- - R_1 \cdot i_1 = 0 \Rightarrow i_1 = \frac{v_i}{R_1}$$

$$v_o - R_2 \cdot i_2 - v_- = 0$$

$$v_o = R_2 \cdot i_2 + v_- \quad \uparrow = v_i$$

$$v_o = R_2 \cdot i_2 + v_i$$

$$v_o = R_2 \cdot i_1 + v_i$$

$$v_o = R_2 \cdot \frac{v_i}{R_1} + v_i$$

$$\rightarrow v_o = \left(1 + \frac{R_2}{R_1}\right) \cdot v_i$$

$$v_o = k \cdot v_i$$

$$k = 1 + \frac{R_2}{R_1}$$

non-inverting

$$\text{And: } |v_o| < v_{\text{sat}} \Rightarrow |v_i| < \frac{R_1}{R_1 + R_2} \cdot v_{\text{sat}}$$

The voltage follower

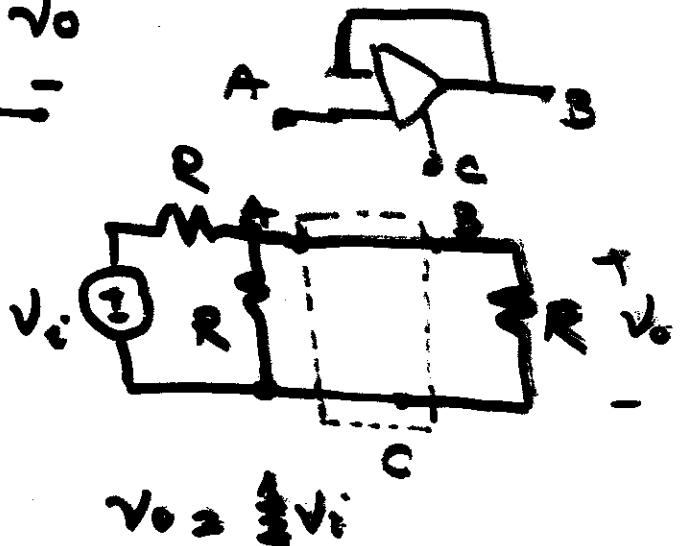
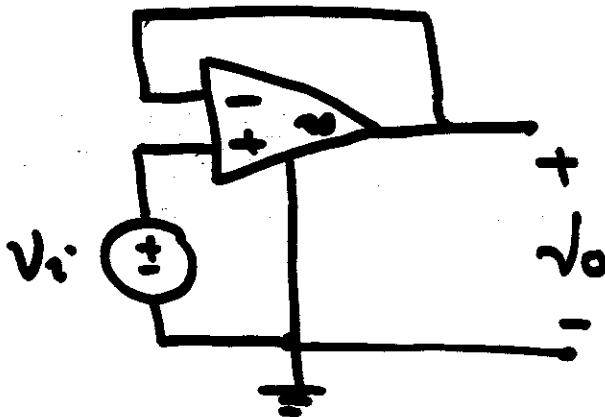
Assume $R_2 = 0$ (feedback resistor)

$$V_o = \left(1 + \frac{R_2}{R_1}\right) \cdot V_i$$

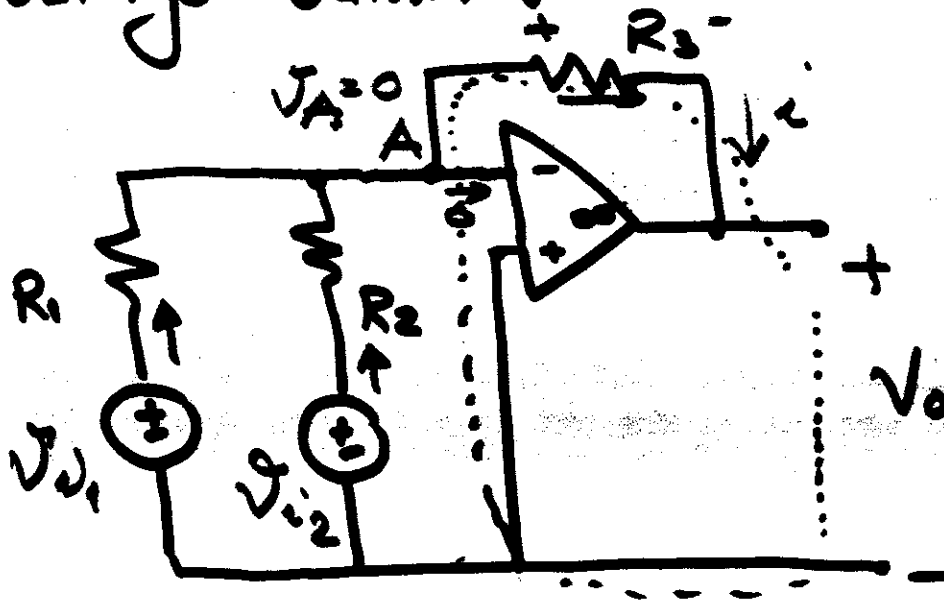
$$R_2 = 0$$

$$V_o = V_i \quad \text{gain} = 1$$

R_1 : does not matter



Voltage Summer:



$$i_{i1} = \frac{V_{i1}}{R_1}$$

$$i_{i2} = \frac{V_{i2}}{R_2}$$

$$i = i_{i1} + i_{i2} \Rightarrow i = \frac{V_{i1}}{R_1} + \frac{V_{i2}}{R_2}$$

KVL: $V_o + R_3 \cdot i = 0$

$$V_o = -R_3 \cdot \left(\frac{V_{i1}}{R_1} + \frac{V_{i2}}{R_2} \right)$$

Sum

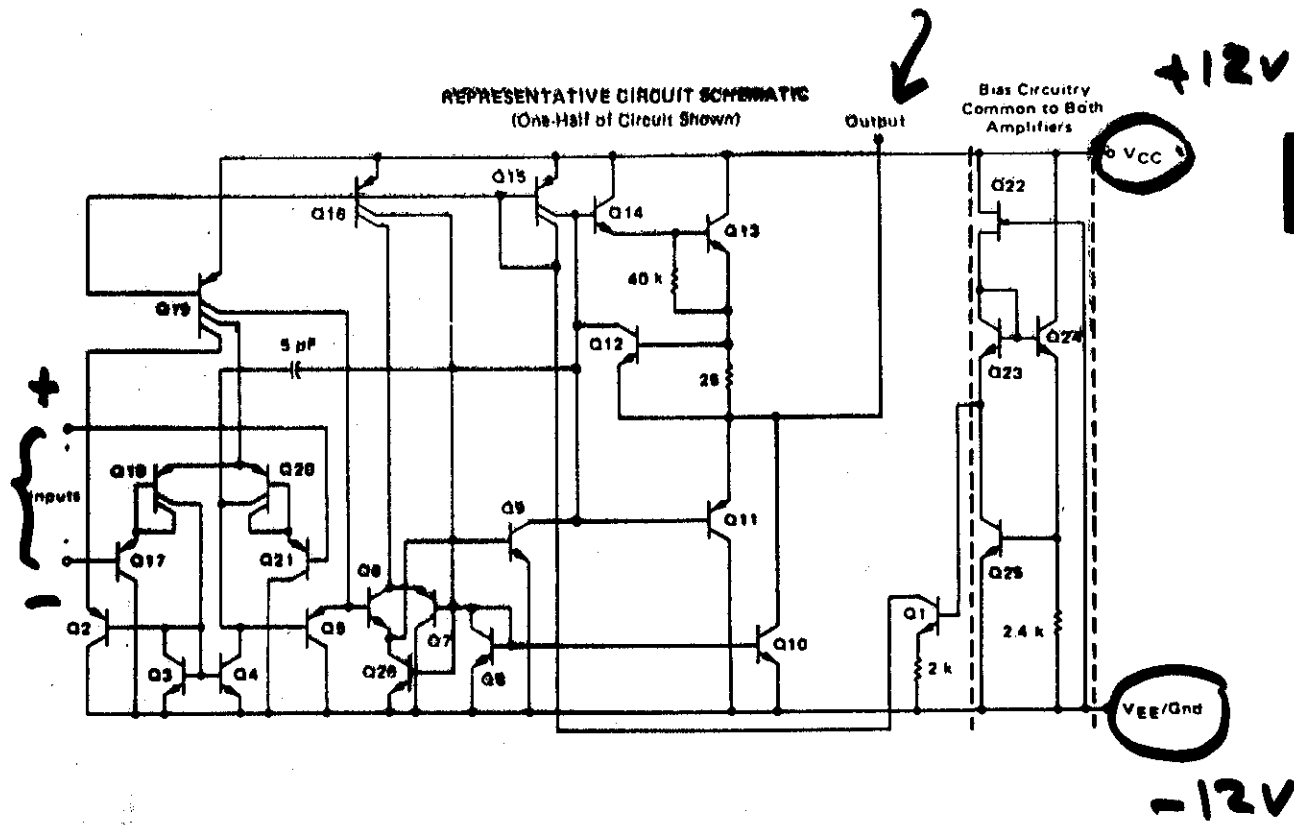
LM158, LM258, LM358, LM2904

LM2904				
Max	Min	Typ	Max	Unit
7.0	-	2.0	7.0	mV
9.0	-	-	10	
-	-	7.0	-	$\mu\text{V}/^\circ\text{C}$
50	-	5.0	50	nA
150	-	45	200	
-	-	10	-	$\mu\text{A}/^\circ\text{C}$
-250	-	-45	-250	nA
-500	-	-50	-900	
28.3	0	-	24.3	V
28	0	-	24	
VCC	-	-	VCC	V
-	-	100	-	V.mV
-	-	-	-	
-	-	-120	-	dB
-	50	70	-	dB
-	50	100	-	dB
3.3	0	-	3.3	V
-	22	-	-	V
-	23	24	-	
20	-	5.0	20	mV
-	20	40	-	mA
-	10	20	-	mA
-	-	-	-	μA
60	-	40	60	mA
3.0	-	1.5	3.0	mA
1.2	-	0.7	1.2	

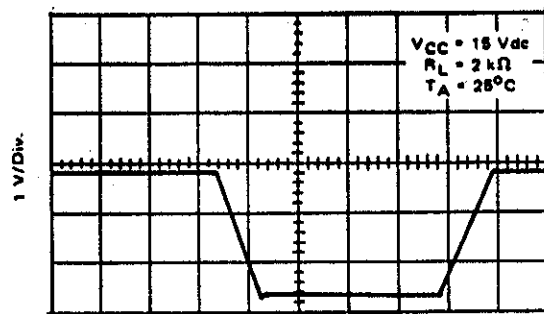
The common mode voltage range of both inputs can go to -32 V (LM2904).

Output to VCC can cause excessive current. Destructive dissipation.

REPRESENTATIVE CIRCUIT SCHEMATIC
(One-Half of Circuit Shown)



LARGE SIGNAL VOLTAGE FOLLOWER RESPONSE



5.0 $\mu\text{s}/\text{Div.}$

CIRCUIT DESCRIPTION

The LM158 Series is made using two internally compensated, two-stage operational amplifiers. The first stage of each consists of differential input devices Q20 and Q18 with input buffer transistors Q21 and Q17 and the differential to single ended converter Q3 and Q4. The first stage performs not only the first stage gain function but also performs the level shifting and transconductance reduction functions. By reducing the transconductance a smaller compensation capacitor (only 5 pF) can be employed, thus saving chip area. The transconductance reduction is accomplished by splitting the collectors of Q20 and Q18. Another feature of this input stage is that the input common-mode range can include the negative supply or ground, in single supply operation, without saturating either the input devices or the differential to single-ended converter. The second stage consists of a standard current source load amplifier stage.



MOTOROLA

LM158, LM258,
LM358, LM2904

Specifications and Applications Information

DUAL LOW POWER OPERATIONAL AMPLIFIERS

Utilizing the circuit designs perfected for recently introduced Quad Operational Amplifiers, these dual operational amplifiers feature 1) low power drain, 2) a common mode input voltage range extending to ground/VEE, 3) Single Supply or Split Supply operation and 4) pin outs compatible with the popular MC1558 dual operational amplifier. The LM158 Series is equivalent to one-half of an LM124.

These amplifiers have several distinct advantages over standard operational amplifier types in single supply applications. They can operate at supply voltages as low as 3.0 Volts or as high as 32 Volts with quiescent currents about one-fifth of those associated with the MC1741 (on a per amplifier basis). The common mode input range includes the negative supply, thereby eliminating the necessity for external biasing components in many applications. The output voltage range also includes the negative power supply voltage.

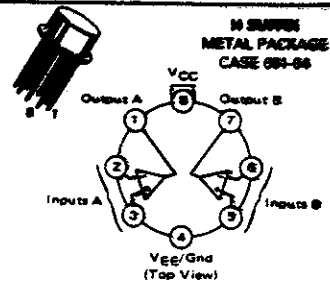
- Short Circuit Protected Outputs
- True Differential Input Stage
- Single Supply Operation: 3.0 to 32 Volts
- Low Input Bias Currents
- Internally Compensated
- Common Mode Range Extends to Negative Supply
- Single and Split Supply Operation
- Similar Performance to the Popular MC1558

MAXIMUM RATINGS (T _A = +25°C unless otherwise noted)				
Rating	Symbol	LM158 LM258 LM358	LM2904	Unit
Power Supply Voltages				Vdc
Single Supply	V _{CC}	32	26	
Split Supplies	V _{CC} , V _{EE}	:16	-13	
Input Differential Voltage Range (1)	V _{IDR}	:32	:26	Vdc
Input Common Mode Voltage Range (2)	V _{ICR}	-0.3 to 32	-0.3 to 26	Vdc
Input Forward Current (3)	I _{IF}	50	-	mA
(V _I = -0.3 V)				
Output Short Circuit Duration	t _S	Continuous		
Junction Temperature	T _J	175		°C
Ceramic and Metal Packages		150		
Plastic Package				
Storage Temperature Range	T _{STG}	-65 to +150		°C
Ceramic and Metal Packages		-55 to +125		
Plastic Package				
Operating Ambient Temperature Range	T _A			°C
LM158		-55 to +125	-	
LM258		-25 to +85	-	
LM358		0 to +70	-	
LM2904		-	-40 to +85	

(1) Split Supply Supplies
 (2) For Supply Voltages less than 32 V for the LM158, 258, 358 and 26 V for the LM2904, the absolute maximum input voltage is equal to the supply voltage.
 (3) This input current will only exist when the voltage is negative at any of the input leads. Normal output states will reestablish when the input voltage returns to a voltage greater than 0.3 V.

DUAL DIFFERENTIAL INPUT OPERATIONAL AMPLIFIERS

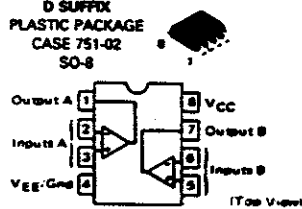
SILICON MONOLITHIC INTEGRATED CIRCUIT



J SUFFIX CERAMIC PACKAGE CASE 085-02



D SUFFIX PLASTIC PACKAGE CASE 751-02 SO-8



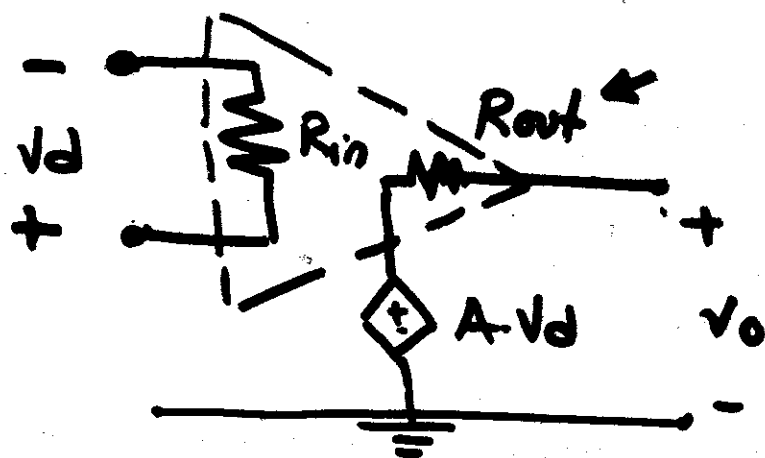
ORDERING INFORMATION

Device	Temperature Range	Package
LM158H	-55 to +125°C	Metal Can
LM158J		Ceramic DIP
LM2904D	-40 to +85°C	SO-8
LM2904H		Metal Can
LM2904J	-25 to +85°C	Ceramic DIP
LM2904K		Plastic DIP
LM258D	-25 to +85°C	SO-8
LM258H		Metal Can
LM258J	-25 to +85°C	Ceramic DIP
LM258K		Plastic DIP
LM358D	0 to +70°C	SO-8
LM358H		Metal Can
LM358J	0 to +70°C	Ceramic DIP
LM358K		Plastic DIP

Nonideal op-amp models

Assumptions:

1. R_{in} large, but $< \infty$
2. A large, but $< \infty$
3. R_{out} small, but > 0



$$v_o = A \cdot v_d$$

Circuit analyzed by applying

KCL
KVL

Transistors and their models

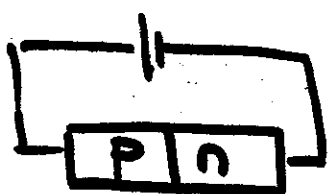
inventor by W. Shockley
 J. Bardeen } Bell Laboratories
 J. Brattain } 1953

BJT: Bipolar junction transistor

MOS: Metal Oxide Silicon transistor

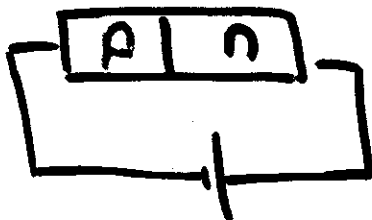
FET: Field Effect transistor

JFET: junction FET



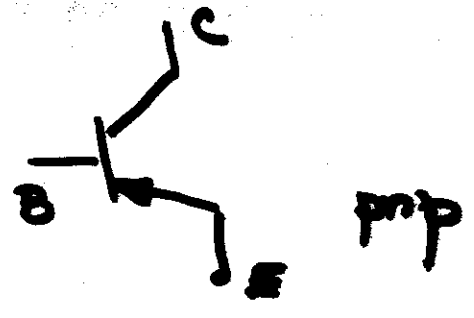
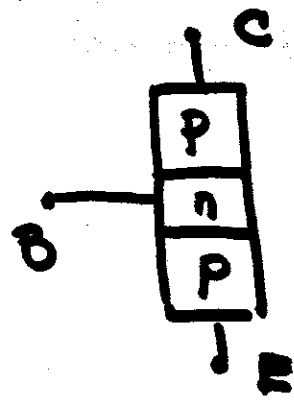
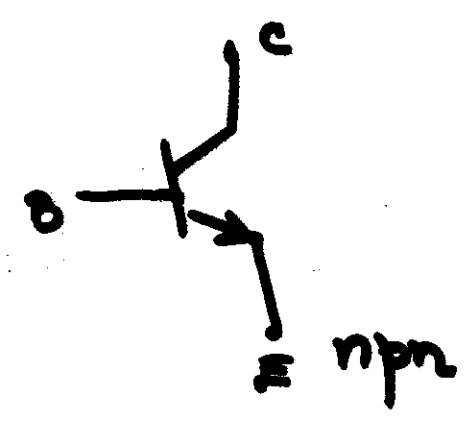
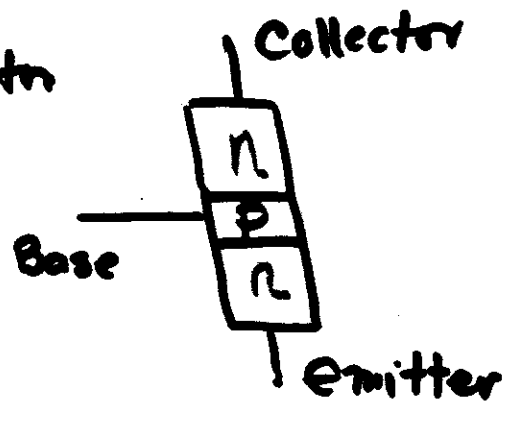
Forward biased

Semiconductor junction
 <diode>

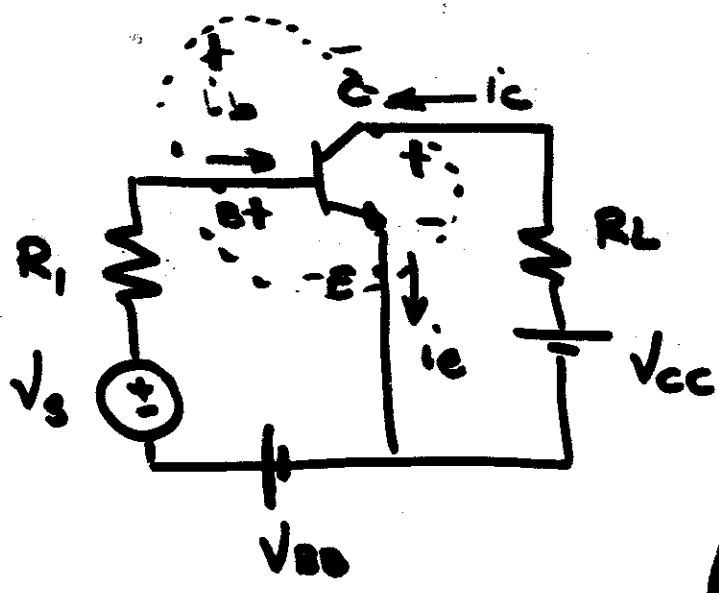


Reverse biased

Transistor



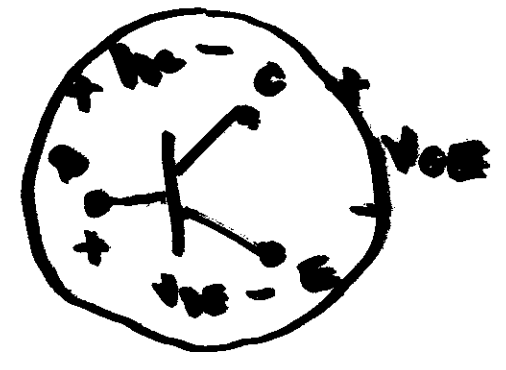
BJT

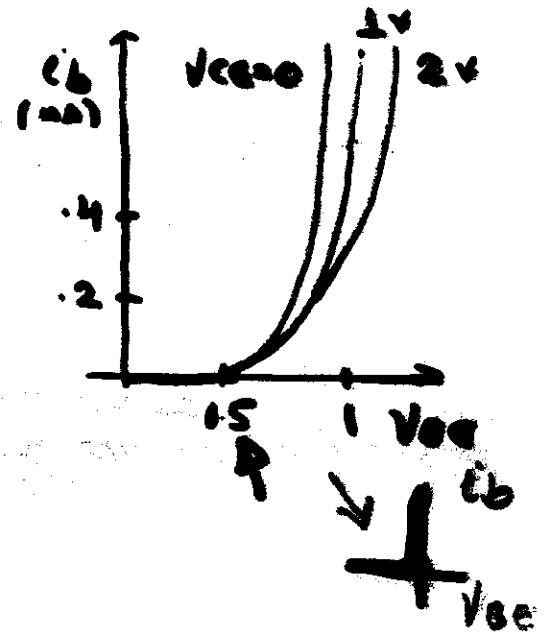
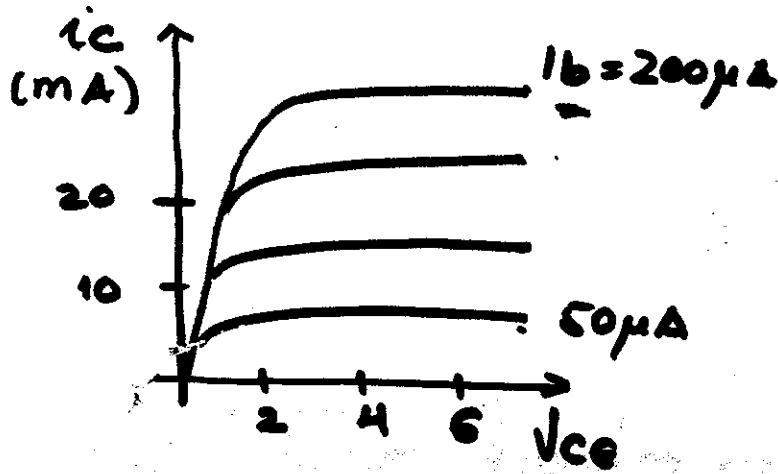



$$i_e = i_b + i_c$$

$$V_{CC} = V_{CE} - V_{BE}$$

BJT



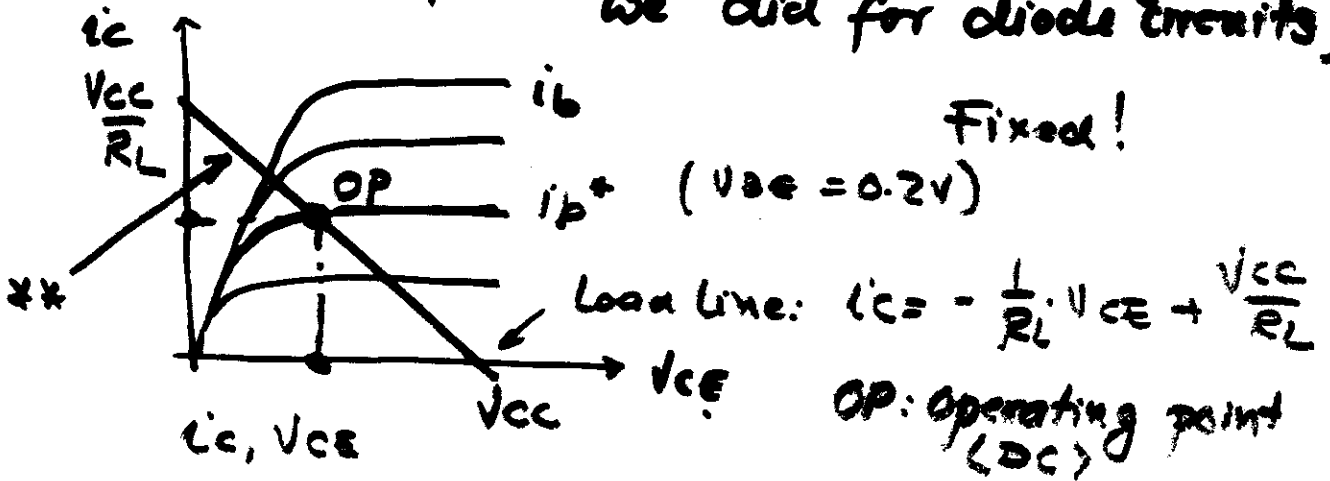


For the circuit called transistor amplifier: 

$$* \quad \underline{I_B} = -\frac{1}{R_1} \cdot V_{BE} + \frac{V_{BB}}{R_1} \quad \leftarrow \text{KVL}$$

$$** \quad \underline{I_C} = -\frac{1}{R_L} \cdot V_{CE} + \frac{V_{CC}}{R_L} \quad \leftarrow \text{KVL} \quad \underline{V_S = 0}$$

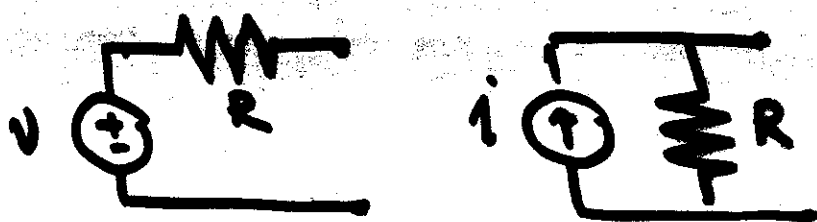
Load line analysis (similar to the analysis we did for diode circuits)



General Analysis of dissipative Circuits 25

Systematic approach:

Source:



Accompanied!

<Essential!>

Branch variables:

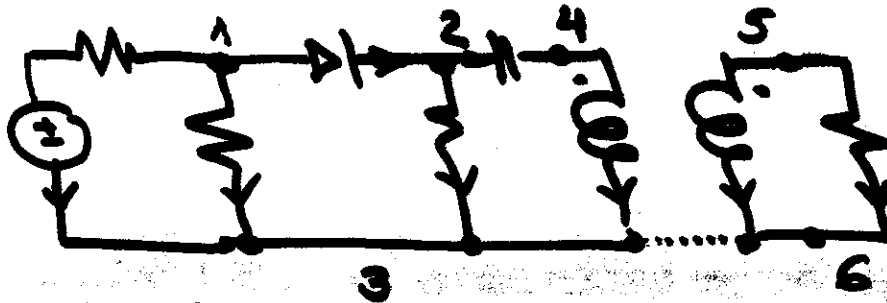
Voltages : v
currents : i

For every branch :- Two variables

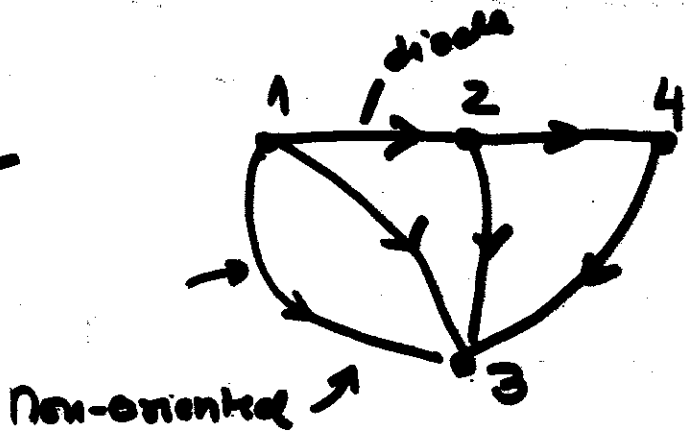
- One equation relating v and i

ex: Ohm's law
graph if nonlinear
or function

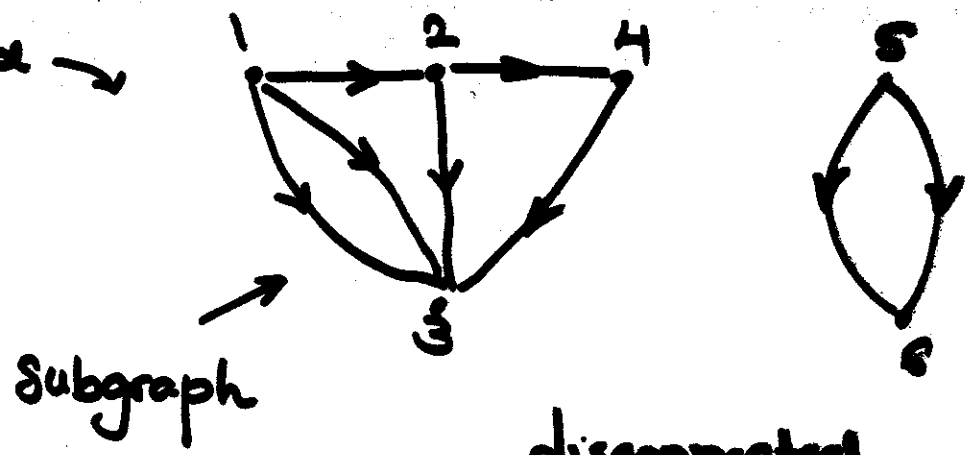
Graph of a circuit:



↑
↓
+
-
V



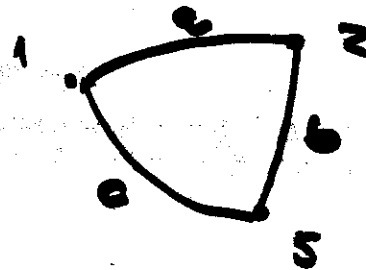
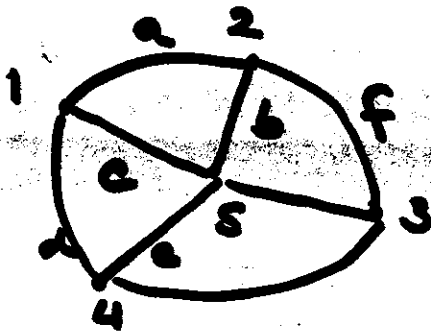
Oriented →



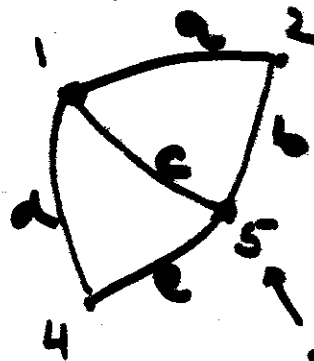
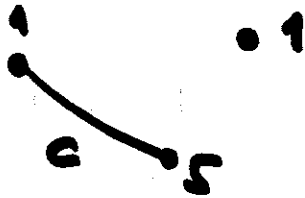
disconnected
Graph

Loops:

A connected subgraph that has exactly two branches of the subgraph incident at each of its nodes



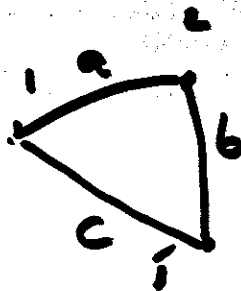
Loop



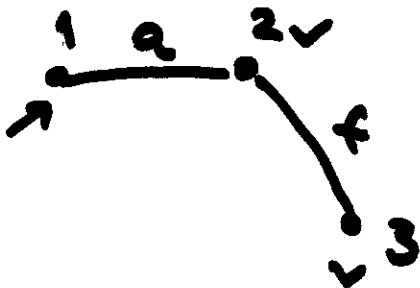
X loop

3 branches incident to node 5.

"incident"

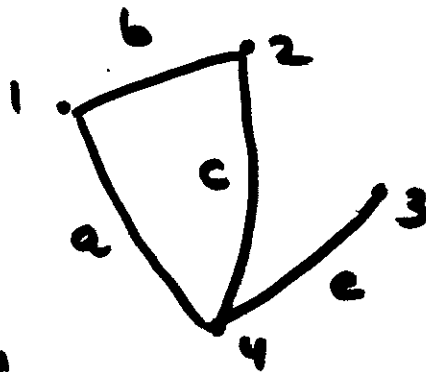
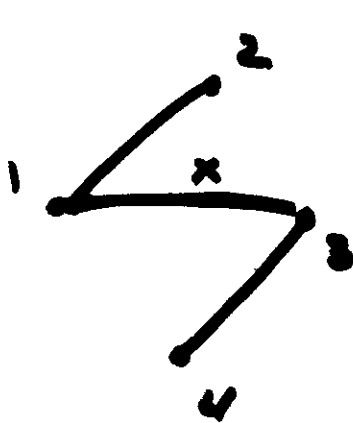
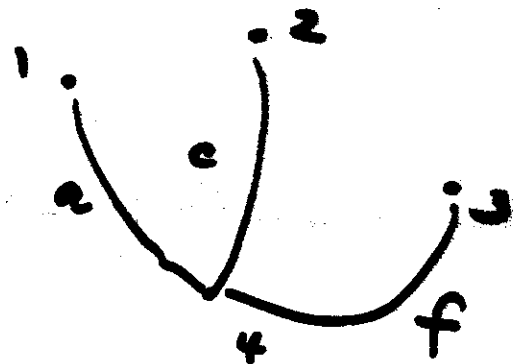
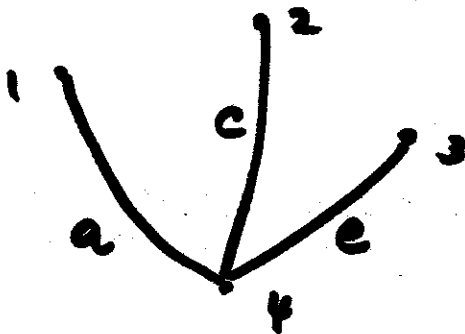
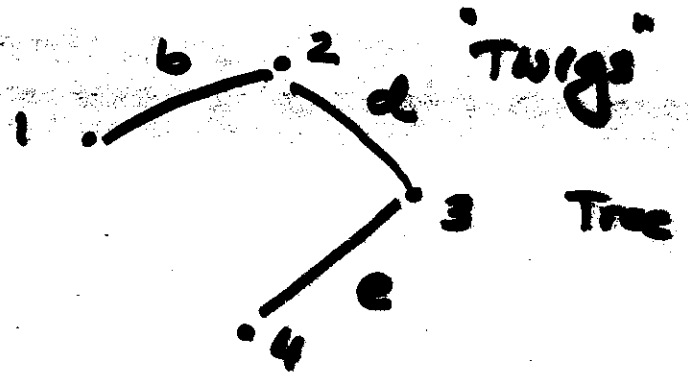
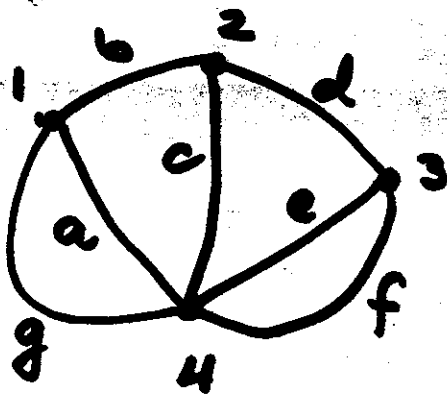


a is incident to nodes 1 and 2.



Tree :

A connected subgraph consisting of a set of branches which connect all the nodes of the graph without forming any loops



X Tree
Loop: a, b, c

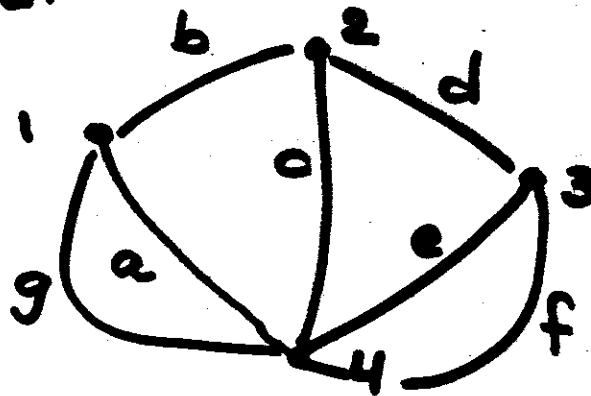
↓
<co-trees> links

There are many trees in a given graph.
 (The number is finite.)

In a graph with: b : branches
 n : nodes

We can choose a tree:

Example.



$n = 4$
 $b = 7$

Example



(3)

Tree: a, c, e (twigs)

= $n - 1$

Co-tree: b, d, f, g (links)

= $b - (n - 1)$ (4)

example

In any connected graph:

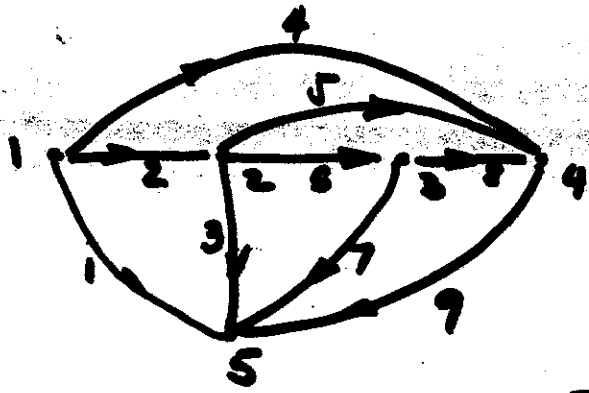
No. of twigs = $n - 1$

No. of links = $b - (n - 1)$

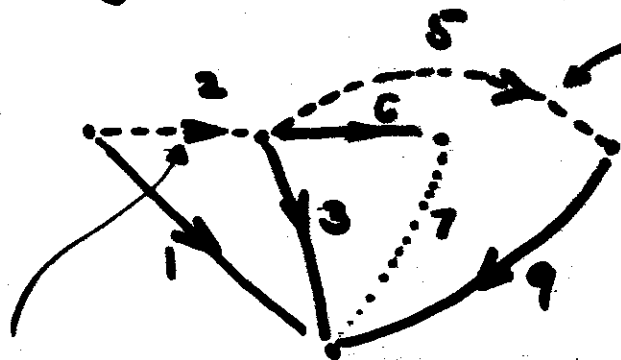
< The rest of branches >

Independent Voltage Equations:

Number = $n-1$:= number of twigs



Why?

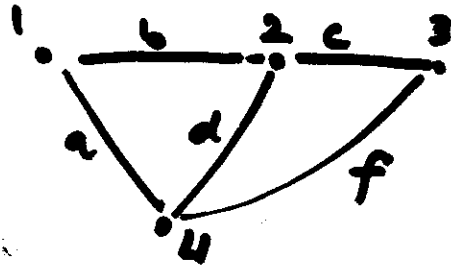


kvl:
 $V_4 + V_9 - V_3 = 0$
 $V_4 = V_3 - V_9$
 link twigs

kvl:
 $V_2 + V_3 - V_1 = 0$
 $V_2 = V_1 - V_3$
 link twigs

Fundamental loops: A loop formed by adding any one link to a tree.
 → 1, 2, 3
 → 3, 5, 9 Also: 3, 6, 7 But not: 7, 8, 9

The number of independent voltages =
the number of twigs.



$$\begin{aligned} n &= 4 \\ n-1 &= 3 \\ b &= 5 \end{aligned}$$

of independent voltages
= 3

$V_a, V_b,$ and V_c

In a graph having b branches and n nodes,
there are $b-(n-1)$ fundamental loops

Number of independent KVL equations
is exactly

$$b-(n-1)$$

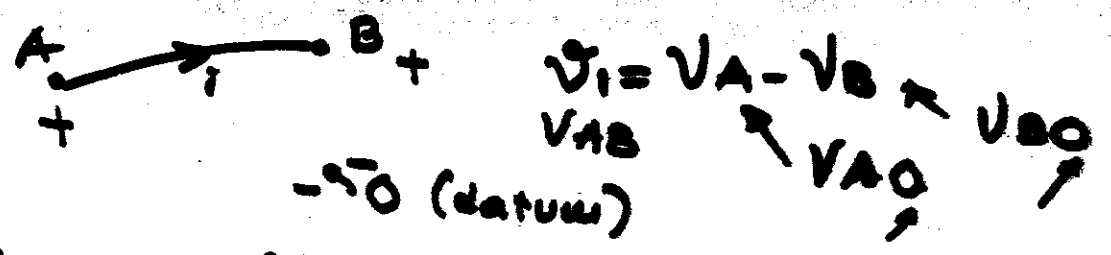
$$5-3=2$$

↳ fundamental loops
independent KVL
equations

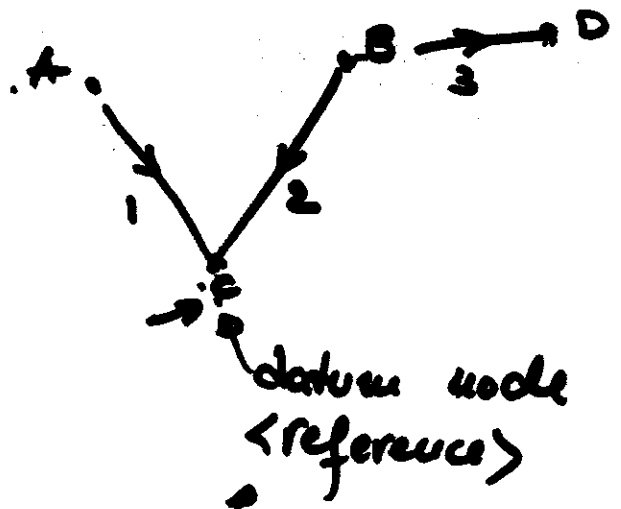
Node voltages as a basis set:

$n-1$: node voltages

- Each twig voltage = difference in voltage of the nodes at its two ends



- All nodes lie on a tree. Tree is connected. There must be a path in the tree from each node to every other node. Node voltages can be expressed in terms of twig voltages



$v_A \text{ wrt } C = v_1$

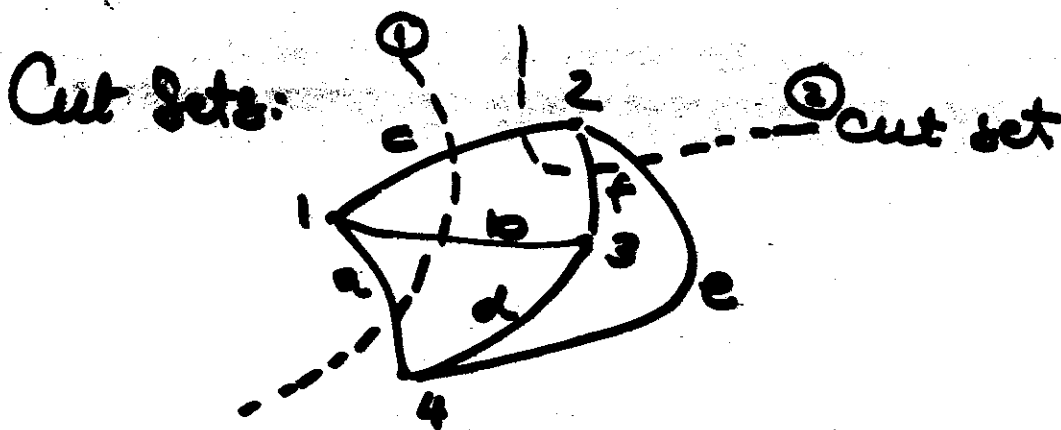
$v_B \text{ wrt } C = v_2$

$v_D \text{ wrt } C = v_2 - v_3$

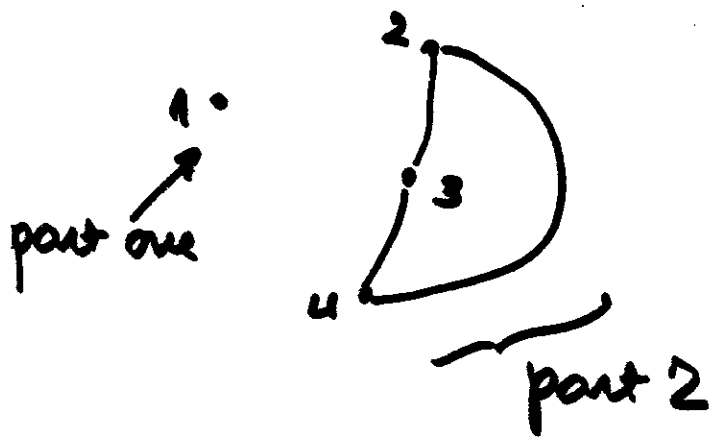
useful to choose a node to which most branches are connected

The set of node voltages is a basis set.
 All branch voltages can be obtained from node voltages.

How about currents?



It is a set of the smallest number of branches of a graph which, when cut, divide it into two parts:



Cut-set: a, b, c ①
 c, f, e ②

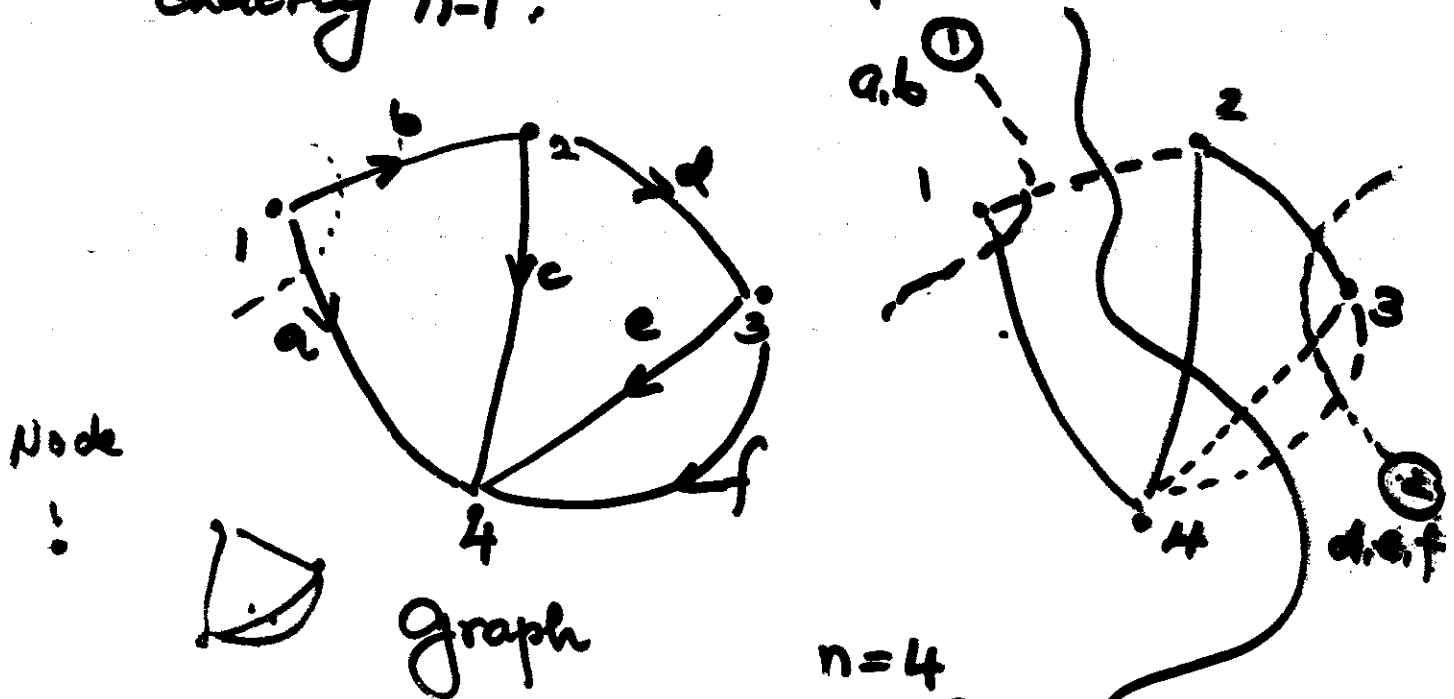
a, b, c, f x

Fundamental cut set: contains only one twig

There are $n-1$ fundamental cut sets
 (For each tree there are $n-1$ twigs)

Independent Current equations:

In a graph having n nodes, the number of independent KCL equations is exactly $n-1$.



Node
1



Graph

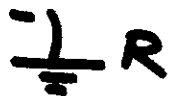
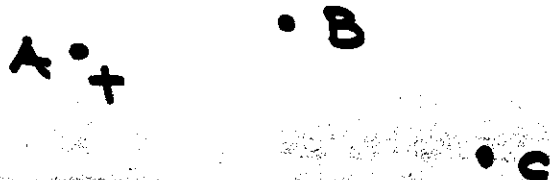
$n = 4$
 $n - 1 = 3$

$i_a + i_b = 0 \quad \textcircled{1}$
 $-i_d + i_e + i_f = 0 \quad \textcircled{2}$
 $i_b - i_c - i_e - i_f = 0 \quad \textcircled{3}$

③ Cut-set
 b, c, e, f ✓

Node Equations:

1. Choose a datum (reference) node



$$V_{AR} = V_A$$

$$V_{BR} = V_B$$

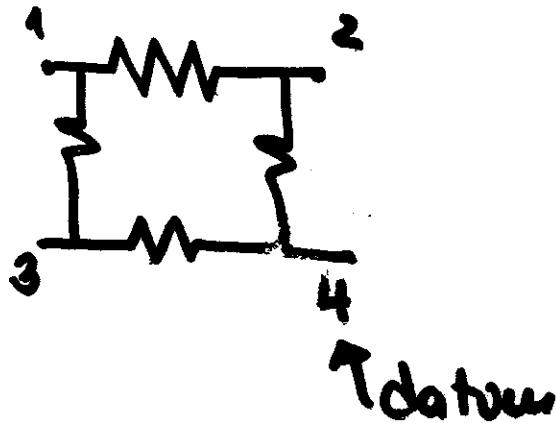
$$V_{CR} = V_C$$

$$V_{AB} = V_A - V_B$$

↑
branch
voltage

↑
Node voltage
(w/ datum node)

(w/ datum node)



$$V_{12} = V_1 - V_2$$

↓
 V_{13} ↓
 V_{24}
 ↑ ↑
 datum datum
 node node

Node-voltage analysis <or: Node Analysis>

Procedure:

- Write KCL equations at all non-reference nodes

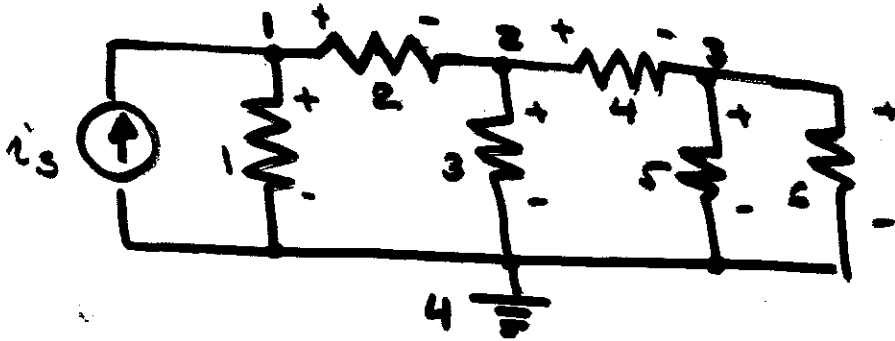
$n-1$ equations with \underline{b} unknowns
 \uparrow
 currents
- Eliminate currents by using Ohm's Law

$i = G \cdot v$

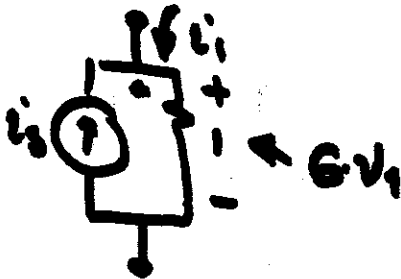
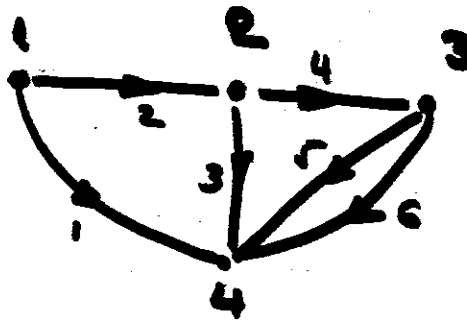
$n-1$ equations with b unknowns
 \uparrow
 voltages
- Eliminate b branch voltages by expressing them in terms of $n-1$ node voltages

$n-1$ equations with $n-1$ unknowns
 \uparrow
 node voltages

Example:



Graph:



$$i_2 + i_3 = G \cdot V_{b1}$$

$$i_1 = G \cdot V_{b1} - i_s$$

$$i_1 + i_2 = 0$$

$$\text{Step 1: } -i_2 + i_3 + i_4 = 0$$

$$-i_4 + i_5 + i_6 = 0$$

Eq: 3 unknown: 6

$$\text{Step 2: } G_1 V_{b1} - i_s + G_2 V_{b2} = 0$$

$$-G_2 V_{b2} + G_3 V_{b3} + G_4 V_{b4} = 0$$

$$-G_4 V_{b4} + G_5 V_{b5} + G_6 V_{b6} = 0$$

Eq: 3 unknown: 6

Step 3: $v_{b1} = v_1 - v_4$ ← datum node

$$\rightarrow v_{b1} = v_1$$

$$v_{b2} = v_1 - v_2$$

$$v_{b3} = v_2$$

$$v_{b4} = v_2 - v_3$$

$$v_{b5} = v_3$$

$$v_{b6} = v_3$$

Hence:

$$G_1 \cdot v_1 + G_2 \cdot (v_1 - v_2) = i_s$$

$$-G_2 \cdot (v_1 - v_2) + G_3 \cdot v_2 + G_4 \cdot (v_2 - v_3) = 0$$

$$-G_4 \cdot (v_2 - v_3) + G_5 \cdot v_3 + G_6 \cdot v_3 = 0$$

or:

Eq: 3

unknown: 3

=

=

$$(G_1 + G_2) \cdot v_1 - G_2 \cdot v_2 = i_s$$

$$-G_2 \cdot v_1 + (G_2 + G_3 + G_4) v_2 - G_4 \cdot v_3 = 0$$

$$-G_4 \cdot v_2 + (G_4 + G_5 + G_6) v_3 = 0$$

Matrix form:

$$\begin{bmatrix} G_1 + G_2 & -G_2 & 0 \\ -G_2 & G_2 + G_3 + G_4 & -G_4 \\ 0 & -G_4 & G_4 + G_5 + G_6 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} i_s \\ 0 \\ 0 \end{bmatrix}$$

$G \cdot v = i_s \leftarrow \text{sources}$
 \uparrow \nwarrow
 3×3 node voltages
 $(n-1) \times (n-1)$
 $n = 4$

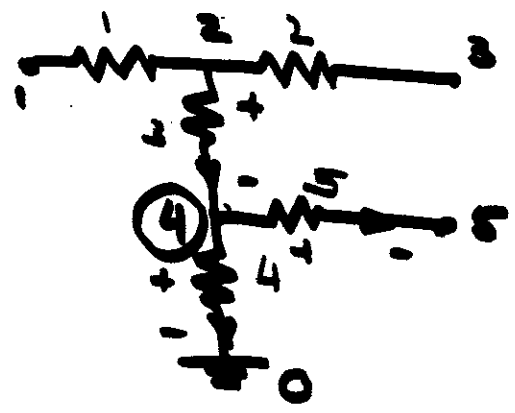
This is a general algorithm!

In a circuit with resistors only:

$G = \text{symmetric}$
 diagonal elements: all positive
 off diagonal elements: all negative.

} consistent !!!

< Above is not true if controlled sources are present >



$$-i_3 + i_4 + i_5 = 0$$

$$-G_3 \cdot V_{b3} + G_4 \cdot V_{b4} + G_5 \cdot V_{b5} = 0$$

\downarrow \uparrow \uparrow
 $V_2 - V_4$ V_4 $V_4 - V_5$

$$-G_3 \cdot (V_2 - V_4) + G_4 V_4 + G_5 (V_4 - V_5) = 0$$

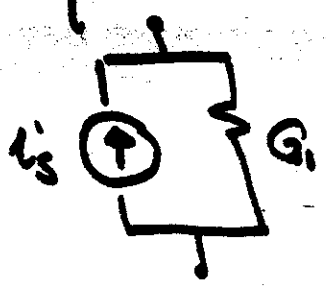
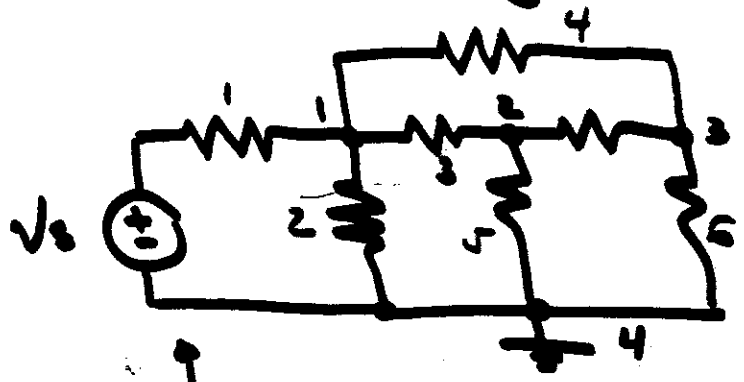
$$-G_3 \cdot V_2 + \underbrace{(G_3 + G_4 + G_5)}_{\text{all +}} V_4 - G_5 V_5 = 0$$

Conductance
between nodes
2 and 4

Sum of all
conductances connects
to node 4

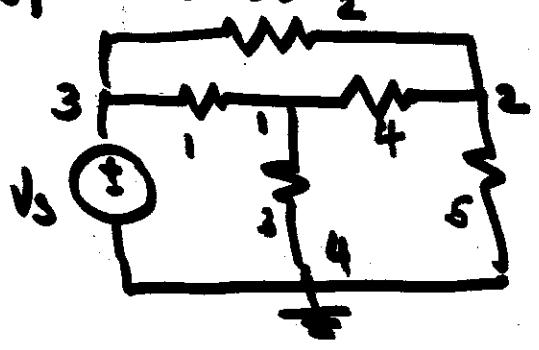
Conductance
between nodes
5 and 4

How about voltage sources?



acomponed source, an easily transformed into each other!

But, how about:



$V_3 = V_s$ known!!

No need to write KCL equation for node 3.

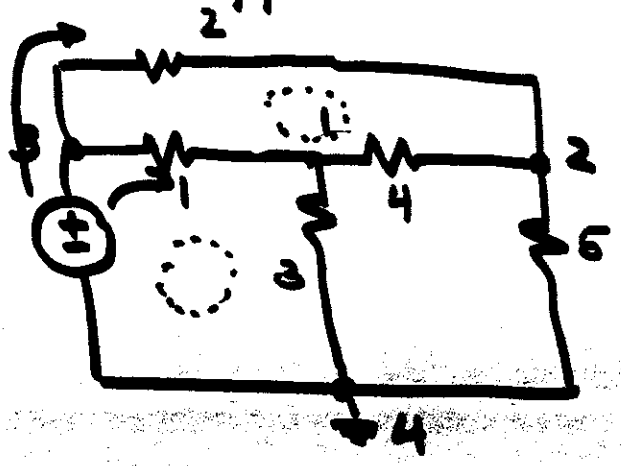
Node equations:

$$G_1 \cdot (V_1 - V_3) + G_2 \cdot V_1 + G_4 \cdot (V_1 - V_2) = 0$$

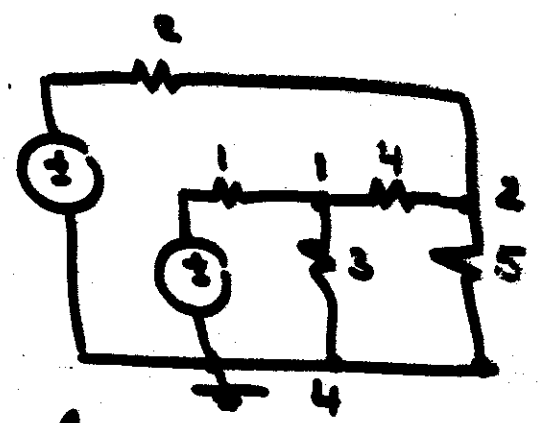
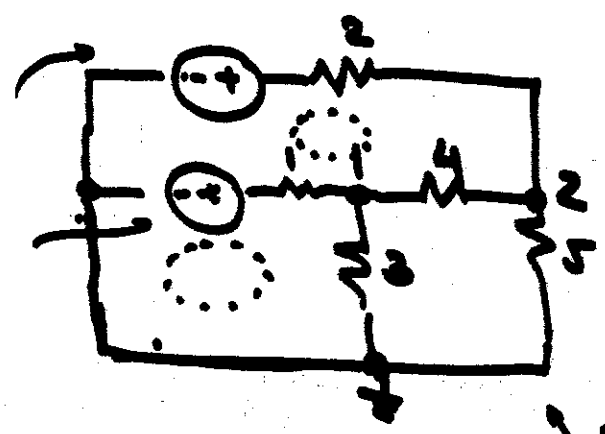
$$G_2 \cdot (V_2 - V_3) + G_4 \cdot (V_2 - V_1) + G_5 \cdot V_2 = 0$$

Eq: 2 = unknown V_1, V_2
2

Another approach: source shift



Voltage source shift:



Same equations describe both circuits.

Loop and mesh equations:

b : branches
 n : nodes

$n-1$: KCL equations

< fundamental
cut-sets >

$b-(n-1)$: KVL equations

< fundamental
loops >

$2b$ unknowns : b branch voltages
 b currents.

b : equations relating branch voltages
and currents

Hence:

$$\begin{matrix} n-1 \\ b-(n-1) \end{matrix} \left. \vphantom{\begin{matrix} n-1 \\ b-(n-1) \end{matrix}} \right\} b \text{ equations (KVL)} \\ + \underline{b} \text{ (Ohm's law)}$$

$2b$ equations

with $2b$ variables

(voltages
currents)
in a branch

We need to solve 26 equations!

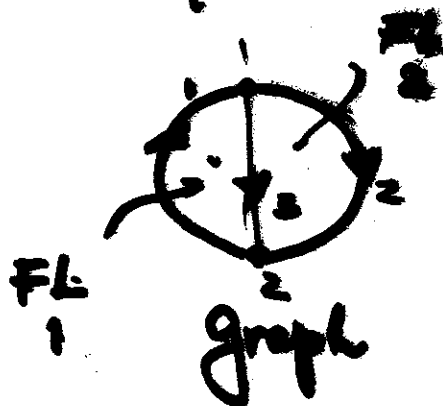
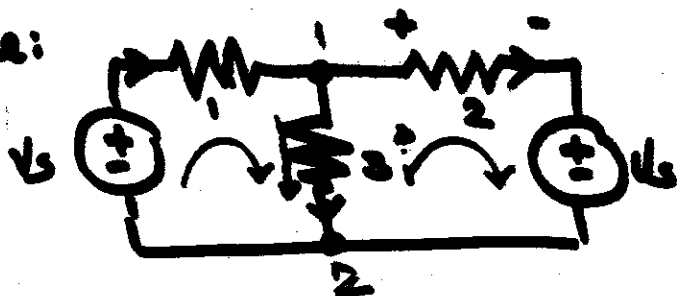
Can we do better?

↓ smaller set of equations to solve simultaneously

Yes: Node equations: $n-1$ simultaneous equations.

Another approach: Loop and mesh equations

Example:



FL: fundamental loop

$$V_{b1} + V_{b3} = 0$$

$$V_{b2} - V_{b3} = 0$$

$$-i_1 + i_2 + i_3 = 0$$

KVL

KCL

$$V_{b1} = -V_3 + R_1 i_1$$

$$V_{b2} = V_3 + R_2 i_2$$

(accompanied sources)

Eliminate branch voltages from KVL equation by using Ohm's law:

$$-V_s + R_1 i_1 + R_3 i_3 = 0$$

$$V_s + R_2 i_2 - R_3 i_3 = 0$$

$$\uparrow i_3 = i_1 - i_2$$

$$1. \quad (R_1 + R_3) i_1 - R_3 i_2 = V_s$$

$$2. \quad -R_3 i_1 + (R_2 + R_3) i_2 = -V_s$$

2 equations
2 unknowns

$$\begin{bmatrix} R_1 + R_3 & -R_3 \\ -R_3 & R_2 + R_3 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} V_s \\ -V_s \end{bmatrix}$$

current

i_1
 i_2

Link current:

: 1
: 2

$$R \cdot i = V_s$$

Loop equations

Algorithm for mesh equations:

1. Identify meshes and assign a mesh current
2. Write KVL in terms of branch voltages
3. Eliminate branch voltages by Ohm's law
4. Replace each branch current by one or difference of mesh currents.

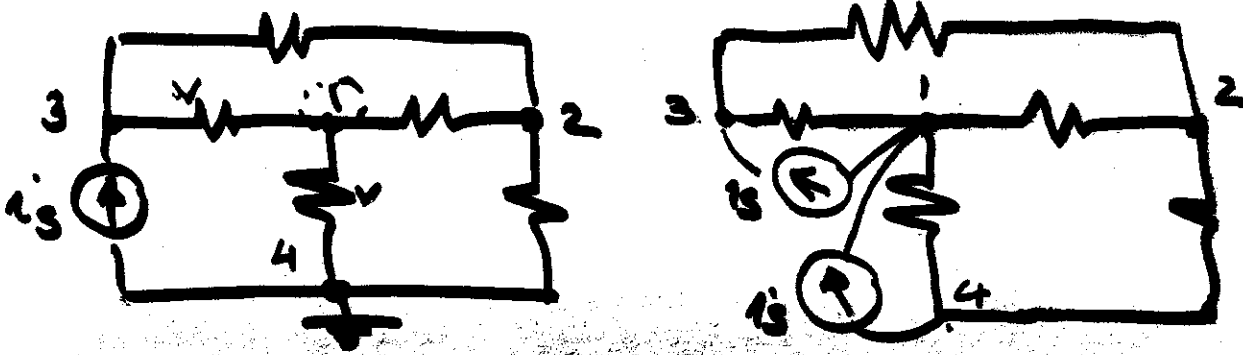
For our example:

$$-V_s + R_1 \cdot i_{m1} + R_3 \cdot (i_{m1} - i_{m2}) = 0$$

$$R_2 i_{m2} + V_s - R_3 \cdot (i_{m1} - i_{m2}) = 0$$

$$\left. \begin{aligned} (R_1 + R_3) i_{m1} - R_3 i_{m2} &= V_s \\ -R_3 i_{m1} + (R_2 + R_3) i_{m2} &= -V_s \end{aligned} \right\}$$

How about unaccompanied current sources?

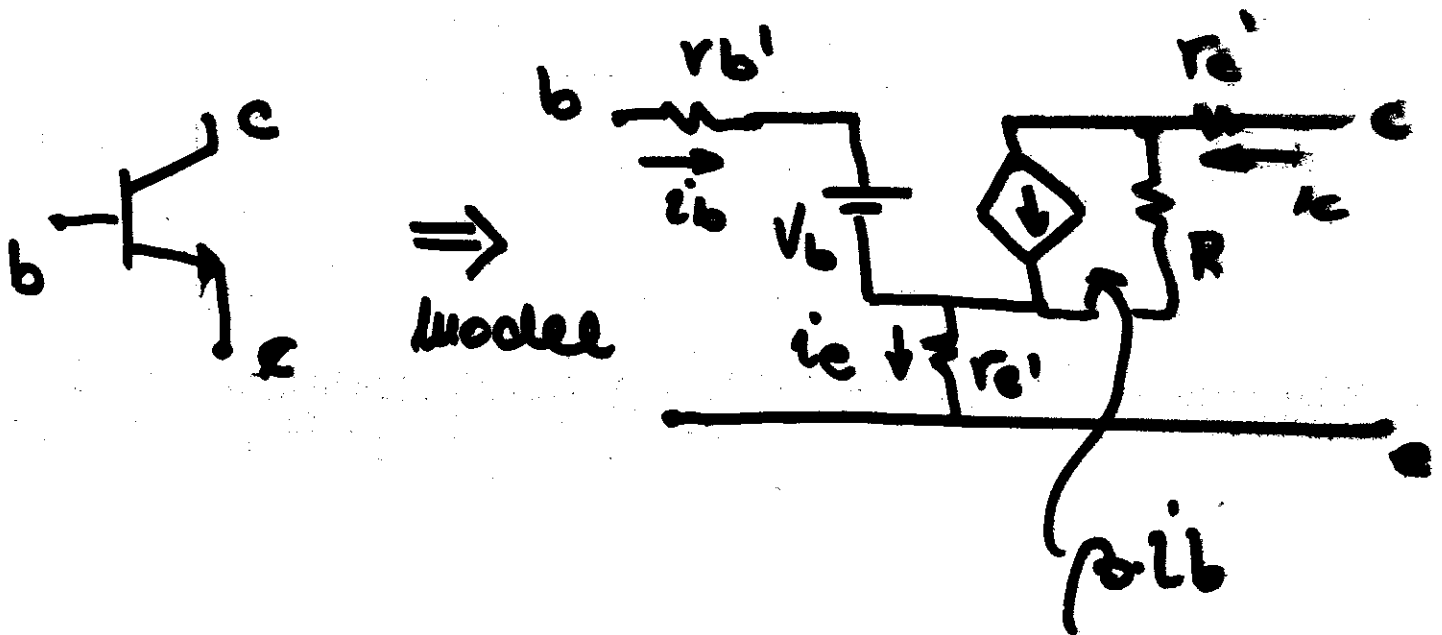
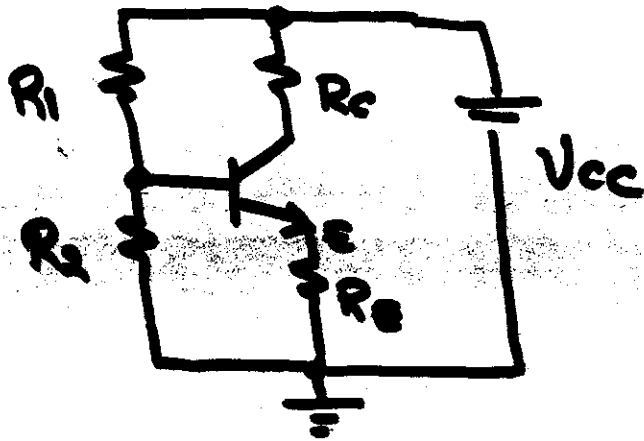


Current source shift!

KCL is the same in (a) and (b)!

How: each source is accompanied and can be transformed into a voltage source.

Simple amplifier circuit with a bipolar transistor.



$V_b: 0.2-0.7 \text{ v}$

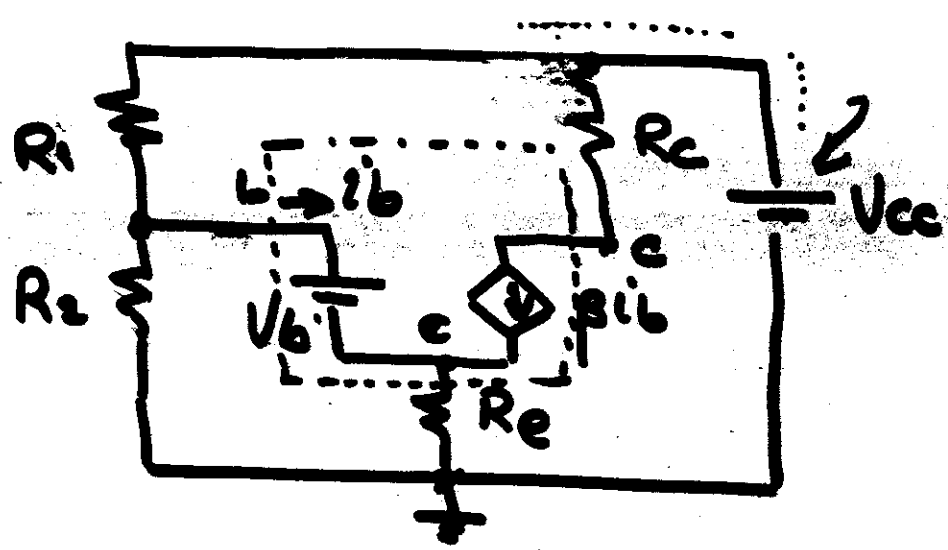
<technology dependent>

Simplified model: $r_b' = 0$ $r_e' = 0$
 $R = 0$

Sometimes even: $V_b = 0$, $R = 0$

Redraw the circuit:

< Replace BJT with its model >



$r_b' = 0$
 $r_c' = 0$
 $r_e' = 0$
 $R = \infty$

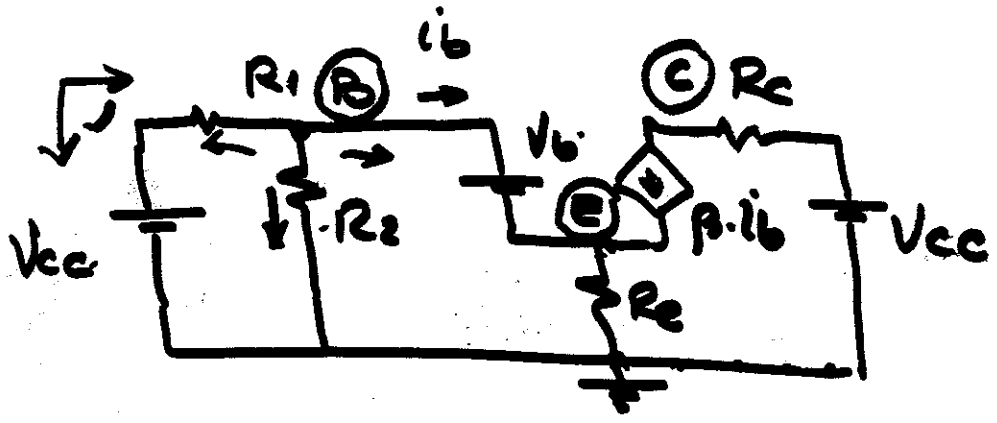
$i_c = \beta \cdot i_b$

< often used in BJT circuit >

Write nodal equations

1. There are unaccompanied independent voltage sources

< Do the "voltage source shift" before attempting to write equations >



Nodal equations:

< Note: V_b is unaccompanied by a resistor!

Special attention required for nodes B and E! >

Option: Do source shift on V_b

ⓑ

$$G_1 \cdot (V_B - V_{cc}) + G_2 \cdot V_B + \underline{i_b} = 0$$

ⓔ

$$-\underline{i_b} + G_E \cdot V_E - \beta \cdot \underline{i_b} = 0 \leftarrow$$

ⓒ

$$+\beta \cdot i_b + G_C \cdot (V_C - V_{cc}) = 0$$

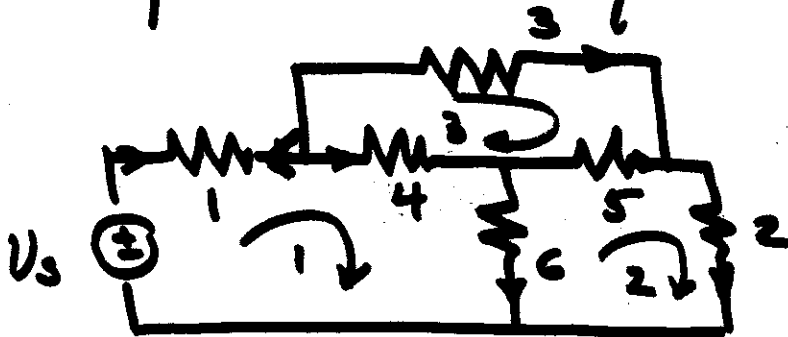
V_B
 V_E and $\underline{i_b}$
 V_C

Additional equation: $V_B - V_E = V_b$

4 equations
4 unknowns

How would you solve it by "shifting" V_b first?

Loop or mesh equations:



KVL for each mesh:

Mesh

①

$$+V_s - R_1 \cdot i_1 - R_4 \cdot (i_1 - i_3) - R_6 \cdot (i_1 - i_2) = 0$$

or

$$-V_s + R_1 i_1 + R_4 (i_1 - i_3) + R_6 (i_1 - i_2) = 0$$

Mesh

②

$$-R_2 \cdot i_2 + R_6 \cdot (i_2 - i_1) + R_5 \cdot (i_2 - i_3) = 0$$

Mesh

③

$$R_3 \cdot i_3 + R_5 \cdot (i_3 - i_2) + R_4 \cdot (i_3 - i_1) = 0$$

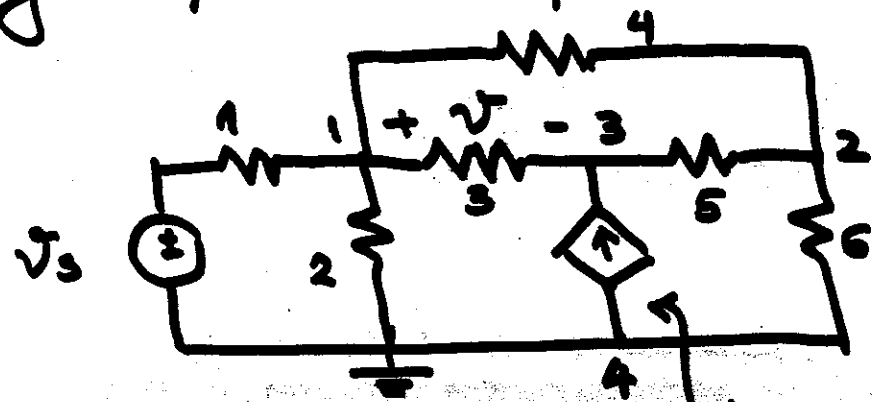
$\left. \begin{matrix} i_1 \\ i_2 \\ i_3 \end{matrix} \right\}$ Mesh currents

$$i_{b1} = i_1; \quad i_{b2} = i_2, \quad i_{b3} = i_3$$

$$\begin{aligned}
 i_{b4} &= i_1 - i_3 \\
 i_{b5} &= i_3 - i_2 \\
 i_{b6} &= i_1 - i_2
 \end{aligned}$$

Resistance

Fig 26 (p. 210) example:



$$G = \frac{1}{R}$$

conductance

$$i_{C3} = A \cdot V$$

voltage controlled
current source

datum node: 4

Node ①

$$G_1 (V_1 - V_s) + G_2 \cdot V_2 + G_3 \cdot (V_1 - V_3) + G_4 (V_1 - V_2) = 0$$

Node ②

$$G_4 \cdot (V_2 - V_1) + G_5 (V_2 - V_s) + G_6 \cdot V_2 = 0$$

Node ③

$$G_3 \cdot (V_3 - V_1) + G_5 (V_3 - V_s) - i_{C3} = 0$$

$$i_{C3} = A \cdot V$$

\uparrow
 $V_1 - V_3$

3 equations with 3 unknowns! $i_{C3} = A (V_1 - V_3)$

General dissipative circuits

113

Circuits with controlled sources:

< continued >

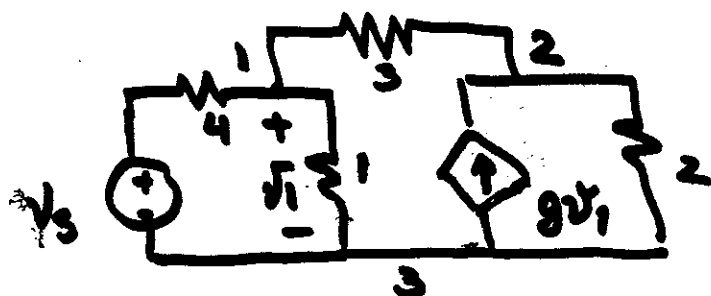


Fig. 28
p. 212

Nodal equations: < easy! >

$$\textcircled{1} \quad G_4 \cdot (v_1 - v_s) + G_1 \cdot v_1 + G_3 (v_1 - v_2) = 0$$

$$\textcircled{2} \quad G_3 \cdot (v_2 - v_1) + G_2 \cdot v_2 - g \cdot v_1 = 0$$

$$(G_1 + G_3 + G_4) \cdot v_1 - G_3 \cdot v_2 = G_4 \cdot v_s$$

$$-(G_3 + g) \cdot v_1 + (G_2 + G_3) \cdot v_2 = 0$$

$$\begin{bmatrix} G_1 + G_3 + G_4 & -G_3 \\ -G_3 - g & G_2 + G_3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} G_4 \cdot v_s \\ \cdot \end{bmatrix}$$

↑
node
voltages

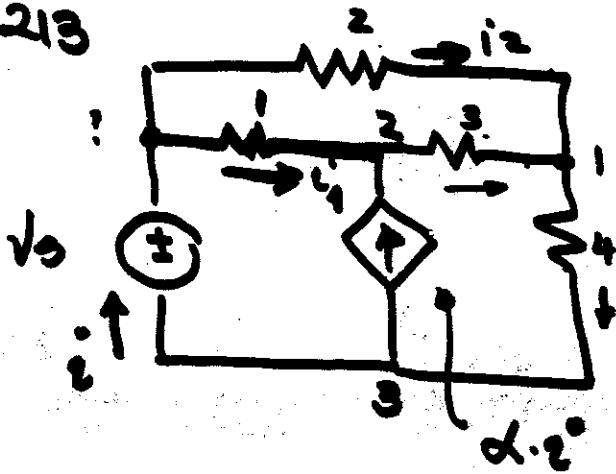
↑
currents

$g=0$: Symmetric conductances.

$g \neq 0$: Not symmetric any longer

Fig. 29:

P. 213



Nodal equations:

Why? + { 1. current controlled source $d.c.$
 2. current is the controlling variable
 - { 3. unaccompanied voltage source

Options: 1. source shift <easy>
 2. keep v_s and worry about it after the first step
 3. Add a resistor to v_s and later let $R \rightarrow 0$!

Why is option 4 not good!

① Because e^o is the controlling variable of the CCCS: After the source shift, it disappears!

② Not bad!

③ interesting and novel (at least to us) approach.

Nodal equations:

$$\textcircled{2} \quad G_1 \cdot (V_2 - V_3) - d\dot{i} + G_3 \cdot (V_2 - V_1) = 0$$

$$\textcircled{1} \quad G_2 \cdot (V_1 - V_3) + G_3 \cdot (V_1 - V_2) + G_4 \cdot V_1 = 0$$

<3 unknowns>

$$i = i_1 + i_2$$

$$\left. \begin{aligned} i_1 &= G_1 \cdot (V_3 - V_2) \\ i_2 &= G_2 \cdot (V_3 - V_1) \end{aligned} \right\} !$$

Hence:

$$\textcircled{1} \quad (G_2 + G_3 + G_4) V_1 - G_3 \cdot V_2 = G_2 \cdot V_3 \quad \leftarrow$$

$$\textcircled{2} \quad G_1(V_2 - V_3) - d \cdot \left[\overbrace{G_1(V_3 - V_2) + G_2 \cdot (V_3 - V_1)}^i \right] \leftarrow \\ + G_3 \cdot (V_2 - V_1) = 0$$

And

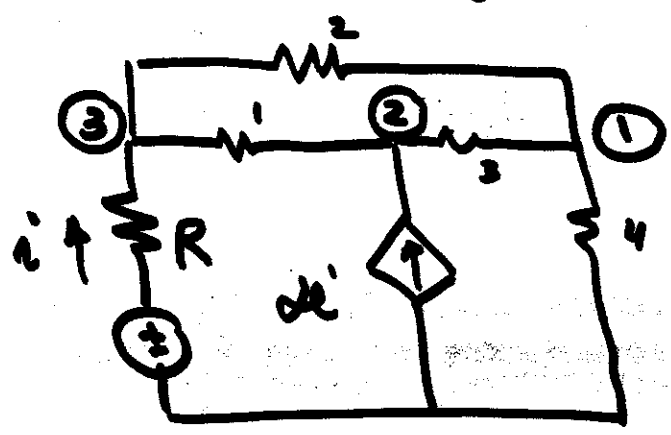
$$\textcircled{2} \quad (-G_3 - d \cdot G_2) V_1 + (G_1 + 2G_1 + G_3) V_2 \\ = G_1(1+d) V_3 + d \cdot G_2 \cdot V_3$$

Finally

$$\textcircled{1} \quad \begin{array}{cccc} \checkmark & \checkmark & \checkmark & \checkmark \\ (G_2 + G_3 + G_4) V_1 - G_3 \cdot V_2 = G_2 \cdot V_3 \\ - (2G_2 + G_3) V_1 + (G_1(1+d) + G_3) V_2 \\ = \{G_1 + 2(G_1 + G_2)\} V_3 \end{array}$$

Check: if $d=0$ is it symmetric!
Yes

What about adding R !



Node equations:

$$i = (v_3 - v_2)G$$

$$G = \frac{1}{R}$$

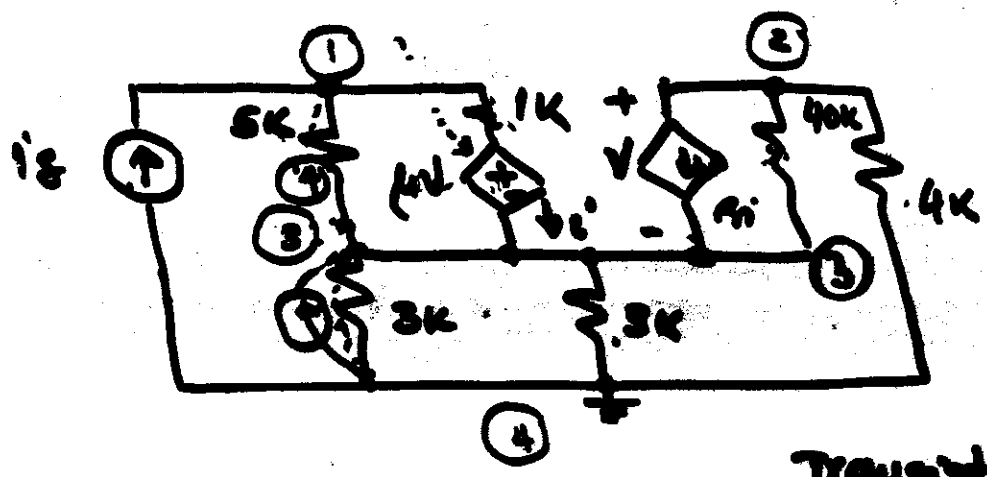
- ① $G_3 \cdot (v_1 - v_2) + G_2 \cdot (v_1 - v_3) + G_4 \cdot v_1 = 0$
- ② $G_1 \cdot (v_2 - v_3) + G_3 \cdot (v_2 - v_1) - i = 0$
- ③ $G_1 \cdot (v_3 - v_2) + G_2 \cdot (v_3 - v_1) + G \cdot (v_3 - v_3) = 0$

\uparrow
 $G = 1/R$
added!

3 eq
 3 unknown voltages

Solve them even at the end let $R \rightarrow 0$ //
 $G \rightarrow \infty$

Design problem #2 < p. 237 >

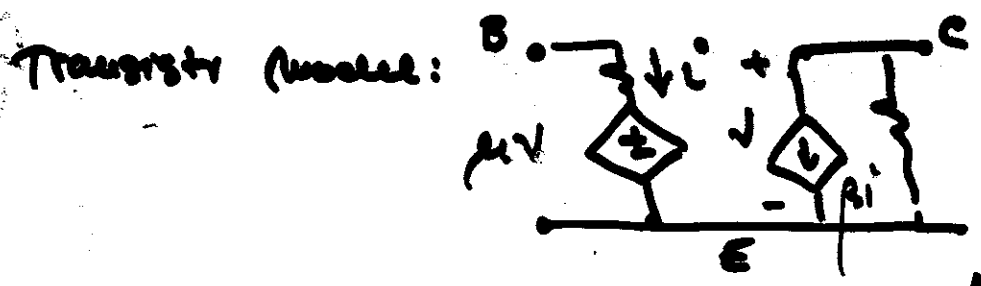


$\beta = 100$
 $\mu = 2.5 \times 10^{-3}$

Transistor amplifier

Fig. DP2

- a) Node equations
- b) mesh equations



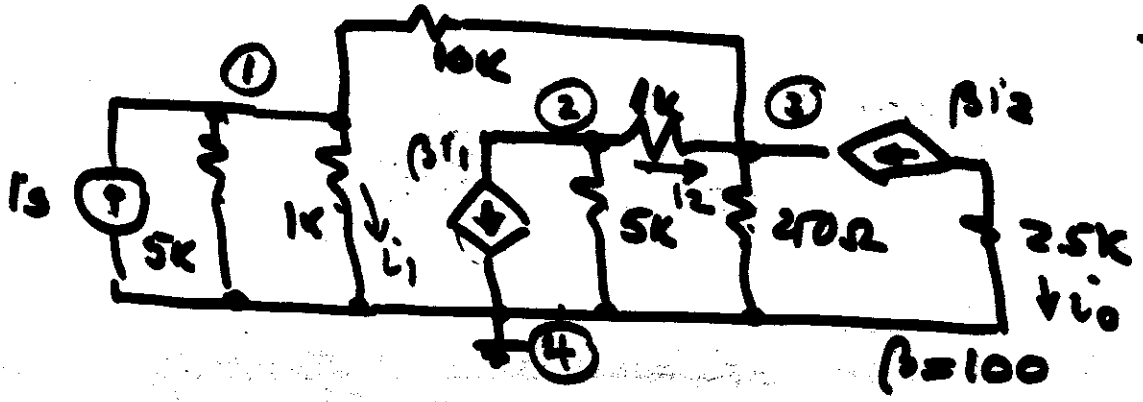
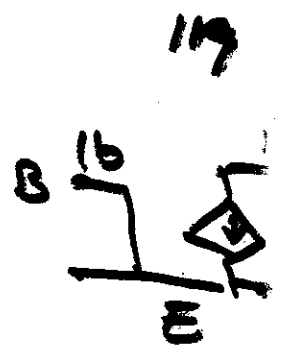
$n = 4$ $n - 1 = \underline{3}$ nodes

$b = 6$ $b - (n - 1) = \underline{3}$ mesh

independent equations

More detailed model than the model we use in the past.

Design problem #3 <p. 240>



two-transistor amplifier

$i_o/i_s = ?$

a) Nodal equation !

$n = 4$ $n - 1 = 3$ ← much easier to write!

$b = 6$ $b - (n - 1) = 3$

Signals and First-Order Circuits

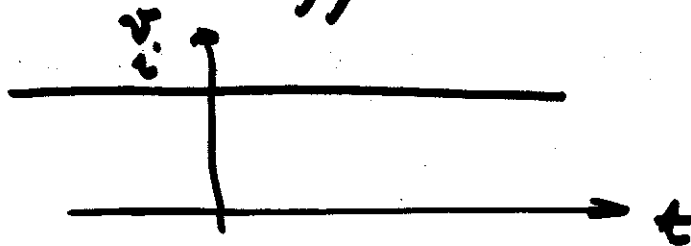
Circuits with R resistors
 C capacitors
 L inductors

First order circuits:

or RC
 RL

(but not L and C
 simultaneously!)

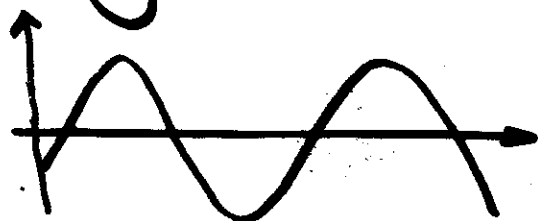
until now supplies were mostly: DC



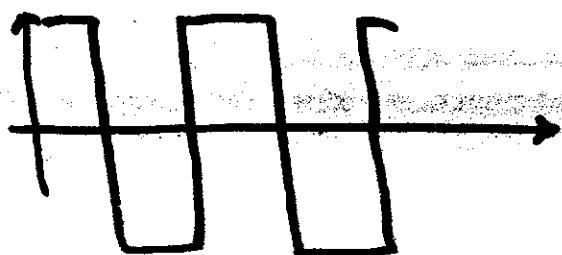
In a linear circuit with R controlled source,

resulting currents and voltages were also
DC.

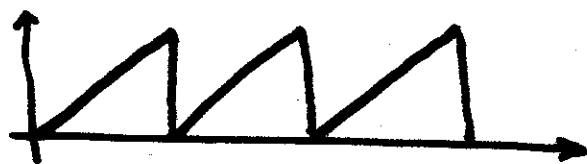
Function generators can produce:



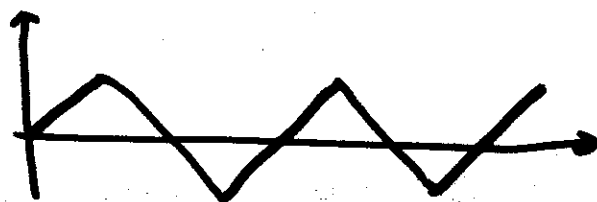
sinusoidal



square



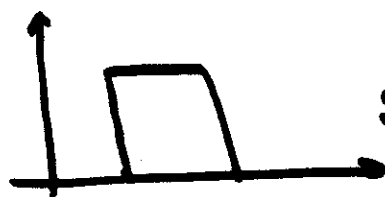
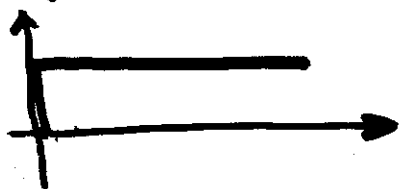
sawtooth



triangular

< All : periodic >

or
step



square-pulse



ramp



exponential

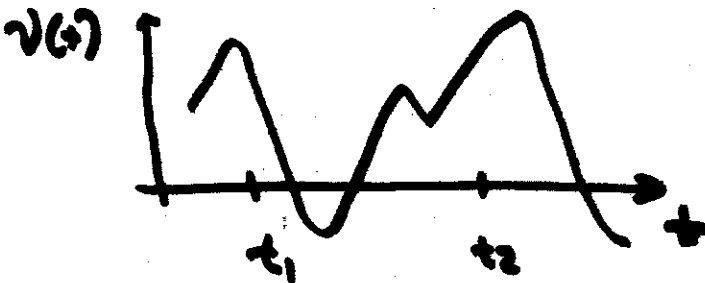
Periodic:

$$f(t+T) = f(t) \quad -\infty < t < \infty$$

T = period

$$f = \frac{1}{T} \text{ frequency}$$

Amplitude: largest value



$$\text{Average} = \frac{1}{t_2 - t_1} \cdot \int_{t_1}^{t_2} v(x) dx$$

if periodic:

$$= \frac{1}{T} \int_{t_1}^{t_1+T} v(x) dx$$

Root-mean-square value:

Resistor:

i : current
 R : resistance

periodic
 excitation

$$W = \int_{t_1}^{t_1+T} R \cdot i^2(x) dx$$

What would be a constant value of $i = I$ that would produce the same power dissipation:

$$W = R \cdot I^2 \cdot T$$

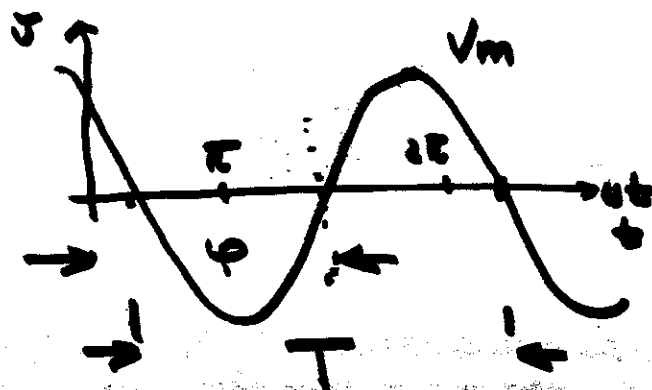
Hence:

$$R I^2 T = \int_{t_1}^{t_1+T} R \cdot i^2(x) dx$$

$$I = \sqrt{\frac{1}{T} \int_{t_1}^{t_1+T} i^2(x) dx}$$

rms value

Sinusoidal waveforms.



$$v(t) = V_m \cdot \sin(\omega t + \phi)$$

↑ amplitude
↙ phase
↑ angular frequency
↘ radian frequency

$$\omega = 2\pi f; = 2\pi \cdot \frac{1}{T}$$

$$f = \frac{1}{T}; T = \frac{1}{f}$$

$$\text{rad/sec}$$

$$f = \frac{1}{\text{sec}} / \text{Hz}$$

Average: Full-cycle : 0

$\frac{1}{2}$ cycle: $\frac{1}{T/2} \int_0^{T/2} V_m \sin \omega t \cdot dt$

$$= \frac{0.637 V_m}{2/\pi}$$

RMS:

$$V_{rms} = \sqrt{\frac{1}{T} \int_0^T V_m^2 \cdot \cos^2 \omega t \, dt}$$

↑ Does it matter if
sin or cos?

$$V_{rms} = \frac{V_m}{\sqrt{2}} ; = 0.707 V_m \leftarrow$$

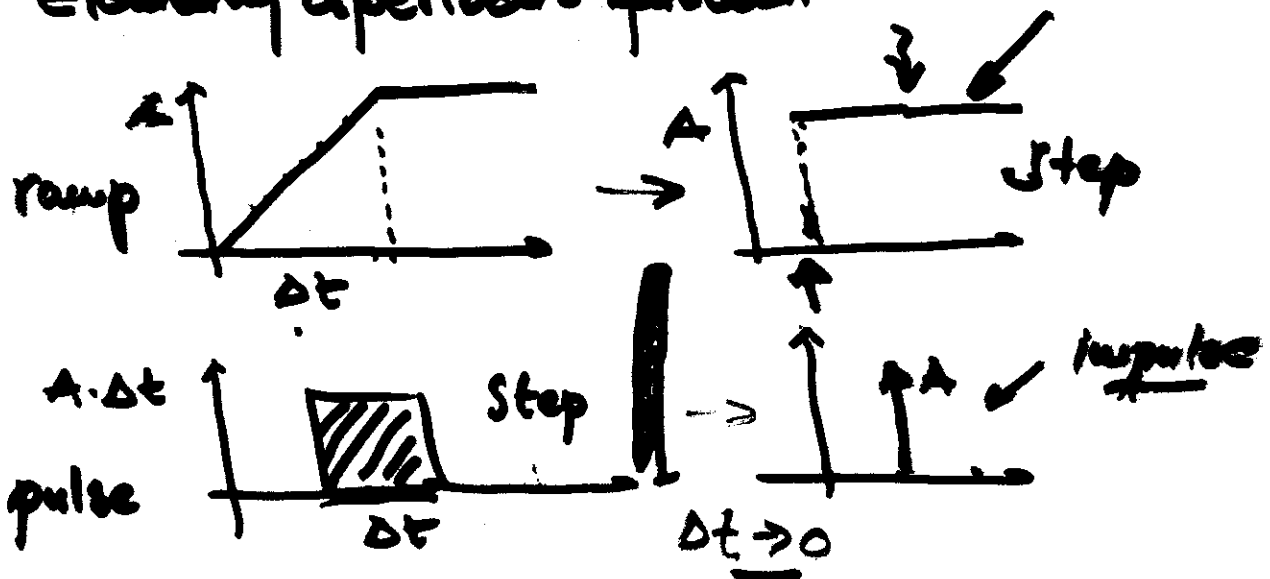
< Recall:

$$\cos^2 x = \frac{1 + \cos 2x}{2}$$

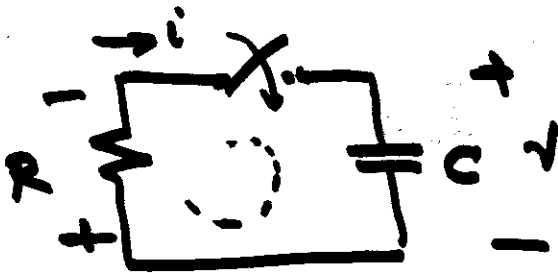
$$\cos 2x = \cos^2 x - \sin^2 x$$

$$\sin^2 x = \frac{1 - \cos 2x}{2}$$

Elementary aperiodic functions:



RC circuits :



$i = C \frac{dv}{dt}$

$$i = C \frac{dv}{dt}$$

$$C \frac{dv}{dt} + \frac{1}{R} \cdot v = 0$$

$\frac{dv}{dt}$

$$\rightarrow \frac{dv}{dt} + \frac{1}{RC} \cdot v = 0$$

DE

Linear

constant coefficient

$\frac{1}{RC}$

homogeneous

0 RHS

$$\int_{v_0}^{v(t)} \frac{dv}{v} = - \int_0^t \frac{1}{RC} dt$$

$$\ln v \Big|_{v_0}^{v(t)} = - \frac{t}{RC}$$

$$\ln v(t) - \ln v_0 = - \frac{t}{RC}$$

$$\frac{v(t)}{v_0} = e^{-t/RC}$$

$$\rightarrow v(t) = v_0 e^{-t/RC}$$

$$V(t) = V_0 e^{-t/RC}$$

↑ exponential

initial value of the capacitor voltage

Note:

$$t \rightarrow \infty \quad - \infty/RC$$

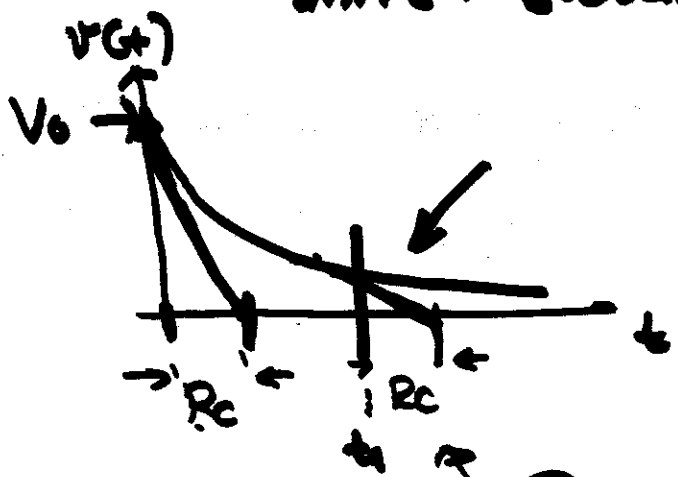
$$V(0) = V_0$$

$$V(0) = \underline{V_0}$$

RC = time constant

< dimension: time >

units: seconds



RC

Prove! t_1

Natural response

<another method for finding solution>

Suppose $v(t) = \underline{k} e^{st}$ ←

is a solution to

$$\frac{dv}{dt} + \frac{1}{RC}v = 0$$

If yes, then:

$$\rightarrow k \cdot s e^{st} + \frac{1}{RC} \cdot k e^{st} = 0$$

or

$$\rightarrow \underline{k} e^{st} \cdot \left(s + \frac{1}{RC} \right) = 0 \Rightarrow$$

Natural freq!

$$\underline{s = -\frac{1}{RC}}$$

Hence

$$\rightarrow v(t) = k e^{-t/RC}$$

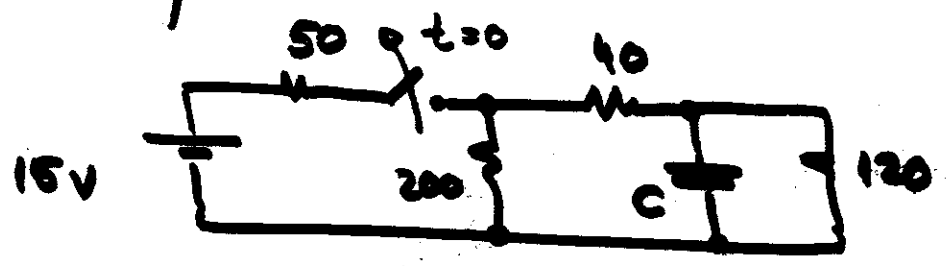
k is defined by knowing $v(t)$ at some t.

if $v(0) = V_0 \Rightarrow$

$$\underline{k = V_0} \text{ and}$$

$$v(t) = V_0 e^{-t/RC}$$

Example:



Switch opens at $t=0$

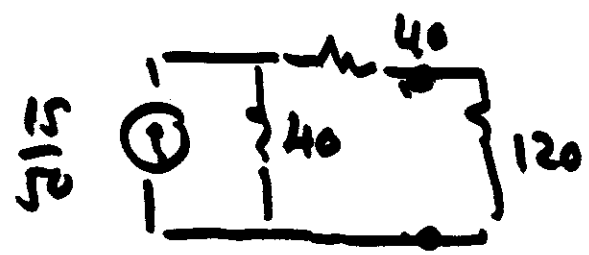
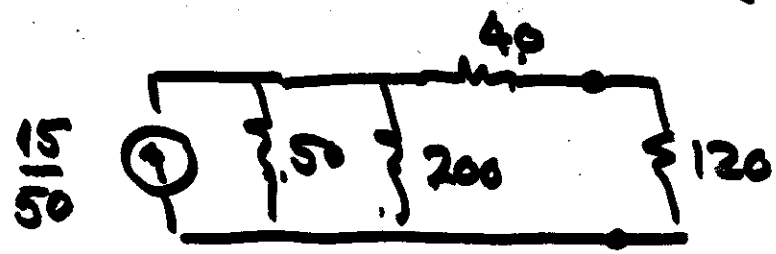
< It was closed for a very long time >

If closed for a long time:

$$\frac{dV}{dt} = 0 \Rightarrow i_C = 0$$

No current flows through C

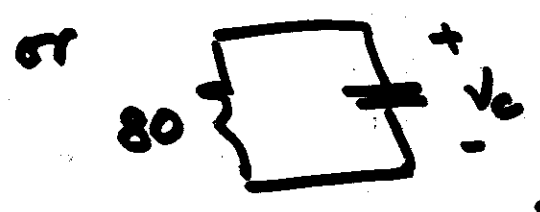
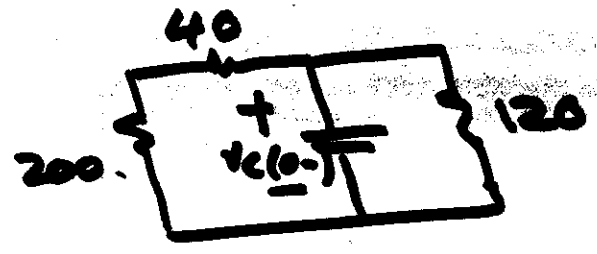
< DC battery! >



$V_C(0_-) = 7.5$
 just before
 switch opens

Hence, initial voltage across C is: 7.5V

At $t=0$, switch opens:



$-t/RC$

$C = 12.5 \mu F$

$V_c(t) = V_c(0) e^{-t/RC}$

$RC = 80 \times 12.5 \times 10^{-6}$

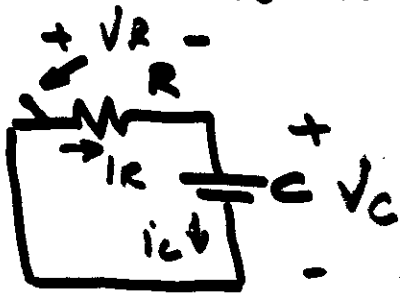
$RC = 1 \text{ msec}$

$\rightarrow V_c(t) = 7.5 e^{-1000t}$

$V_c(0) = V_c(0+)$ after switch opens
 $= V_c(0-) \downarrow$ before.

$\rightarrow V_c(0+) = V_c(0-)$ Capacitor voltage has No jump

RC circuit without input (again)



$$i_R - i_C = 0$$

$$V_R = Ri$$

$$V_C = \frac{1}{C} \int i_C(x) dx$$

Hence:

$$\frac{V_R}{R} - C \cdot \frac{dV_C}{dt} = 0$$

$$i_C = C \cdot \frac{dV_C}{dt}$$

KVL: $V_R + V_C = 0 \Rightarrow V_R = -V_C$

$$\textcircled{1} \quad -\frac{V_C}{R} - C \cdot \frac{dV_C}{dt} = 0 \Rightarrow \frac{dV_C}{dt} + \frac{1}{RC} V_C = 0$$

$$\textcircled{2} \quad \frac{V_R}{R} - C \cdot \frac{d}{dt}(-V_R) = 0 \Rightarrow \frac{dV_R}{dt} + \frac{1}{RC} V_R = 0$$

$$\textcircled{3} \quad V_R + V_C = 0$$

All DE: 1st order

$$R \cdot i_R + \frac{1}{C} \int i_C(x) dx = 0 ;$$

$$i_R = i_C$$

$$R \cdot i_C + \frac{1}{C} \int i_C(x) dx = 0 \Rightarrow \frac{di_C}{dt} + \frac{1}{RC} i_C = 0$$

What is different, if all these equations have the same form of the solution.

$$y = A e^{-t/RC}$$

! depends on which

variable: v_C

v_R

i_C

i_R !

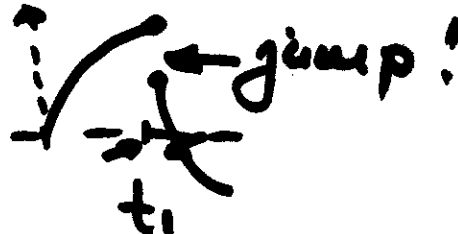
What do we know about their values at some instance

t_1 :

< Because then:

$$y(t_1) = A \cdot e^{-\frac{t_1}{RC}}$$

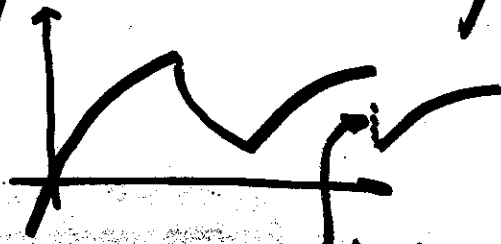
and $A = y(t_1) e^{t_1/RC}$

Slope of i_C ? i_R ?  ← jump!

Since $\underline{v_R} = R \cdot \underline{i_R}$: v_R also can be discontinuous function

One voltage that has to be a continuous function of time is:

Voltage across the capacitor!



Not possible!
Otherwise

$$i_c = C \cdot \frac{dv_c}{dt}$$

$$i_c = \infty$$

in a circuit (model)
that faithfully
represents a physical
circuit in a lab!

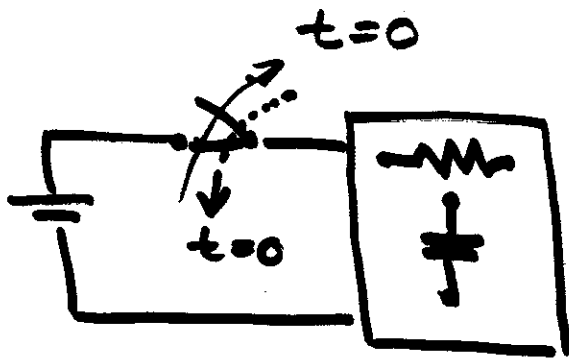
Two consequences:

1. Write your DE in terms of v_c !

2. Use one known value of v_c to find the constant τ :

$$v_c(t) = v_c e^{-t/\tau}$$

Usually <but not always>: $v_c(0)$ is known.



Two cases: ① S closes at $t=0$

$$v_C(0_-) = 0$$

↑ (just before closing)

What is

$$v_C(0_+) = 0$$

↑ (just after closing)

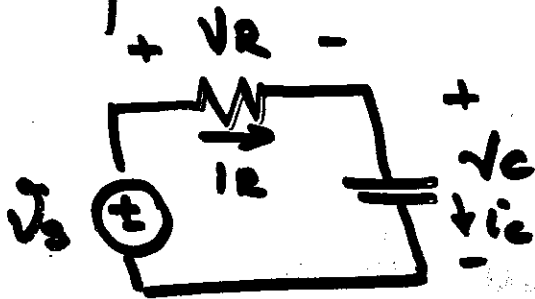
② S opens at $t=0$

$$v_C(0_-) = \bar{V}_C$$

As a consequence

$$v_C(0_+) = \bar{V}_C$$

Resistance - Capacitance circuits with input



$$v_s - v_R - v_C = 0$$

$$v_R = R \cdot i_R$$

$$i_C = C \frac{dv_C}{dt}$$

$$i_C = i_R$$

$$v_R + v_C = v_s$$

$$R \cdot i_R + v_C = v_s$$

$$R \cdot i_C + v_C = v_s$$

$$R \cdot C \cdot \frac{dv_C}{dt} + v_C = v_s \leftarrow \text{Non homogeneous!}$$

$$R \cdot v_s(t)$$

function of time

$$RC \frac{dv_c}{dt} + v_c = 0$$

homogeneous
(As $v_s(t) \equiv 0$)

DE: 1st order
linear
constant coefficients

$$v_c(t) = v_h(t) + v_p(t)$$

\leftarrow particular solution that depends on $v_s(t)$
 \uparrow solution to the homogeneous DE

Proof: $RC \frac{d}{dt} (v_h + v_p) + (v_h + v_p) = v_s(t)$

$$\underbrace{\left(RC \frac{dv_h}{dt} + v_h \right)}_{\text{homog}} + \underbrace{\left(RC \frac{dv_p}{dt} + v_p - v_s(t) \right)}_{\text{non-homog}} = 0$$

$= 0$ $= 0$

We already know that solutions to:

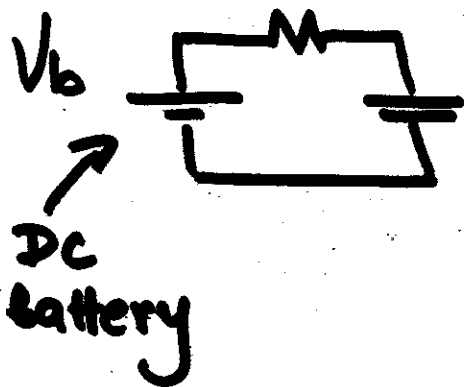
$$RC \frac{dV_c}{dt} + V_c = 0$$

$$\text{is } V_c(t) = K e^{-\frac{t}{RC}}$$

What is $V_p(t) = ?$

The form of $V_p(t)$ depends on $V_s(t)$

Assume: $V_s(t) = V_b$



$V_p(t) = ?$

Could it be a constant?

If yes:

$$RC \frac{dV_p}{dt} + V_p - V_b = 0$$

$$\Rightarrow V_p = V_b !$$

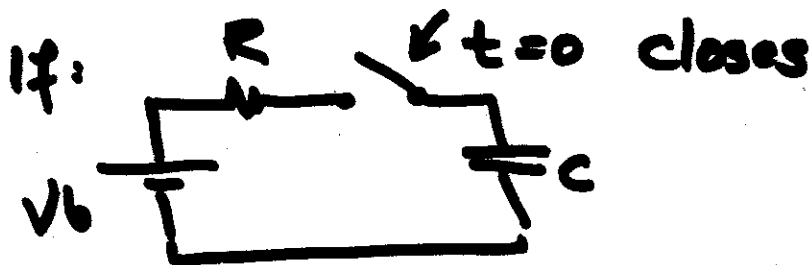
Hence

$$V_c(t) = V_b + K e^{-t/RC}$$

How about constant K ?

We need to know at least one solution to v_c (at some time t_1)

Usually: $t_1 = 0$ ← initial condition



then $v_c(t) = V_b + K e^{-t/RC}$

$v_c(0^-) = 0$ (no charge on the capacitor)

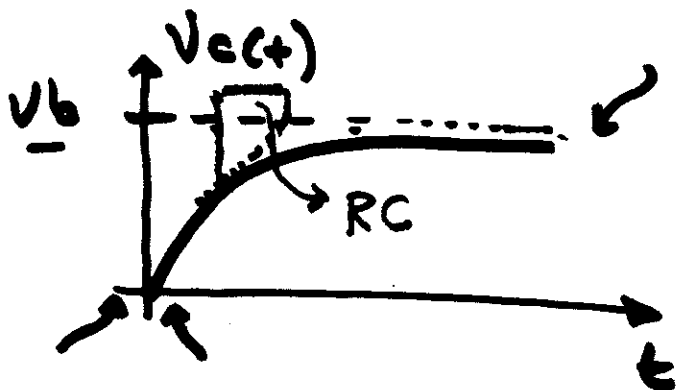
$v_c(0^+) = 0$

From $v_c(t) = V_b + K e^{-t/RC}$

$v_c(0^+) = V_b + K$

$V_b + K = 0 \Rightarrow K = -V_b$ ←

And, finally $v_c(t) = V_b (1 - e^{-t/RC})$

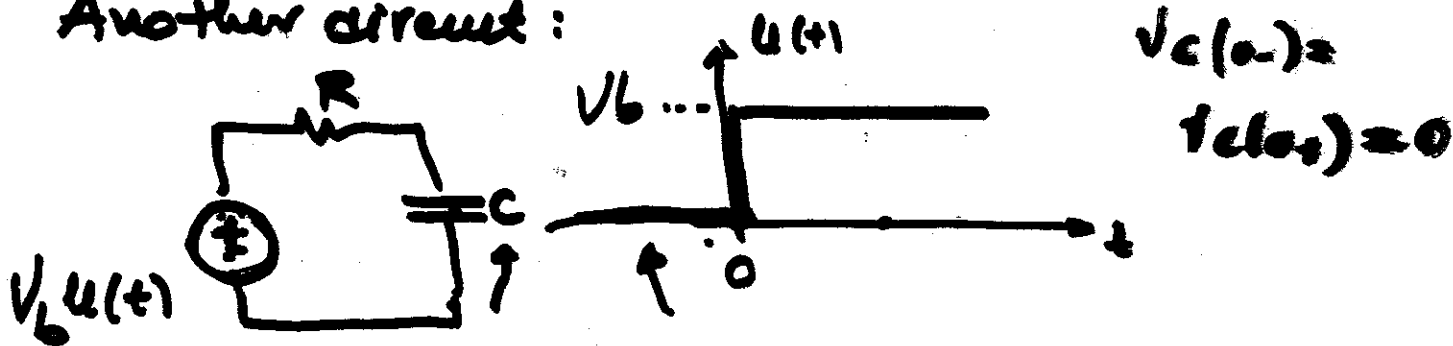


exponential function of time:

RC : time constant

$s = +1/RC$: natural frequency

Another circuit:



For $t > 0$: same circuit as before

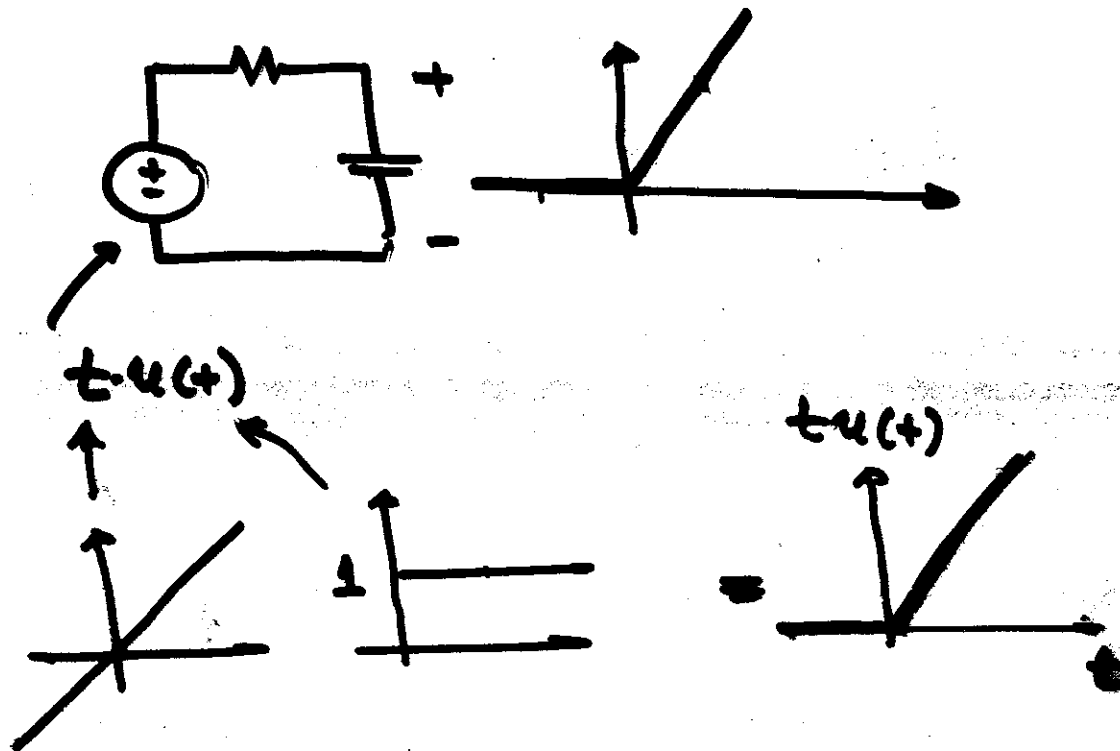
$t < 0$: Not: in this circuit
 $u(t) = 0$



C cannot be charged

In the previous circuit, S was open
and C could have maintained the charge!

What about the ramp function:



$$v_c(t) = K e^{-t/RC} + v_p(t)$$

$$v_p(t) = ?$$

$$RC \frac{dv_c}{dt} + v_c(t) = v_s(t)$$

$$RC \frac{dv_c}{dt} + v_c(t) = t \cdot u(t)$$

Can it be:

$$v_p(t) = (A + Bt) \cdot u(t) \quad ?$$

Substitute predicted solution (only a candidate) into DE:

$$RC \cdot B + (A + Bt) = t \quad t > 0$$

$$B = 1/R \\ RC \cdot B + A = 0 \\ \Rightarrow A = -RC$$

Hence

$$V_p(t) = (-RC + t) \cdot u(t) \quad t > 0$$

0+
0-

$$V_c(t) = \underbrace{K e^{-t/RC}}_{V_h(t)} + \underbrace{(-RC + t)}_{V_p(t)} u(t)$$

at $t = 0^-$: $V_c(0^-) = 0$

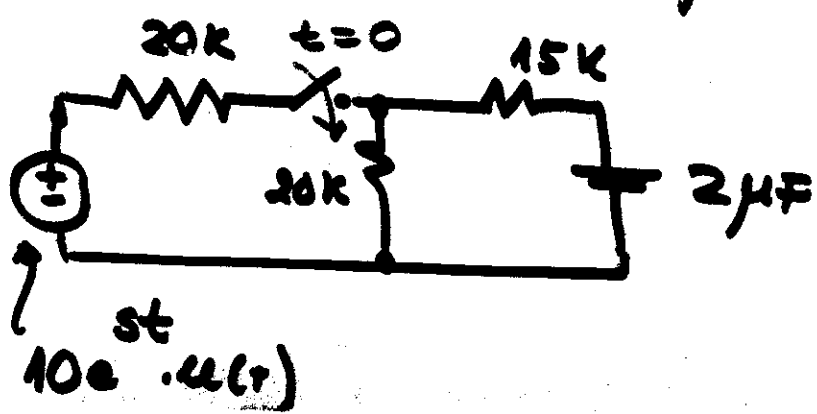
Hence: $V_c(0^+) = 0$ or: $K - RC = 0$
 $K = RC$

Ans

$$V_c(t) = (t - RC) u(t) + RC e^{-t/RC} u(t)$$

to explain that for $t < 0$ $V_c(t) = 0$

RC circuit with an exponential input.



$$u(t) = 0 \quad t < 0$$

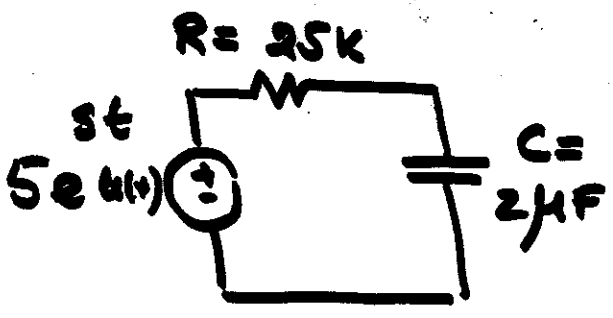
$$= 1 \quad t > 0$$

undefined at $t = 0$

$$u(0^-) = 0$$

$$u(0^+) = 1$$

S = switch : S open for a long time : $V_c(t) = 0$
 S closes at $t = 0$



$$V_s(t) = R \cdot i + V_c$$

$$i = C \cdot \frac{dV_c}{dt}$$

$$RC \cdot \frac{dV_c}{dt} + V_c = V_s(t)$$

$$\frac{dV_c}{dt} + \frac{1}{RC} \cdot V_c = \frac{1}{RC} \cdot V_s(t)$$

DE:

$$\frac{dv_c}{dt} + 20v_c = 100 e^{st}$$

↑
error in the text

$$R = 25k$$

$$C = 2\mu F$$

$$RC = 50 \cdot 10^{-3} \cdot 10^{-6} \text{ sec}$$

$$RC = 50 \text{ msec}$$

$$\frac{1}{RC} = \frac{1}{50 \cdot 10^{-3}}$$

$$\frac{1}{RC} = 20$$

What is $v_c(t)$?

RHS: exponential function

Linear DE with constant coefficients:

$$v_c(t) = v_{c \text{ homogenous}} + v_{c \text{ particular}}$$

$$\uparrow \frac{dv_c}{dt} + 20v_c = 0 \Rightarrow$$

$$v_{c_h}(t) = K e^{-20t}$$

Conjecture: $v_{c \text{ particular}} = A \cdot e^{st}$

Does it satisfy DE?

$$A \cdot s \cdot e^{st} + 20 \cdot A \cdot e^{st} = 100 \cdot e^{st} \quad A(s+20) = 100$$

(S)

104

$$A(s+20) = 100$$

Only if $s \neq -20$

$$A = \frac{100}{s+20}$$

$\langle 20 \rangle$
 $\frac{1}{s+20}$

from the source!

let $s = -10$

$$V_c(t) = \{ K e^{-20t} + 10 e^{-10t} \} u(t)$$

How to find K:

$$V_c(0^-) = 0$$

$$V_c(0^+) = K + 10 \Rightarrow V_c(0^+) = 0$$

$$K = -10$$

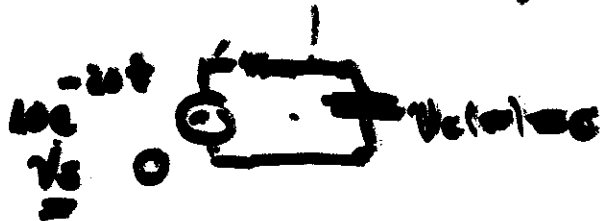
$$V_c(t) = 10 (e^{-10t} - e^{-20t}) u(t)$$

$t=0$
 $V_c(0) = 0$
 $V_c(0^-) = 0$

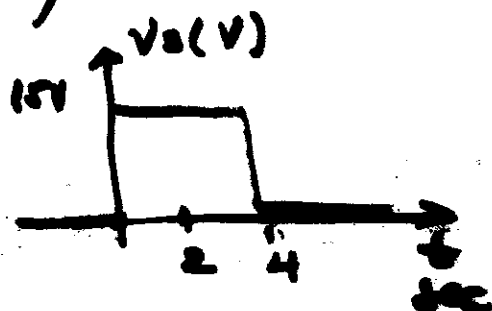
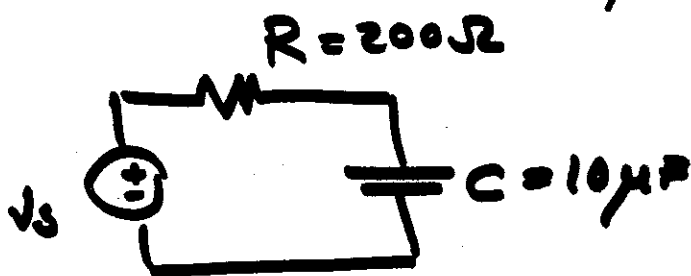
$t=0$
 $V_c(0^+) = 0$

Exercice (p. 266)
10

$$V_s(t) = A \cos(\omega t + \theta)$$



RC circuit with a pulse input



$$RC = 2 \text{ sec}$$

$$Ri + Vc = v_s$$

$$RC \frac{dVc}{dt} + Vc = v_s \quad \leftarrow$$

$$\rightarrow 2 \cdot \frac{dVc}{dt} + Vc = v_s$$

$$0 < t \leq 4 : \quad 2 \frac{dVc}{dt} + Vc = 15 \quad (1)$$

$$t \geq 4 \quad 2 \frac{dVc}{dt} + Vc = 0 \quad (2)$$

$$(1) \quad Vc(t) = K \cdot e^{-t/2} + A$$

$$Vc(t) = K e^{-t/2} + 15$$

$$Vc(0^-) = 0$$

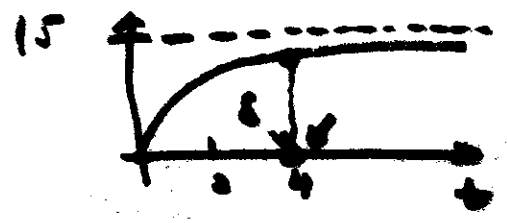
$$Vc(0^+) = K + 15 \Rightarrow K = -15$$

↑ because $v_s = 15$

$$2 \cdot \frac{dA}{dt} + A = 15$$

$$0 \quad A = 15$$

$$V_C(t) = 15(1 - e^{-t/2}) \quad 0 < t < 4$$



② At $t = 4 \mu\text{s}$.

$$V_C(4_-) = 15 \cdot (1 - e^{-2}) \approx 13 \text{ V}$$

Then at $t = 4_+$

$$2 \frac{dV_C}{dt} + V_C = 0$$

A) $V_C(t) = K e^{-t/2}$ But now $t' = t - 4$ shifted

$$V_C(t') = K e^{-t'/2} \quad t' = 0$$

$$V_C(0_-) = 13, \quad V_C(0_+) = 13 e^{-0/2}$$

$$V_C(t') = 13 e^{-t'/2} \quad t' = t - 4$$

$$V_C(t) = 13 e^{-\frac{t-4}{2}} \quad t \geq 4 \mu\text{s}$$

B: $2 \frac{dv_c}{dt} + v_c = 0 \quad t \geq 4$

$v_c = K e^{-t/2}$

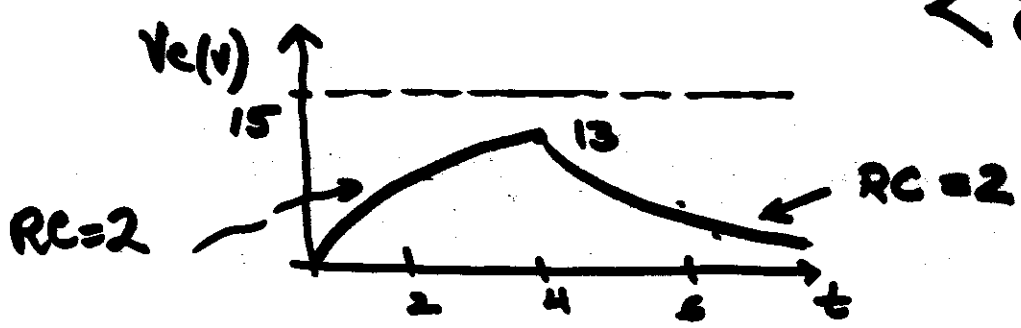
$v_c(4^-) = 13 \text{ V}$

$v_c(4^+) = K e^{-2} \Rightarrow K = 13e^2 \checkmark$

$v_c(t) = 13 \cdot e^2 \cdot e^{-t/2}$

$v_c(t) = 13 e^{-\frac{t-4}{2}} \quad t \geq 4$

< Same answer! >



How about LC: $LC = C \frac{dv_c}{dt}$

$0 < t \leq 4 \quad v_c(t) = 15(1 - e^{-t/2})$

$t \geq 4 \quad v_c(t) = 13 e^{-\frac{t-4}{2}}$

$v_c \rightarrow \uparrow ?$ is this correct?

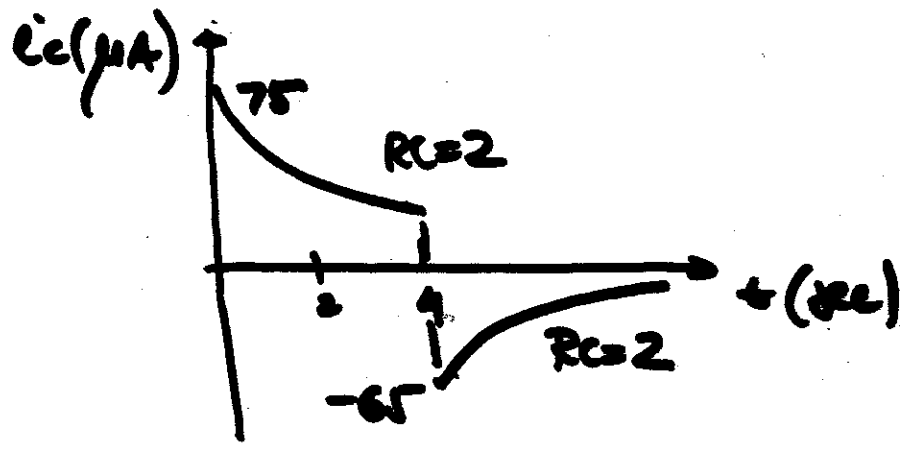
$C = 10 \mu F$

$$i_c = 10 \cdot 15 \cdot \frac{1}{2} e^{-t/2} \mu A \quad 0 \leq t < 4$$

$$i_c = 75 e^{-t/2} \quad 0 \leq t < 4$$

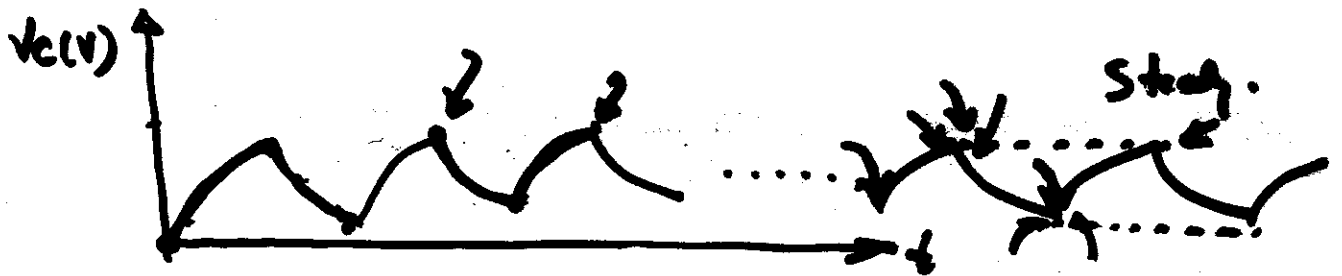
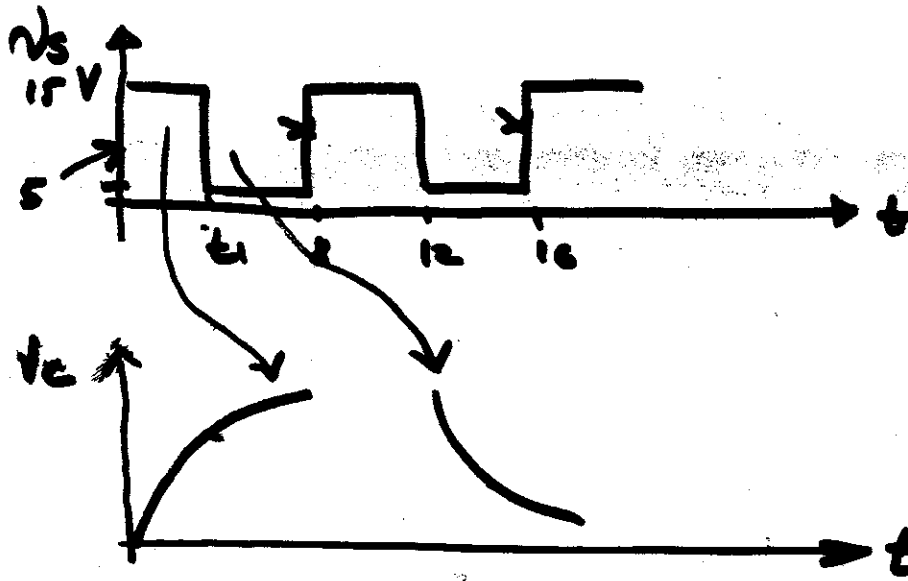
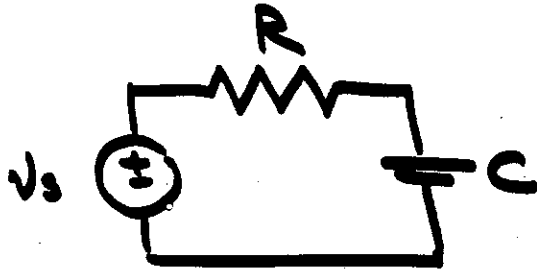
For $t > 4$: $i_c = 10 \cdot 13 \cdot \left(-\frac{1}{2}\right) e^{-\frac{t-4}{2}}$

$$i_c = -65 e^{-\frac{t-4}{2}}$$



$i_R = i_c$
 $V_R = R \cdot i_R$
} all have the same shape

How about RC with a periodic wave?



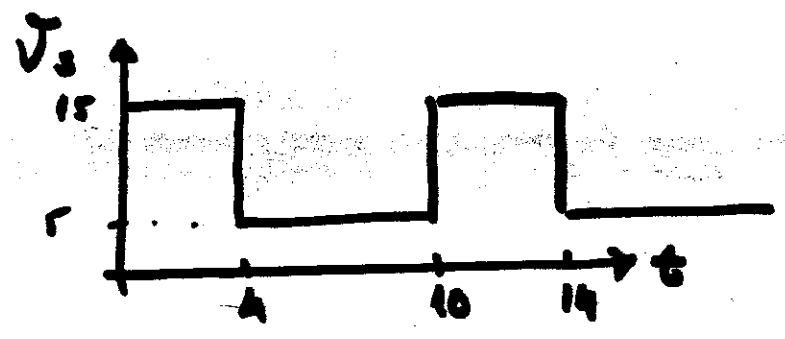
How can we calculate the "steady-state" response?

< periodic in most systems >

Aperiodic steady-state: chaotic systems

$0 \leq t \leq 4 \quad RC \cdot \frac{dv_c}{dt} + v_c = 15$

$4 \leq t \leq 10 \quad RC \cdot \frac{dv_c}{dt} + v_c = 5$



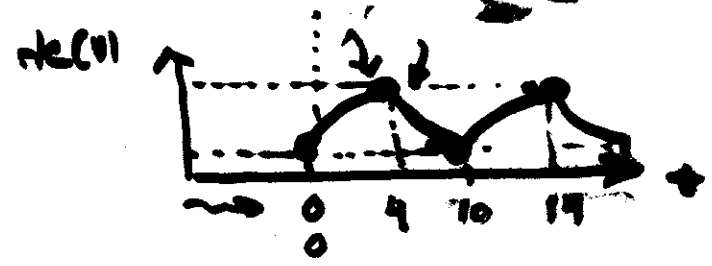
Solutions:

$0 \leq t \leq 4: v_c(t) = 15 + k_1 e^{-t/RC}$

$4 \leq t \leq 10 \quad v_c(t) = 5 + k_2 e^{-t/RC}$

at 4_- : $15 + k_1 e^{-4/RC} = 5 + k_2 e^{-4/RC}$ at 4_+

at 10_- : $5 + k_2 e^{-10/RC} = 15 + k_2 e^{-10/RC}$ at 10_+

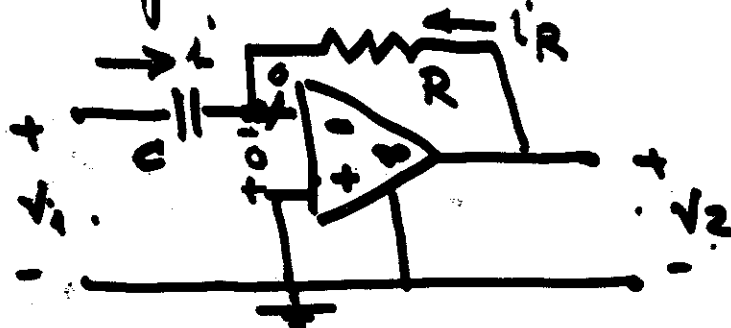


RC circuits with op-amps

→ Source integrator R Load

interference
and affects
the integrator

To separate Load :



$$i = C \cdot \frac{dv_1}{dt} \leftarrow$$

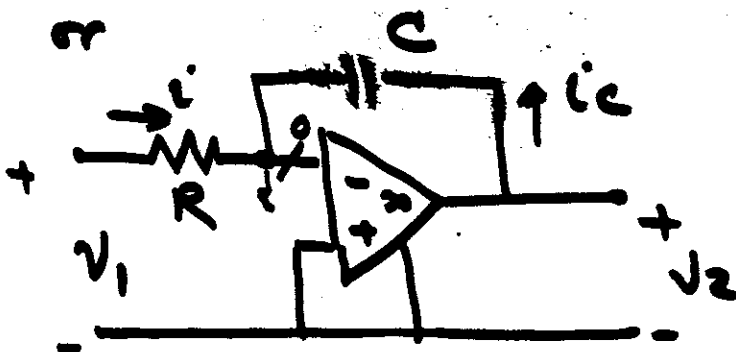
$$v_2 = R \cdot i_R \leftarrow$$

$$i + i_R = 0$$

$$C \frac{dv_1}{dt} + \frac{v_2}{R} = 0$$

$$\rightarrow v_2 = -RC \frac{dv_1}{dt}$$

Diffrent.



$$v_1 = R \cdot i$$

$$i + i_c = 0$$

$$i_c = C \cdot \frac{dv_2}{dt}$$

$$\frac{v_1}{R} + C \frac{dv_2}{dt} = 0$$

$$\frac{dv_2}{dt} = -\frac{1}{RC} \cdot v_1$$

integrator

Saturation:

$$V_{out} = V_{sat}$$

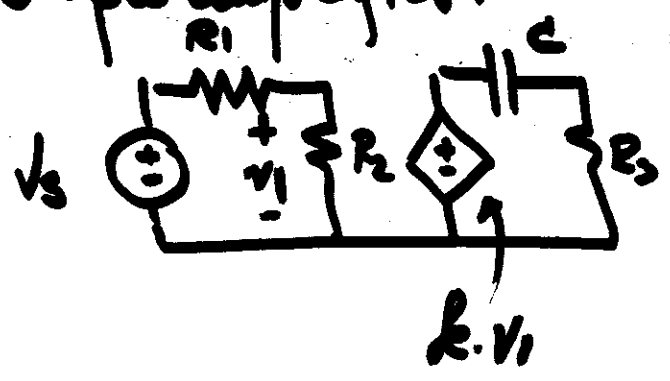
or $V_2 = V_{sat}$

Differentiate: $|R_C \cdot \frac{dV_1}{dt}| \leq V_{sat}$

Integrate: $|\frac{1}{R_C} \int V_1(x) dx| \leq V_{sat}$

Circuits with controlled sources:

Simple amplifier:



$$V_1 = \frac{R_2}{R_1 + R_2} \cdot v_s$$

$$k \cdot V_1 - V_C - R_3 \cdot i = 0 \leftarrow$$

$$i = C \cdot \frac{dV_C}{dt} \leftarrow$$

$$V_C + R_3 C \cdot \frac{dV_C}{dt} = k \cdot \frac{R_2}{R_1 + R_2} \cdot v_s$$

DE

RL circuits

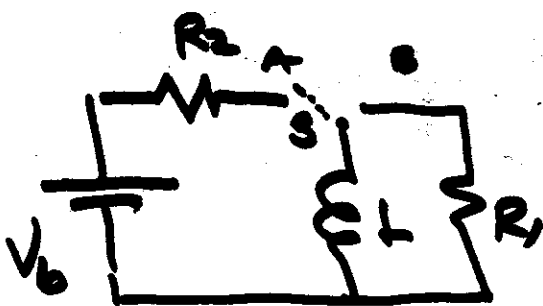
Duality: i_L vs. v_C

↑
continuous
function of
time

→

1st order DE, linear, with constant coeff.

$i_L(0^-) = i_L(0^+)$ ← condition used to find unknown constant when solving DE



S: A for a long time

$$v_L = 0$$

$$i_L = \frac{V_b}{R_2}$$

L: looks like a short circuit!

S: At $t=0$ switch moves to position B



$$V_L = L \frac{di_L}{dt}$$

$$V_R = R_1 \cdot i_R$$

$$i_R + i_L = 0 \quad ; \quad V_L = V_R$$

$$\text{Let } i_L = i \quad ; \quad i_R = -i$$

$$L \cdot \frac{di}{dt} = R \cdot (-i) \quad \text{or:}$$

$$\rightarrow L \frac{di}{dt} + Ri = 0 \quad \text{1st order DE}$$

$$\frac{di}{i} = -\frac{R}{L} dt$$

$$\int \frac{di}{i} = -\frac{R}{L} \int dt$$

$$\ln i = -\frac{R}{L} t + \ln k$$

$$i = k e^{-\frac{R}{L} t} \quad \leftarrow$$

$$i(0+) = k$$

$$i(0-) = \frac{V_b}{R}$$

Time constant: $\frac{L}{R}$

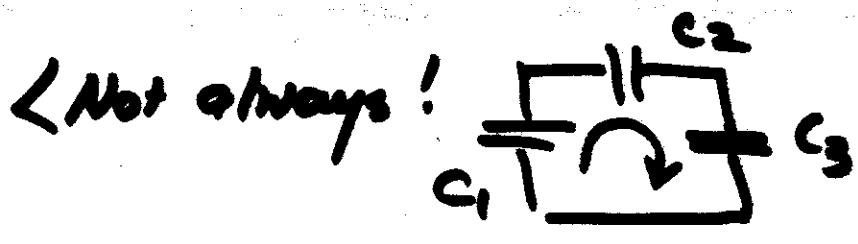
$$\text{Hence: } i = \frac{V_b}{R} e^{-\frac{R}{L} t} \quad \leftarrow$$

7.

Second order circuits

Number of C's and L's will define the order of the DE

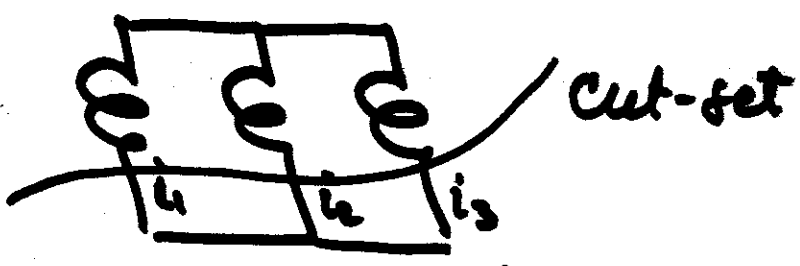
Usually: #C's + #L's = #DE



$$V_{C1} + V_{C2} + V_{C3} = 0$$

Algebraic equation

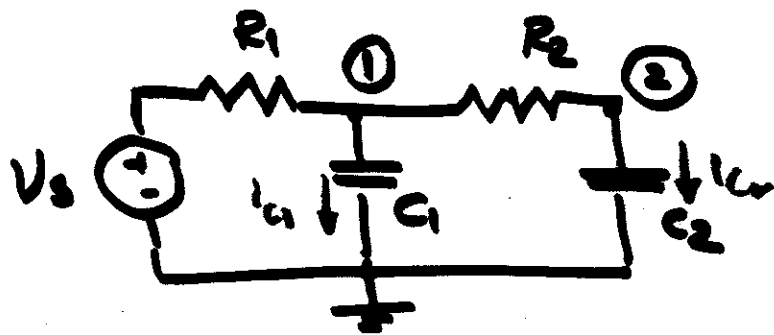
or:



$$i_{L1} + i_{L2} + i_{L3} = 0$$

A circuit with C_1 and C_2 :

2nd order DE: Linear with constant coefficients.



Nodal equations:

$$(V_1 - V_s) \cdot \frac{1}{R_1} + i_{C1} + \frac{V_1 - V_2}{R_2} = 0$$

$$\frac{V_2 - V_1}{R_2} + i_{C2} = 0$$

$$i_{C1} = C_1 \cdot \frac{dV_1}{dt} \quad ; \quad i_{C2} = C_2 \cdot \frac{dV_2}{dt}$$

$$V_1 \cdot \frac{1}{R_1} + C_1 \cdot \frac{dV_1}{dt} + \frac{V_1}{R_2} - \frac{1}{R_2} \cdot V_2 = \frac{V_s}{R_1}$$

$$\frac{V_2}{R_2} - \frac{1}{R_2} \cdot V_1 + C_2 \cdot \frac{dV_2}{dt} = 0$$

$$V_1 \cdot \left(\frac{1}{R_1} + \frac{1}{R_2} \right) + C_1 \cdot \frac{dV_1}{dt} - \frac{1}{R_2} \cdot V_2 = \frac{V_s}{R_1}$$

$$-\frac{1}{R_2} \cdot V_1 + \frac{1}{R_2} \cdot V_2 + C_2 \cdot \frac{dV_2}{dt} = 0$$

$$C_1 \cdot \frac{dv_1}{dt} + \left(\frac{1}{R_1} + \frac{1}{R_2}\right)v_1 - \frac{1}{R_2}v_2 = \frac{1}{R_1}v_s$$

$$-\frac{1}{R_2}v_1 + C_2 \cdot \frac{dv_2}{dt} + \frac{1}{R_2}v_2 = 0$$

Nodal equation.

Re-arranged:

$$\left. \begin{aligned} C_1 \cdot \frac{dv_1}{dt} + \left(\frac{1}{R_1} + \frac{1}{R_2}\right)v_1 - \frac{1}{R_2}v_2 &= \frac{1}{R_1}v_s \\ C_2 \cdot \frac{dv_2}{dt} - \frac{1}{R_2}v_1 + \frac{1}{R_2}v_2 &= 0 \end{aligned} \right\}$$

Matrix:

$$\begin{pmatrix} C_1 & 0 \\ 0 & C_2 \end{pmatrix} \frac{d}{dt} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} + \begin{pmatrix} \frac{1}{R_1} + \frac{1}{R_2} & -\frac{1}{R_2} \\ -\frac{1}{R_2} & \frac{1}{R_2} \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} \frac{1}{R_1} \\ 0 \end{pmatrix} \cdot v_s$$

State-equation.

2 equations: for 2 capacitors

v_1, v_2 : capacitor's voltages

Solutions:

$$2 \text{ DE } \rightarrow 1 \text{ DE}$$

1st order 2nd order

by substitution!

Nodal equations:

From 2nd equati-: $V_1 = V_2 + R_2 C_2 \cdot \frac{dV_2}{dt}$

Substitute it into 1st:

$$C_1 \left\{ \frac{dV_2}{dt} + R_2 C_2 \frac{d^2 V_2}{dt^2} \right\} + \left(\frac{1}{R_1} + \frac{1}{R_2} \right) \cdot \left(V_2 + R_2 C_2 \frac{dV_2}{dt} \right) - \frac{1}{R_1} V_s = \frac{1}{R_1} V_s$$

Or:

$$\left. \begin{aligned} \frac{d^2 V_2}{dt^2} + \left(\frac{G_1 + G_2}{C_1} + \frac{G_2}{C_2} \right) \frac{dV_2}{dt} + \frac{G_1 G_2}{C_1 C_2} V_2 \\ = \frac{G_1 G_2}{C_1 C_2} \cdot V_s \end{aligned} \right\}$$

$$(G_i = 1/R_i, i=1,2)$$

How about V_1 ? Find the DE.

How to solve it:

$$V_2 = V_{2 \text{ homogeneous}} + V_{2 \text{ particular}}$$

Homogeneous:

$$V_{2h} = K e^{st} \quad \begin{array}{l} \text{Natural response} \\ \leftarrow \text{Conjecture!} \end{array}$$

Substitute it into the DE:

$$s^2 + \left(\frac{G_1 + G_2}{C_1} + \frac{G_2}{C_2} \right) s + \frac{G_1 G_2}{C_1 C_2} = 0$$

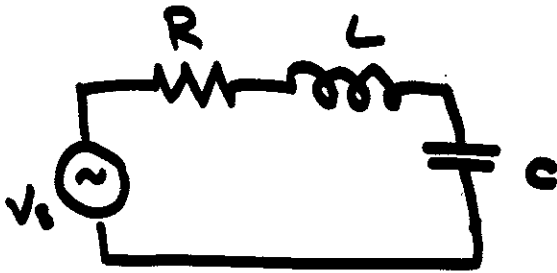
$s_{1/2}$ Two natural frequencies
 Two time constants

Characteristic equation

Solutions: two real, distinct,
negative numbers!

$$V_{2h} = K_1 e^{s_1 t} + K_2 e^{s_2 t}$$

RLC Circuits



$$v_s = Ri + L \frac{di}{dt} + v_C$$

$$i = C \frac{dv_C}{dt}$$

$$v_s = Ri + LC \frac{d^2 v_C}{dt^2} + v_C$$

$$RC \frac{dv_C}{dt} + LC \frac{d^2 v_C}{dt^2} + v_C = v_s$$

$$LC \frac{d^2 v_C}{dt^2} + RC \frac{dv_C}{dt} + v_C = v_s$$

2nd order DE: Linear
constant coefficients

$$v_C = v_{C, \text{homogenous}} + v_{C, \text{particular}}$$

Homogeneous solution:

$$LC \frac{d^2 V_c}{dt^2} + RC \frac{dV_c}{dt} + V_c = 0$$

Homogeneous:
RHS = 0

Assume $V_c(t) = K \cdot e^{st}$

Then: $\frac{dV_c}{dt} = Ks e^{st}$

$$\frac{d^2 V_c}{dt^2} = Ks^2 e^{st}$$

Substitute into DE:

$$LC \cdot Ks^2 e^{st} + RC \cdot Ks e^{st} + K e^{st} = 0$$

$$(LCs^2 + RCs + 1) \cdot K e^{st} = 0$$

$\neq 0$

$$LCs^2 + RCs + 1 = 0$$

Characteristic equation.

$$s_{1/2} = -\frac{R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}$$

2 solutions!

Characteristic equation is quadratic:

$$S_{1/2} = -\frac{R}{2L} \pm \sqrt{\frac{R^2}{4L^2} - \frac{1}{LC}}$$

\uparrow Always < 0
 \swarrow
 > 0
 < 0

Case 1: $\frac{R^2}{4L^2} - \frac{1}{LC} > 0 \Rightarrow R^2 > \frac{4L}{C}$
 $R > 2\sqrt{\frac{L}{C}}$

$S_1 =$ Real and both Negative
 $S_2 =$

Case 2: $\frac{R^2}{4L^2} = \frac{1}{LC} \Rightarrow R = 2\sqrt{\frac{L}{C}}$

$S_1 = S_2$ (identical)
 Both real and Negative.

$S_1 = S_2; S_1 = -R/2L$

Case 3: $\frac{R^2}{4L^2} - \frac{1}{LC} < 0$
 $R < 2\sqrt{\frac{L}{C}}$

$$s_{1/2} = -\frac{R}{2L} \pm j \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}$$

↑
 imaginary: $j^2 = -1$

$s_{1/2}$ complex conjugate numbers

Real part of $s_{1/2} = -\frac{R}{2L}$

Always negative

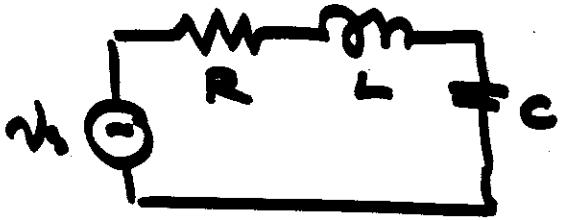
Note: always in pairs:

$$-d + j\omega$$

$$-d - j\omega$$

$\pm j\omega$: because all
 R, L, C
 are real
 numbers.

Another way of writing the equation:



$$v_s = Ri_L + L \frac{di_L}{dt} + v_C$$

$$i_L = C \frac{dv_C}{dt}$$

or:

$$\frac{di_L}{dt} = -\frac{R}{L} i_L + \frac{1}{L} v_C + \frac{1}{L} v_s$$

$$\frac{dv_C}{dt} = \frac{1}{C} i_L$$

Matrix form:

$$\frac{d}{dt} \begin{pmatrix} i_L \\ v_C \end{pmatrix} = \begin{pmatrix} -\frac{R}{L} & -\frac{1}{L} \\ \frac{1}{C} & 0 \end{pmatrix} \cdot \begin{pmatrix} i_L \\ v_C \end{pmatrix} + \begin{pmatrix} \frac{1}{L} \\ 0 \end{pmatrix} v_s$$

i_L : current through L

v_C : voltage across capacitor C

↑
State variables

let $x = \begin{pmatrix} i_L \\ v_C \end{pmatrix}$

$$\frac{dx}{dt} = Ax + b \leftarrow \begin{pmatrix} -1/2 \\ 0 \end{pmatrix} \cdot V_s$$

$$\begin{pmatrix} -R/L & -1/2 \\ 1/C & 0 \end{pmatrix}$$

b: depends on the type of the source connected to the circuit

A: depends only on circuit topology and elements

Homogeneous equation:

$$\frac{dx}{dt} = Ax$$

(Matrix DE homogeneous.)

Characteristic equation:

$$x = \begin{pmatrix} i_L \\ v_C \end{pmatrix}$$

Solutions: $k_1 e^{s_1 t} \leftarrow i_L$
 $k_2 e^{s_2 t} \leftarrow v_C$

Hence, suppose $x = \begin{pmatrix} k_1 e^{st} \\ k_2 e^{st} \end{pmatrix}$ is the solution. 106

$$s \begin{bmatrix} k_1 \\ k_2 \end{bmatrix} e^{st} = A \cdot \begin{bmatrix} k_1 \\ k_2 \end{bmatrix} e^{st}$$

$$e^{st} \neq 0 \quad \begin{bmatrix} k_1 \\ k_2 \end{bmatrix} \neq 0 \text{ matrix.}$$

Hence:

$$(sI - A) \begin{bmatrix} k_1 \\ k_2 \end{bmatrix} = 0$$

↑
identity matrix

(also denoted as I)
↖ text

(*) $\det(sI - A) = 0$ is the characteristic equation we have found earlier:

$$A = \begin{pmatrix} -R/L & -1/L \\ 1/C & 0 \end{pmatrix}$$

Prove that this is indeed the case!

Substitute A into (*) and expand the determinant.

let us consider again the three cases:

$$s_{1/2} = -\frac{R}{2L} \pm j \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}$$

$$s_{1/2} = -\alpha \pm j\omega$$

$$\alpha = R/2L \quad ; \quad \omega = \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}$$

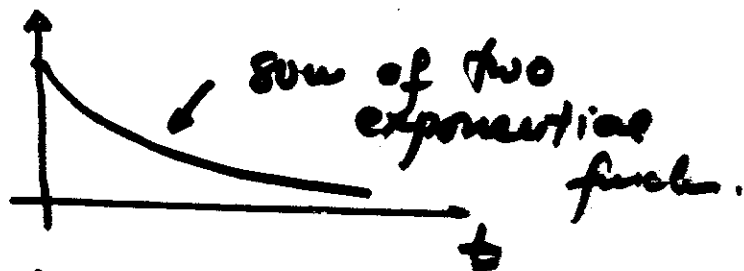
Case 1: $s_{1/2}$ Real and distinct $v_C(t) = k_1 e^{s_1 t} + k_2 e^{s_2 t}$

$$\rightarrow v_C = k_1 e^{s_1 t} + k_2 e^{s_2 t}$$

s_1, s_2 Real, negative.

Assum $v_C(0) \neq 0$

v_C : sum of two exponential functions



Case 2: $s_1 = s_2 := -\alpha$
 $\alpha = R/2L$

then

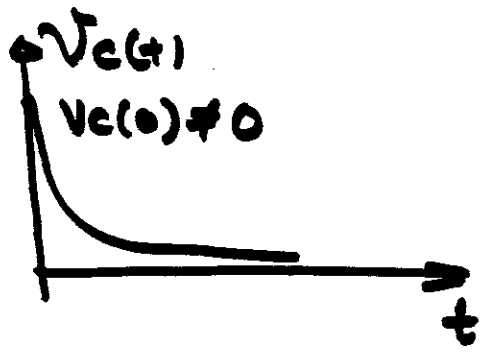
$$V_c(t) = K_1 e^{-\alpha t} + K_2 t e^{-\alpha t}$$

↑
 homogeneous solution

↑
 we have to assume this form in case

$\neq K_1 e^{s_1 t}$
 $K_1 e^{s_1 t} + K_2 e^{s_2 t}$

$s_1 = s_2$
 since
 $K_1 e^{s_1 t} + K_2 e^{s_2 t}$
 is not general enough
 if $s_1 = s_2$:
 $(K_1 + K_2) e^{s_1 t}$
 $= \underline{K e^{s_1 t}}$
 is too simplified!



as $t \rightarrow \infty \Rightarrow V_c(\infty) \rightarrow 0$ Homogeneous solution

Case 3:

$$s_{1/2} = -d \pm j\omega$$

$$j^2 = -1$$

 ω : Real

 $s_{1/2}$ complex conjugate

$$V_o(t) = k_1 e^{s_1 t} + k_2 e^{s_2 t}$$

$$V_o(t) = k_1 e^{(-d + j\omega)t} + k_2 e^{(-d - j\omega)t}$$

$$V_o(t) = e^{-dt} \cdot (k_1 e^{j\omega t} + k_2 e^{-j\omega t})$$

Euler's formulae: $e^{j\omega t} = \cos \omega t + j \sin \omega t$
 $e^{-j\omega t} = \cos \omega t - j \sin \omega t$

Hence:

$$k_1 e^{j\omega t} + k_2 e^{-j\omega t} = (k_1 + k_2) \cos \omega t + j(k_1 - k_2) \sin \omega t$$

$$= A \cos \omega t + B \sin \omega t$$

$$= \sqrt{} \cdot \sin(\omega t + \theta)$$

If: $A \cos \omega t + B \sin \omega t = V \sin(\omega t + \theta)$

Find V θ in terms of A B

Or: Since k_1 k_2 are unknown constants to be determined from "initial conditions"

A B are also unknown

V θ are also unknown

Hence, it is advantageous to assume:

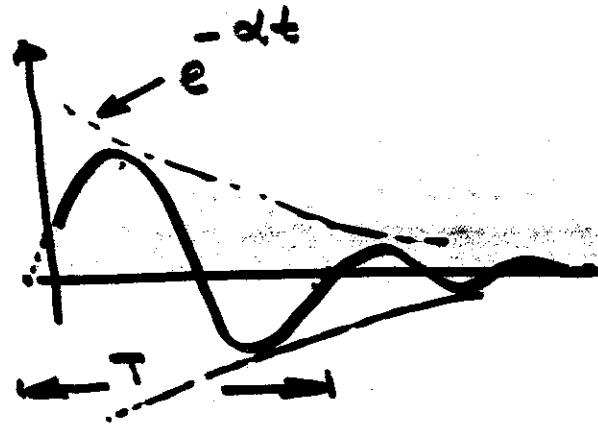
$$Vc(t) = e^{-dt} \cdot A \sin(\omega t + \theta)$$

unknown constants to be determined in the same way as k_1 or A k_2 or B would have been from the initial conditions.

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Response for the case:

s_1, s_2 complex conjugate:



$$T = 2\pi f$$
$$\omega = 1/f$$

$$v_s(t) = V e^{-\alpha t} \cdot \sin(\omega t + \theta)$$

↑

Natural
Response

$$\omega = \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}$$

< homogeneous solution >

Hence: Natural response of an RLC circuit depends on its natural frequencies:

- sum of two exponentials
- exponential + $t \cdot$ exponential
- decaying sinusoidal

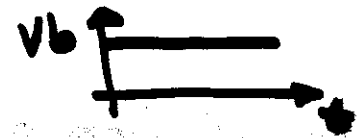
What if $V_s(t) = \text{Step function}$:

$$LC \frac{d^2V_c}{dt^2} + RC \frac{dV_c}{dt} + V_c = V_s(t)$$

$\leftarrow V_b \cdot u(t)$

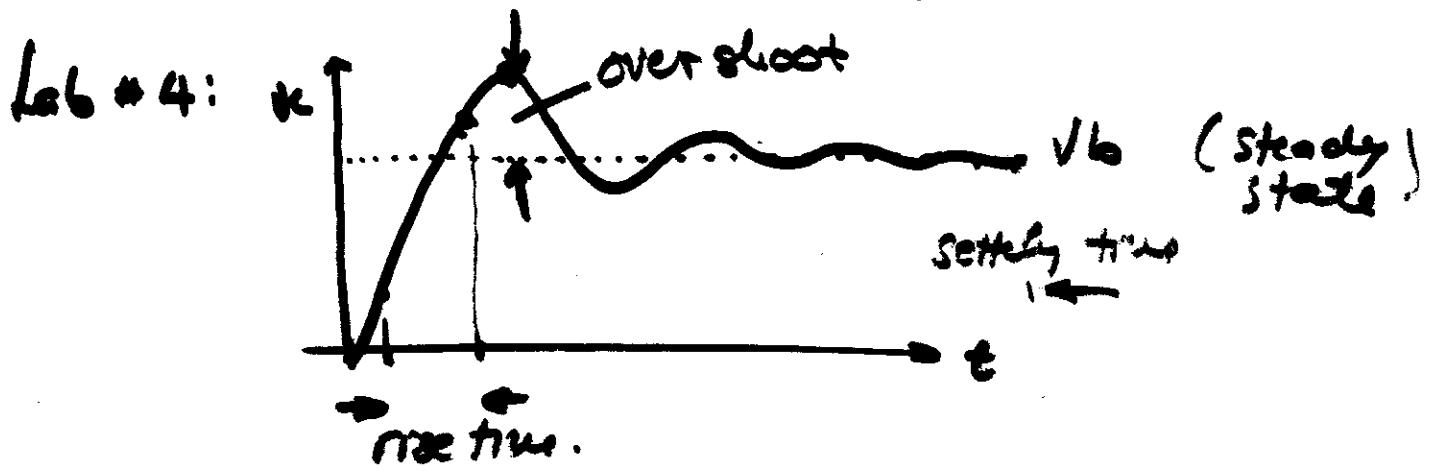
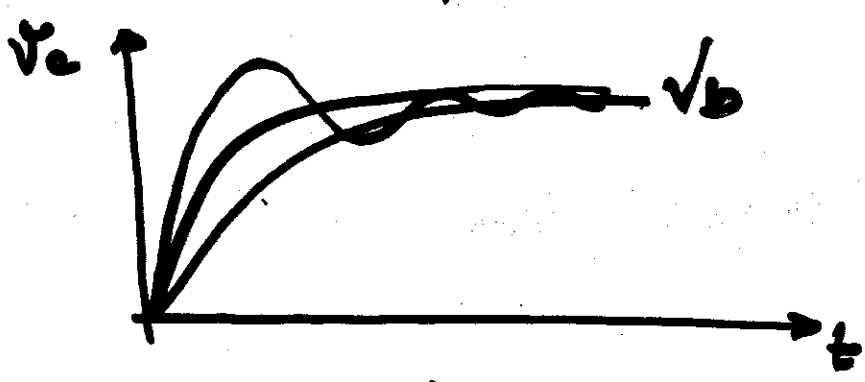
$V_{c, \text{particular}} = K$

$$K = V_b$$

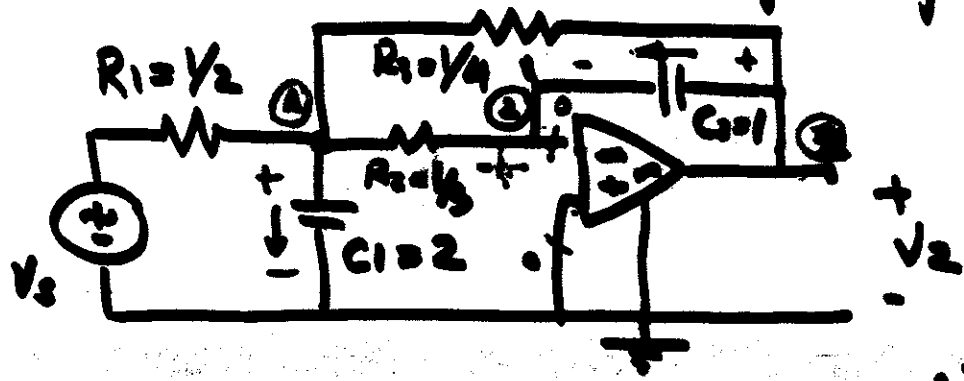


$$V_c(t) = V_h(t) + V_b$$

\uparrow Voltage across the capacitor.



RC circuit with an op-amp.



Note $\langle R_3 = \frac{1}{3} \rangle$

$V_2 = V_-$

$V_{C1} = V_1$

$V_{C2} = V_2 - V_-$

≈ 0

• Ideal op-amp:

Two capacitors : 2nd order DE

① $(V_1 - V_s) \cdot \frac{1}{R_1} + (V_1 - V_-) \cdot \frac{1}{R_2} + i_{C1} + (V_1 - V_2) \cdot \frac{1}{R_3} = 0$ KCL ①

② $(V_- - V_1) \cdot \frac{1}{R_2} - i_{C2} = 0$ $V_- = 0$

Also:

$i_{C1} = C_1 \frac{dV_{C1}}{dt}$ or $i_{C1} = C_1 \frac{dV_1}{dt}$

$i_{C1} = 2 \cdot \frac{dV_1}{dt}$

$i_{C2} = C_2 \frac{dV_{C2}}{dt}$ or $i_{C2} = \frac{dV_2}{dt}$

$V_{C2} = V_2 - V_-$
 $\approx V_2$

Hence:

$$2(V_1 - V_s) + 3V_1 + 2 \frac{dV_1}{dt} + 4(V_1 - V_2) = 0$$

$$-3V_1 - \frac{dV_2}{dt} = 0$$

And:

$$\left. \begin{aligned} 2 \frac{dV_1}{dt} + 9V_1 - 4V_2 &= 2V_s \\ \frac{dV_2}{dt} + 3V_1 &= 0 \leftarrow \end{aligned} \right\}$$

Two approach.

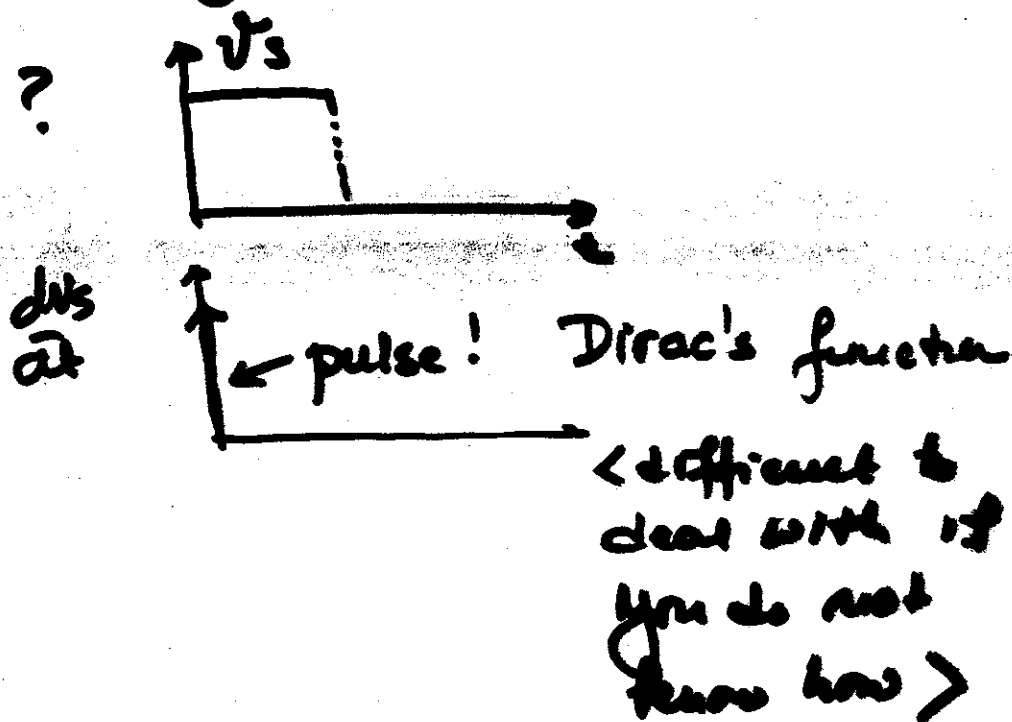
1) Substitution: Final DE equation is of 2nd order

2) Matrix form:

Method 1: Finding 2nd order DE

* Avoid taking derivative of $V_2(t)$

Why?



Let us find derivative of the 2nd equation:

$$\frac{d^2 V_2}{dt^2} + 3 \cdot \frac{dV_1}{dt} = 0$$

From the 1st equation: $\frac{dV_1}{dt} = -4.5 \cdot V_1 + 202 + V_2$

Hence

$$V_1 = -\frac{1}{3} \frac{dV_2}{dt}$$

$$\frac{d^2 v_2}{dt^2} + 3 \cdot \{-4.5 v_1 + 2v_2 + v_s\} = 0$$

$$\downarrow -\frac{1}{3} \cdot \frac{dv_2}{dt}$$

Hence:

$$\frac{d^2 v_2}{dt^2} + 3 \cdot \left\{ 1.5 \cdot \frac{dv_2}{dt} + 2v_2 + v_s \right\} = 0$$

or:

$$\frac{d^2 v_2}{dt^2} + 4.5 \cdot \frac{dv_2}{dt} + 6v_2 = -3v_s$$

DE: 2nd order

Characteristic equation:

$$s^2 + 4.5s + 6 = 0$$

Natural frequencies:

$$s_{1/2} = -2.25 \pm \sqrt{2.25^2 - 6}$$

or

$$s_{1/2} = -2.25 \pm j0.97$$

! Complex conjugate!

RC network

Why should you be surprised that natural frequencies of an RC network are complex numbers?

$$RC_1: s = -1/RC$$

RC_1C_2 : $s_{1/2}$: real and negative

RC_1C_2 and op-amp: $s_{1/2}$: complex!

↑
because of the op-amp!

Not a passive element

It could even make s_1
 s_2

to have positive Real part.

Nevertheless: if complex natural frequencies they will always appear as complex conjugate pairs.

2) Matrix form

< State equations: $v_1 = v_{c1}$
 $v_2 = v_{c2}$

↑
State variables

$$\left. \begin{aligned} 2 \frac{dv_1}{dt} + 9v_1 - 4v_2 &= 2v_s \\ \frac{dv_2}{dt} + 3v_1 &= 0 \end{aligned} \right\}$$

or: $\frac{dv_1}{dt} = -4.5v_1 + 2v_2 + v_s$

$$\frac{dv_2}{dt} = -3v_1$$

Matrix form:

$$\frac{d}{dt} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} -4.5 & 2 \\ -3 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} + \begin{bmatrix} v_s \\ 0 \end{bmatrix}$$

\uparrow x \uparrow A \uparrow b

$$\frac{dx}{dt} = Ax + b$$

$$A = \begin{bmatrix} -4.5 & 2 \\ -3 & 0 \end{bmatrix}$$

How can we find natural frequencies;

Assume: $x_1 = k_1 e^{st} \leftarrow v_1$
 $x_2 = k_2 e^{st} \leftarrow v_2$

(10)
(01)

$$\underbrace{(sI - A)}_{2 \times 2} k = 0, \quad \uparrow \text{vectors}$$

Has nontrivial solutions only if:

$$\det \begin{matrix} (sI - A) = 0 \\ \uparrow \quad \uparrow \\ 2 \times 2 \quad 2 \times 2 \end{matrix} \quad \sim \text{Another notation:} \\ sI - A = 0$$

$$\det \left\{ s \cdot \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} -4.5 & 2 \\ -3 & 0 \end{pmatrix} \right\} = 0$$

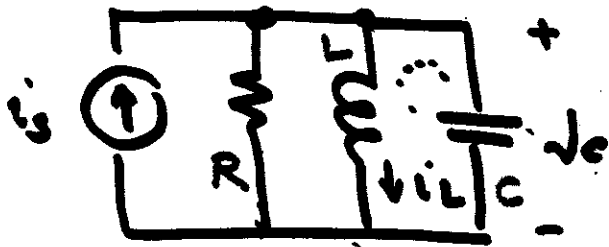
$$\det \begin{pmatrix} s+4.5 & -2 \\ 3 & s \end{pmatrix} = 0$$

$$\text{or: } (s+4.5) \cdot s + 6 = 0$$

$$s^2 + 4.5s + 6 = 0 \leftarrow$$

identical to the characteristic eq. found by method 1).

RLC parallel circuit



① $i_s = i_R + i_L + i_C$: KCL

Ohm $\rightarrow i_R = v_c / R$ }
 $i_C = C \frac{dv_c}{dt}$ }

$v_L = v_c$; $v_L = L \frac{di_L}{dt}$ ←

② $L \frac{di_L}{dt} - v_c = 0$

Hence:

$C \cdot \frac{dv_c}{dt} + \frac{1}{R} \cdot v_c + i_L = i_s$ }

$L \frac{di_L}{dt} - v_c = 0$

2nd order

or

2 : 1st order

DE

State equations form:

$$\begin{bmatrix} C & 0 \\ 0 & L \end{bmatrix} \cdot \frac{d}{dt} \begin{bmatrix} v_c \\ i_L \end{bmatrix} + \begin{bmatrix} 1/R & 1 \\ -1 & 0 \end{bmatrix} \cdot \begin{bmatrix} v_c \\ i_L \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \cdot i_s$$

Let $x = \begin{bmatrix} v_c \\ i_L \end{bmatrix}$ (vector: 2×1)

$$\begin{bmatrix} C & 0 \\ 0 & L \end{bmatrix} \cdot \frac{dx}{dt} + \begin{bmatrix} 1/R & 1 \\ -1 & 0 \end{bmatrix} \cdot x = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \cdot i_s$$

Or:

$$\frac{dx}{dt} = - \begin{bmatrix} C & 0 \\ 0 & L \end{bmatrix}^{-1} \cdot \begin{bmatrix} 1/R & 1 \\ -1 & 0 \end{bmatrix} \cdot x$$

$$+ \begin{bmatrix} C & 0 \\ 0 & L \end{bmatrix}^{-1} \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix} \cdot i_s$$

$$\frac{dx}{dt} = \begin{bmatrix} -\frac{1}{RC} & -\frac{1}{C} \\ \frac{1}{L} & 0 \end{bmatrix} \cdot x + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \cdot i_s$$

Form: $\frac{dx}{dt} = Ax + b$ $\begin{bmatrix} C & 0 \\ 0 & L \end{bmatrix}^{-1}$

Characteristic equation:

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Homogeneous DE:

$$\frac{dx}{dt} = Ax$$

Solution $x = k \cdot e^{st}$ (vectors!)

$$s \cdot k \cdot e^s = A k e^s$$

$$(s \cdot I - A) \cdot k e^s = 0$$

vector

Nontrivial solutions only if:

$(sI - A)$ is a singular matrix

or

$$\det(sI - A) = 0$$

$$\det \left\{ s \cdot \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} -\frac{1}{RC} & -\frac{1}{C} \\ \frac{1}{L} & 0 \end{pmatrix} \right\} = 0$$

$$\det \left\{ \begin{pmatrix} s & 0 \\ 0 & s \end{pmatrix} - \begin{pmatrix} -\frac{1}{RC} & -\frac{1}{C} \\ \frac{1}{L} & 0 \end{pmatrix} \right\} = 0$$

$$\det \begin{pmatrix} s + \frac{1}{RC} & \frac{1}{C} \\ -\frac{1}{L} & s \end{pmatrix} = 0$$

$$s \cdot (s + \frac{1}{RC}) + \frac{1}{LC} = 0$$

$$s^2 + \frac{1}{RC}s + \frac{1}{LC} = 0$$

Compare with the characteristic of RLC in series:

$$s^2 + \frac{R}{L}s + \frac{1}{LC} = 0$$

Duality

$$R \leftrightarrow G$$

$$L \leftrightarrow C$$

$$C \leftrightarrow L$$

Same equation

Natural frequency:

$$s_{1/2} = -\frac{1}{2RC} \pm \sqrt{\left(\frac{1}{2RC}\right)^2 - \frac{1}{LC}}$$

3 cases: $s_{1/2}$: Real dist.
 : $-n$ - ident
 : complex

Natural response:

Finding coefficients k_1 and k_2

$$v_c(t) = k_1 e^{s_1 t} + k_2 e^{s_2 t}$$

homog.

$$i_L(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

homog

How to find k_1, k_2 ?
 A_1, A_2 ?

From initial conditions:

$$v_c(0^-) = v_c(0^+)$$

$$i_L(0^-) = i_L(0^+)$$

conservation laws!

Recall:

$$C \frac{dv_c}{dt} + \frac{1}{R} v_c + i_L = 0$$

← Homogeneous case

$$L \frac{di_L}{dt} - v_c = 0$$

} Our DE.

Let us find k_1 and k_2 :

$$V_C(0+) = k_1 + k_2 \Rightarrow k_1 + k_2 = V_0$$

↑
assume
C was charged
with V_0 .

What if $V_C(0-) = 0$

$$\Rightarrow k_1 + k_2 = 0$$

if, in addition,

$$i_L(0-) = 0$$

TRIVIAL solutions
(all 0) only!

$$\frac{dv_C}{dt} = k_1 s_1 e^{s_1 t} + k_2 s_2 e^{s_2 t}$$

$$\left(\frac{dv_C}{dt} \right)_{0+} = k_1 s_1 + k_2 s_2$$

↑ How do we find $\frac{dv_C}{dt}$ at $t = 0+$!

From DE equations and by knowing
 $V_C(0-)$ and $i_L(0-)$!

From DE:

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$$C \cdot \frac{dv_c}{dt} + \frac{1}{R} v_c + i_L = 0 \quad 1)$$

$$L \frac{di_L}{dt} - v_c = 0 \quad 2)$$

From 1)

$$C \cdot \frac{dv_c}{dt} = -\frac{1}{R} v_c - i_L$$

At $t=0+$:

$$C \cdot \frac{dv_c}{dt} \Big|_{0+} = -\frac{1}{R} v_c(0+) - i_L(0+)$$

\downarrow \downarrow
 $v_c(0-)$ $i_L(0-)$

Hence:

$$\left(\frac{dv_c}{dt} \right)_{0+} = -\frac{1}{RC} v_b - \frac{i_b}{C}$$

assume
a value
or 0

Hence:

$$k_1 + k_2 = v_c(0-)$$

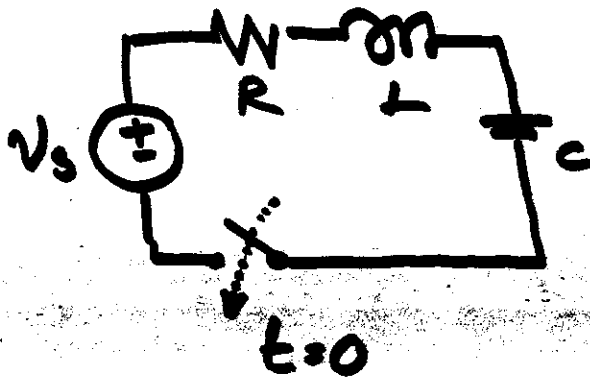
$$k_1 s_1 + k_2 s_2 = -\frac{1}{RC} v_c(0-) - \frac{i_L(0-)}{C}$$

2 equations with k_1 and k_2 unknown
Solve it for k_1 and k_2

< Similar procedure for finding A_1 and $A_2 : i_L >$

Complete response:

RLC (series):



S: closes at $t=0$
 It was open for
 a long time
 (equilibrium)

$$\text{DE: } \frac{di_L}{dt} = -\frac{R}{L} i_L - \frac{1}{L} v_C + \frac{1}{L} v_s$$

$$\frac{dv_C}{dt} = \frac{1}{C} i_L$$

$$\text{State equation: } \frac{dx}{dt} = Ax + b$$

↑ includes
 $v_s(t)$

after written as:

$$\rightarrow \dot{b} \cdot v_s(t)$$

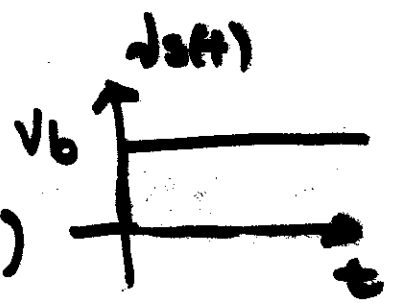
to emphasize time
 function of the
 source!

Procedure:

1. Find solution to the homogeneous DE
two natural frequencies: 2nd order circuit
2. Find the particular solution
3. Add them \Rightarrow complete response
4. Find initial conditions and calculate constants.

RLC circuit:

<series connection>



Step response: $V_s(t) = V_b \cdot u(t)$

$$\left. \begin{aligned}
 \text{DE: } \frac{dV_c}{dt} &= -\frac{R}{L} \cdot V_c - \frac{1}{L} \cdot V_c + \frac{1}{L} \cdot V_b \cdot u(t) \\
 \frac{dV_L}{dt} &= \frac{1}{C} \cdot V_L
 \end{aligned} \right\}$$

①

$$v_c(t) = \underbrace{k_1 e^{s_1 t} + k_2 e^{s_2 t}}_{v_{ch}} + \underbrace{V_b}_{v_{cp}}$$

Ody?

- ① 2nd order DE
- ② Set of 1st order DE's

S ②

① $LC \frac{d^2 v_c}{dt^2} + RC \frac{dv_c}{dt} + v_c = v_s$

\uparrow 0 \uparrow 0 \uparrow $v_b u(t)$

in equilibrium
<steady-state>

Hence $v_c = \frac{V_b}{\sqrt{Cp}}$

or

② $\frac{di_L}{dt} = -\frac{R}{L} i_L - \frac{1}{L} v_c + \frac{1}{L} v_b u(t)$

$\frac{dv_c}{dt} = \frac{1}{C} i_L = 0$

\downarrow 0

$v_c = V_b$
< v_{cp} >

particular solution

Look at the circuit!

5 (3)

$$v_c(t) = k_1 e^{s_1 t} + k_2 e^{s_2 t} + V_b \quad (1)$$

(4) Five unspecified constants from the initial conditions:

$$v_c(0^+) = v_c(0^-)$$

$$i_L(0^+) = i_L(0^-)$$

Assume $v_c(0^-) = 0$
 $i_L(0^-) = 0$ } Switch open for a long time.

< see text p. 319 for non-zero case >

(1) $k_1 + k_2 + V_b = 0$

(2) ? From DE: $\frac{dv_c}{dt} = \frac{1}{C} \cdot i_L$

$$s_1 \cdot k_1 e^{s_1 t} + s_2 \cdot k_2 e^{s_2 t} \rightarrow \frac{dv_c}{dt} = \frac{1}{C} \cdot i_L$$

$$\text{at } t=0^+: s_1 k_1 + s_2 k_2 = \frac{1}{C} \cdot i_L(0^+) = \frac{1}{C} \cdot i_L(0^-) = 0$$

Thus:

$$k_1 + k_2 + V_b = 0$$

$$\rightarrow k_1 s_1 + k_2 s_2 = 0 \quad \text{Solve them:}$$

Complete solution:

$$v_c(t) = k_1 e^{s_1 t} + k_2 e^{s_2 t} + V_b \leftarrow$$

$$\rightarrow i_L(t) = C \cdot \frac{dv_c}{dt}$$

↓

$$i_L(t) = C (k_1 s_1 e^{s_1 t} + k_2 s_2 e^{s_2 t})$$

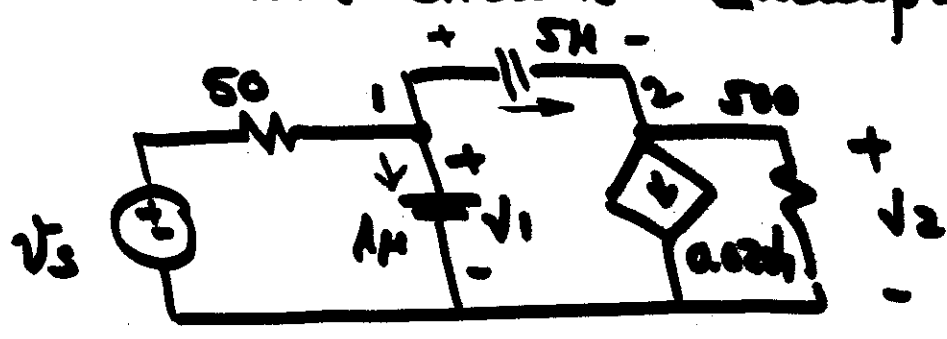
As $t \rightarrow \infty$ $v_c(t) \rightarrow V_b$

$i_L(t) \rightarrow 0$

As expected
in the circuit



2nd order circuits: example



Roller
28
p. 334
text

$$v_s(t) = 10 [u(t) - u(t - 10^{-4})]$$

Find $v_2(t)$?

$$v_{c1} = v_1 \quad \dot{v}_{c1} = 10^{-6} \frac{dv_{c1}}{dt}$$

$$v_{c2} = v_1 - v_2 \quad \dot{v}_{c2} = 5 \times 10^{-6} \frac{dv_{c2}}{dt}$$

Hence:

$$v_2 = v_{c1} - v_{c2} \leftarrow$$

If we write state equations, we can find

$$\begin{matrix} v_{c1} \\ v_{c2} \end{matrix} \Rightarrow v_2 = v_{c1} - v_{c2} \quad (\text{algebraic, no DE})$$

Two node equations:

$$\left\{ \begin{array}{l} \frac{v_{c1} - v_s}{50} + i_1 + i_2 = 0 \quad \text{KCL (1)} \\ -i_2 + 0.02v_1 + \frac{v_2}{500} = 0 \quad \text{KCL (2)} \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{v_{c1}}{50} + C_1 \frac{dv_{c1}}{dt} + C_2 \frac{dv_{c2}}{dt} = \frac{v_s}{50} \quad (1) \\ -C_2 \frac{dv_{c2}}{dt} + 0.02 \cdot \underset{=v_1}{v_{c1}} + \frac{1}{500} \underbrace{(v_{c1} - v_{c2})}_{=v_2} = 0 \quad (2) \end{array} \right.$$

or:

$$10^{-6} \frac{dv_{c1}}{dt} + 5 \times 10^{-6} \frac{dv_{c2}}{dt} + 0.02 \cdot v_{c1} = \frac{v_s}{50} \quad (1)$$

$$-5 \times 10^{-6} \frac{dv_{c2}}{dt} + 0.02 v_{c1} + 0.002 (v_{c1} - v_{c2}) = 0 \quad (2)$$

$$5 \times 10^{-6} \frac{dv_{c2}}{dt} - 0.022 v_{c1} + 0.002 v_{c2} = 0 \quad (3)$$

$$\rightarrow 5 \times 10^{-6} \frac{dv_{c2}}{dt} = 0.022 v_{c1} - 0.002 v_{c2} \quad (2)$$

Substitute into (1)

$$10^{-6} \frac{dV_{c1}}{dt} + 0.022V_{c1} - 0.002V_{c2} + 0.02V_{c1} = \frac{V_s}{10}$$

Hence:

$$\left. \begin{aligned} 10^{-6} \frac{dV_{c1}}{dt} + 0.042V_{c1} - 0.002V_{c2} &= \frac{V_s}{10} \\ 5 \times 10^{-6} \frac{dV_{c2}}{dt} - 0.022V_{c1} + 0.002V_{c2} &= 0 \end{aligned} \right\}$$

let $x = \begin{pmatrix} V_{c1} \\ V_{c2} \end{pmatrix}$

Then

$$\begin{pmatrix} 10^{-6} & 0 \\ 0 & 5 \times 10^{-6} \end{pmatrix} \frac{dx}{dt} + \begin{pmatrix} 0.042 & -0.002 \\ -0.022 & 0.002 \end{pmatrix} x = \begin{pmatrix} 0.1 \\ 0 \end{pmatrix}$$

let $x = k e^{s t}$
 $\quad \quad \quad \uparrow \begin{pmatrix} k_1 \\ k_2 \end{pmatrix}$

$$dft \left\{ 10^{-6} \cdot \begin{pmatrix} 1 & 0 \\ 0 & 5 \end{pmatrix} \cdot s + \begin{pmatrix} 0.042 & -0.002 \\ -0.022 & 0.002 \end{pmatrix} \right\} = 0$$

$$\det \begin{Bmatrix} 10^{-6}s + 0.042 & -0.002 \\ -0.022 & 5 \times 10^{-6}s + 0.002 \end{Bmatrix} = 0$$

$$(10^{-6}s + 0.042)(5 \times 10^{-6}s + 0.002) - 0.002 \times 0.022 = 0$$

$$\Downarrow s_{1/2}$$

$$5 \times 10^{-12} s^2 + 0.212 \times 10^{-6} s + 40 \times 10^{-6} = 0$$

$$5s^2 + 0.212 \times 10^6 s + 40 \times 10^6 = 0$$

$$s_{1/2} = -\frac{0.212}{10} \times 10^6 \pm \sqrt{(0.212 \times 10^6)^2 - 8 \cdot 10^6}$$

$$s_1 = -42240 ; s_2 = -190$$

Then:

$$v_2 = v_{c1} - v_{c2} \leftarrow$$

$$\rightarrow v_2 = K_1 e^{s_1 t} + K_2 e^{s_2 t} + \underline{v_{2p}} \quad \text{Complete solution}$$

Note that:

$$v_2(0+) = v_{c1}(0+) - v_{c2}(0+)$$

$$v_2(0+) = v_{c1}(0-) - v_{c2}(0-)$$

$$v_2(0+) = 0$$

Hence: $v_2(0+) = 0$ (but only because $v_{c1}(0+) = 0$ and $v_{c2}(0+) = 0$)

We also need

$\frac{dv_2}{dt} \Big|_{0+} = ?$ From: $v_2 = v_{c1} - v_{c2}$

$$\frac{dv_2}{dt} \Big|_{0+} = \frac{dv_{c1}}{dt} \Big|_{0+} - \frac{dv_{c2}}{dt} \Big|_{0+}$$

From DS:

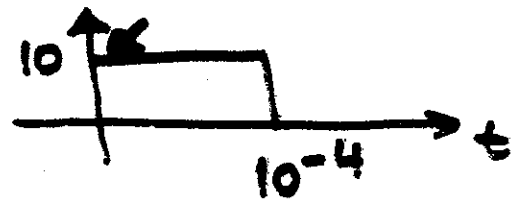
$$10^{-6} \frac{dv_{c1}}{dt} + 0.042 v_{c1} - 0.002 v_{c2} = 0.2$$

$$5 \times 10^{-6} \frac{dv_{c2}}{dt} - 0.022 v_{c1} + 0.002 v_{c2} = 0$$

At $t = 0+$: $v_{c1}(0+) = v_{c2}(0+) = 0$

Recall: $v_s(t) = 10[u(t) - u(t - 10^{-4})]$

$$v_s(0+) = 10$$



Hence: $10^{-6} \cdot \frac{dV_{c1}}{dt} \Big|_{0+} = 0.2$

$5 \times 10^{-6} \cdot \frac{dV_{c2}}{dt} \Big|_{0+} = 0$

And: $\frac{dV_2}{dt} = \frac{dV_{c1}}{dt} - \frac{dV_{c2}}{dt} \quad \forall t$
(For any t)

At $t=0+$: $\frac{dV_2}{dt} \Big|_{0+} = 0.2 \times 10^6$

Again: $V_2 = K_1 e^{s_1 t} + K_2 e^{s_2 t} + V_p$

Recall: $V_2(0+) = 0$
 $\frac{dV_2}{dt} \Big|_{0+} = 0.2 \times 10^6$

And: $K_1 + K_2 + V_p = 0$
 $K_1 s_1 + K_2 s_2 + \frac{dV_p}{dt} = 0.2 \times 10^6$

We now need to find the particular solution for v_2 :

Since the source is constant (DC) and equal to 10V for $t > 0$ (and $t < 10^{-4}$) assume that

$$v_{c1 \text{ part.}} = \text{constant (A)}$$

$$v_{c2 \text{ part.}} = \text{constant (B)}$$

$$v_2 \text{ part.} = \text{constant (C)}$$

From DE: $\leftarrow 0$

$$10^{-6} \frac{dv_{c1}}{dt} + 0.042 v_{c1} - 0.002 v_{c2} = 0.2$$

$$5 \times 10^{-6} \frac{dv_{c2}}{dt} - 0.022 v_{c1} + 0.002 v_{c2} = 0$$

\uparrow

Particular solutions satisfy:

$$0.042 v_{c1p} - 0.002 v_{c2p} = 0.2$$

$$-0.022 v_{c1p} + 0.002 v_{c2p} = 0$$

Find v_{c1p} and v_{c2p} : Then $v_2p = v_{c1p} - v_{c2p}$

$$V_{c1p} = 10$$

$$V_{c2p} = 110$$

$$\text{Hence } V_{2p} = -100$$

We can now find constants k_1 and k_2 ,

$$k_1 + k_2 - 100 = 0$$

$$k_1 s_1 + k_2 s_2 = 0.2 \times 10^6$$

$$k_1 = -5.211 \quad ; \quad k_2 = 105.211$$

Hence

$$V_2(t) = -5.211 e^{-42210t} + 105.211 e^{-190t} - 100$$

Complete solution for

$$0 < t < 10^{-4} \text{ sec.}$$

$$\text{At } t = 10^{-4} \text{ sec: } V_2 \Big|_{\text{at } t = 10^{-4} \text{ sec}} = \underline{\underline{3.154}}$$

Even though we were interested in finding v_2 , it is advantageous to find v_{c1}
 v_{c2}

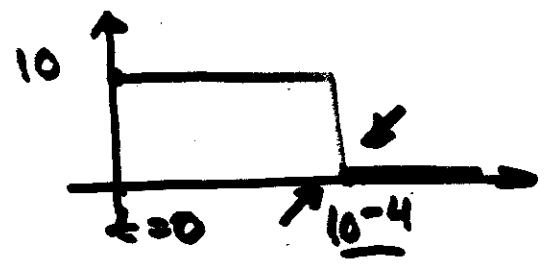
From the same DE, complete solution for two "state" voltages are:

$$v_{c1} = -4.714 e^{-4220t} - 5.286 e^{-190t} + 10$$

$$v_{c2} = 0.497 e^{-4220t} - 110.497 e^{-190t} + 110$$

They can be found from the same DE equations, using the same approach as for finding v_2 .

At $t = 10^{-4}$, $V_s(t)$ changes



Then: DE:

$$10^{-6} \frac{dV_{c1}}{dt} + 0.042V_{c1} - 0.002V_{c2} = 0$$

$$5 \times 10^{-6} \frac{dV_{c2}}{dt} - 0.022V_{c1} + 0.002V_{c2} = 0$$

The system has not changed:

$\delta/2$ are the same

But now; the particular solution is zero.
The system of DE's is homogeneous.

The easiest approach is to find

$$\begin{matrix} V_{c1} \\ V_{c2} \end{matrix} \quad \text{Then: } V_2 = V_{c1} - V_{c2}$$

From:

$$V_{c1} = K_1 e^{s_1 t} + K_2 e^{s_2 t}$$

$$V_{c2} = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

particular
solution
= 0DE are
homogeneous

Note

$$V_{c1}(10^{-4}+) = V_{c1}(10^{-4}-)$$

$$V_{c2}(10^{-4}+) = V_{c2}(10^{-4}-)$$

we already have
expressions for
 V_{c1} for $t < 10^{-4}$
 V_{c2}

Substitute 10^{-4} in these

$$V_{c1}(10^{-4}) = 4.344 \text{ V}$$

$$V_{c2}(10^{-4}) = 1.590$$

From DE:

$$\frac{dV_{c1}}{dt} = 10^6 \times (-0.042V_{c1} + 0.002V_{c2})$$

$$\frac{dV_{c2}}{dt} = 10^6 \times \frac{1}{5} \cdot (0.022V_{c1} - 0.002V_{c2})$$

Hence, we can find

$$\frac{dV_{c1}}{dt} \text{ and } \frac{dV_{c2}}{dt} \text{ at } t=10^{-4}$$

$$(\text{Recall } V_{c1}(10^{-4}) = V_{c1}(10^{-4}+))$$

$$\text{Then: } k_1 e^{-4220 \cdot 10^{-4}} + k_2 e^{-190 \cdot 10^{-4}} = 0$$

$$k_1 (-4220 e^{-4220 \cdot 10^{-4}}) + k_2 (-190 e^{-190 \cdot 10^{-4}}) = \frac{dV_{c1}}{dt} \Big|_{t=10^{-4}+}$$

Repeat the same for finding constant

A_1 and A_2 is

$$V_2 = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

gives

$$V_{c1} = 4.645 e^{-4220 t} + 0.099 e^{-190 t}$$

$$V_{c2} = -0.489 e^{-4220 t} + 2.079 e^{-190 t}$$

and $V_2 = V_{c1} - V_{c2}$

$$V_2 = 5.134 e^{-4220 t} - 1.98 e^{-190 t}$$

Note that once we found

$$v_{c1}$$
$$v_{c2}$$

v_2 was found from an "algebraic" relationship:

$$v_2 = v_{c1} - v_{c2}$$

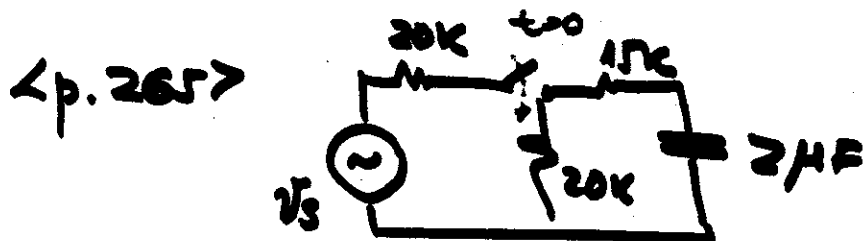
In addition, all other circuit variables (voltages and currents) can be found from simple KCL and KVL equations, or by finding derivatives

Example:

$$i_{c1} = C_1 \frac{dv_{c1}}{dt}$$

$$i_{c2} = C_2 \frac{dv_{c2}}{dt}$$

Complete response: Examples



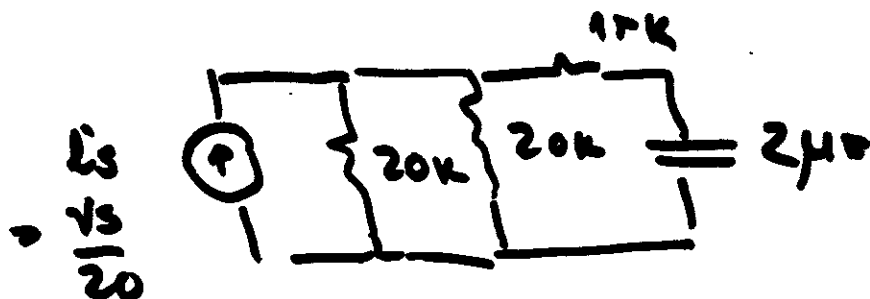
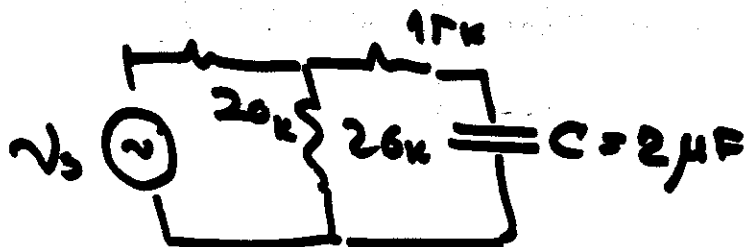
$v_C(0^-) = 0$ (No charge stored at $t=0^-$.)

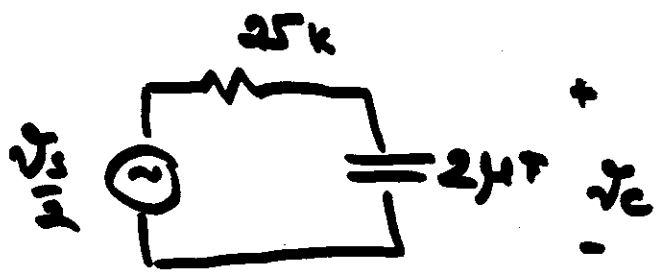
Hence: $v_C(0^+) = 0$

1st order circuit: One capacitor

Switch closes at $t=0$,

Hence, for $t \geq 0$:





$$\frac{v_s}{2} - 25 \times 10^3 \cdot i - v_c = 0$$

$$i = 2 \cdot 10^{-6} \cdot \frac{dv_c}{dt}$$

$$50 \times 10^{-3} \cdot \frac{dv_c}{dt} + v_c = \frac{v_s}{2}$$

$$\frac{dv_c}{dt} + 20 \cdot v_c = \frac{1}{100 \times 10^{-3}} \cdot v_s$$

$$\frac{dv_c}{dt} + 20v_c = 10 \cdot v_s$$

Let $v_s = V_m \sin(\omega t)$ Sinusoidal source

$$v_c(t) = v_{ch}(t) + v_{cp}(t)$$

$$v_{ch}(t) = k \cdot e^{st} \Rightarrow \frac{dv_c}{dt} + 20 \cdot v_c = 0$$

$$k \cdot s + 20 \cdot k = 0$$

$$s = -20$$

$$v_c(t) = k e^{-20t} + v_{cp}(t)$$

$$V_c(t) = V_m \cdot \sin(\omega t + \theta)$$

$$\frac{dV_c}{dt} + 20V_c = 10 \cdot V_s$$

$$V_c \cdot \omega \cdot \cos(\omega t + \theta) + 20 \cdot V_c \cdot \sin(\omega t + \theta)$$

$$\downarrow = 10 \cdot V_m \cdot \sin \omega t$$

For simplicity

let $V_c = V_m$
↑
cap.

$$V_c \cdot \omega \cdot (\cos \omega t \cos \theta - \sin \omega t \cdot \sin \theta) + 20 \cdot V_c \cdot (\sin \omega t \cdot \cos \theta + \cos \omega t \cdot \sin \theta) = 10 V_m \cdot \sin \omega t$$

Hence:

$$V_c \cdot \omega \cdot \cos \theta + 20 \cdot V_c \cdot \sin \theta = 0 \tag{1}$$

$$-V_c \cdot \omega \cdot \sin \theta + 20 \cdot V_c \cdot \cos \theta = 10 V_m \tag{2}$$

Find V_c and θ :

$$\text{From (1): } \omega \cos \theta = -20 \sin \theta \Rightarrow \tan \theta = -\frac{\omega}{20}$$

$$\theta = -\arctan \frac{\omega}{20}$$

From (2)

$$-V_c \cdot \omega \cdot \sin \theta + 20V_c \cos \theta = 10V_m$$

$$V_c = \frac{10V_m}{20 \cos \theta - \omega \sin \theta}$$

Recall: $\omega \cos \theta = -20 \sin \theta$

$$V_c = \frac{10V_m}{20 \cdot \frac{-20}{\omega} \sin \theta - \omega \sin \theta}$$

$$V_c = \frac{10V_m}{\left(-\frac{400}{\omega} - \omega\right) \sin \theta}$$

$$V_c = \frac{-10V_m \cdot}{\frac{400 + \omega^2}{\omega} \cdot \sin \theta}$$

$$\tan \theta = -\frac{\omega}{20}$$

$$\sin \theta = \frac{-\omega/20}{\sqrt{1 + \frac{\omega^2}{400}}}$$

$$V_c = \frac{10V_m}{\sqrt{400 + \omega^2}}$$

$$\sin \theta = \frac{-\omega}{\sqrt{400 + \omega^2}}$$

Hence:

$$v_c(t) = K e^{-20t} + \frac{10V_m}{\sqrt{400 + \omega^2}} \sin(\omega t - \arctan \omega/20)$$

$$v_c(t) = K e^{-20t} + \frac{1}{2} \cdot \frac{20 \text{ Vm}}{\sqrt{400 + \omega^2}} \cdot \sin(\omega t - \arctan \frac{\omega}{20})$$

to be determined

from $v_c(0^+) = v_c(0^-)$

ω from the source

If $v_c(0^-) = 0$

$$K + \frac{1}{2} \cdot \frac{20 \text{ Vm}}{\sqrt{400 + \omega^2}} \cdot \sin(-\arctan \frac{\omega}{20}) = 0$$

$$\tan \theta = -\frac{\omega}{20}$$

$$\theta = -\arctan \frac{\omega}{20}$$

$$\sin \theta = \frac{-\omega/20}{\sqrt{1 + \frac{\omega^2}{400}}}$$

$$K + \frac{10 \text{ Vm}}{\sqrt{400 + \omega^2}} \cdot \frac{-\omega}{\sqrt{400 + \omega^2}} = 0 \quad \tan \theta = \frac{-\omega}{\sqrt{400 + \omega^2}}$$

$$K = \frac{10 \text{ Vm} \cdot \omega}{400 + \omega^2}$$

Form:

$$V_C(t) = k e^{-20t} + \frac{1}{2} \cdot \frac{20 \text{ Vm}}{\sqrt{400 + \omega^2}} \sin(\omega t - \arctan \frac{\omega}{20})$$

Recall: $R = 25 \text{ k}$
 $C = 2 \mu\text{F}$

$$RC = 50 \times 10^{-3} \text{ sec}$$

$$\frac{1}{RC} = 20$$

$$V_C(t) = k e^{-20t} + \frac{1}{2} \cdot \frac{20 \text{ Vm}}{\sqrt{20^2 + \omega^2}} \sin(\omega t - \arctan \frac{\omega}{20})$$

$$V_C(t) = k e^{-\frac{t}{RC}} + \frac{1}{2} \cdot \frac{1}{RC} \cdot \frac{\text{Vm}}{\sqrt{(\frac{1}{RC})^2 + \omega^2}} \sin(\omega t - \arctan \omega RC)$$

$$\frac{1}{RC} \cdot \frac{\text{Vm}}{\sqrt{R^2 + (\frac{1}{\omega C})^2}}$$

The sinusoidal steady state:

As $t \rightarrow \infty$

$$K e^{-t/RC} \rightarrow 0$$

Hence:

$$V_c(t) = V_p(t)$$

$$V_c(t) = \frac{1}{2} \cdot \frac{1}{\omega C} \cdot \frac{V_m}{\sqrt{R^2 + (\omega C)^2}} \cdot \sin(\omega t - \theta)$$

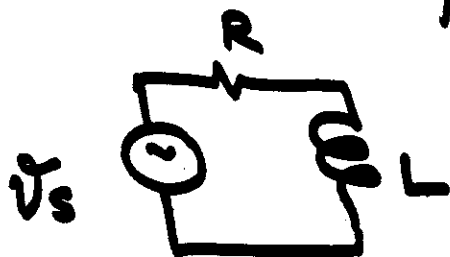
$$\theta = \arctan \omega RC$$

Periodic function:

frequency ω (the same as ω
of the independent
source)

angle θ : lagging $\theta = \arctan \omega RC$

Another simple circuit:



$$L \frac{di}{dt} + Ri = v_s(t)$$

$$v_s = V_m \cos \omega t$$

$$L \frac{di}{dt} + Ri = V_m \cos \omega t$$

$$L \frac{di}{dt} + Ri = 0 \Rightarrow i = k e^{st}$$

$$L \cdot k \cdot s e^{st} + R \cdot k e^{st} = 0$$

$$Ls + R = 0 \quad s = -\frac{R}{L}$$

$$i(t) = k e^{-\frac{R}{L}t} + i_p(t)$$

$$i_p(t) = I_m \cos(\omega t + \varphi)$$

Method ①: substitute $i_p(t)$ into DE
and find I_m and φ

$$\frac{di}{dt} = -Im \omega \sin(\omega t + \phi)$$

$$-L \cdot i_m \cdot \omega \cdot \sin(\omega t + \phi) + R \cdot i_m \cdot \cos(\omega t + \phi) = V_m \cos \omega t$$

< Same method as in the RC case >

$$-L \cdot i_m \cdot \omega \cdot (\sin \omega t \cos \phi + \cos \omega t \sin \phi) + R \cdot i_m \cdot (\cos \omega t \cos \phi - \sin \omega t \sin \phi) = V_m \cos \omega t$$

$$-L \cdot i_m \cdot \omega \cdot \cos \phi - R \cdot i_m \sin \phi = 0 \quad (1)$$

$$-L \cdot i_m \cdot \omega \cdot \sin \phi + R \cdot i_m \cdot \cos \phi = V_m \quad (2)$$

From (1): $-L\omega \cos \phi - R \sin \phi = 0$

$$\tan \phi = -\frac{\omega L}{R} \quad \phi = \arctan \frac{-\omega L}{R}$$

$$\phi = -\arctan \frac{\omega L}{R}$$

$$\phi = -\tan^{-1} \omega L/R$$

$$I_m = \frac{V_m}{R \cos \phi - \omega L \sin \phi}$$

If $\tan \phi = \frac{-\omega L}{R}$

Then: $\sin \phi = \frac{-\frac{\omega L}{R}}{\sqrt{1 + (\frac{\omega L}{R})^2}} \Rightarrow \sin \phi = -\frac{\omega L}{\sqrt{R^2 + \omega L^2}}$

$\cos \phi = \frac{1}{\sqrt{1 + (\frac{\omega L}{R})^2}} \Rightarrow \cos \phi = \frac{R}{\sqrt{R^2 + \omega L^2}}$

Hence:

$$I_m = \frac{V_m}{R \cdot \frac{R}{\sqrt{R^2 + \omega L^2}} - \omega L \cdot \frac{-\omega L}{\sqrt{R^2 + \omega L^2}}}$$

$$I_m = \frac{V_m}{\sqrt{R^2 + \omega L^2}}$$

Hence:

$$i_p(t) = \frac{V_m}{\sqrt{R^2 + \omega L^2}} \cdot \cos(\omega t - \arctan \frac{\omega L}{R})$$

Complete response.

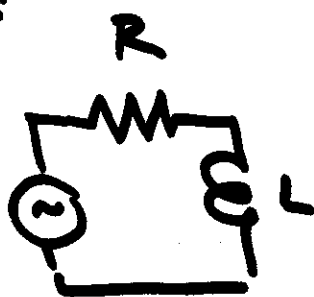
periodic steady state

lags behind $\cos \omega t$

$$i(t) = K e^{-R/Lt} + \frac{V_m}{\sqrt{R^2 + \omega L^2}} \cdot \cos(\omega t - \arctan \frac{\omega L}{R})$$

$\rightarrow 0$ as $t \rightarrow \infty$

Method (2):



$$v_s = V_m \cos \omega t$$

Find the steady-state solution
<or: the particular solution>

$$L \frac{di}{dt} + Ri = V_m \cos \omega t$$

Assume:

$$i(t) = I_m (\cos \omega t + \varphi)$$

Recall that we found by solving DE:

$$i_p(t) = \frac{V_m}{\sqrt{R^2 + (\omega L)^2}} \cdot \cos(\omega t - \arctan \frac{\omega L}{R})$$

<lengthy, but predictable,
process>

<Phasors> or. complex variables

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Euler's identity:

$$e^{jx} = \cos x + j \sin x$$

$$e^{-jx} = \cos x - j \sin x$$

$$\cos x = \operatorname{Re} \{ e^{jx} \}$$

$$\sin x = \operatorname{Im} \{ e^{jx} \}$$

Complex:
 $z = a + jb$

\uparrow
 $\operatorname{Re}\{z\}$

\uparrow
 $\operatorname{Im}\{z\}$

Our assumed solution:

$$i_p(t) = I_m \cos(\omega t + \varphi) \leftarrow$$

$$i_p(t) = I_m \operatorname{Re} \{ e^{j(\omega t + \varphi)} \}$$

$$= \operatorname{Re} \{ I_m e^{j(\omega t + \varphi)} \}$$

$i(t)$ has to satisfy DE:

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$$L \frac{di}{dt} + Ri = V_m \cos \omega t$$

Steady-state:
 $i(t) = \text{Re} \left\{ \text{Im} e^{j(\omega t + \varphi)} \right\}$

Hence:

$$\frac{di(t)}{dt} = \frac{d}{dt} \left\{ \text{Re} \left\{ \text{Im} e^{j(\omega t + \varphi)} \right\} \right\}$$

exchange:

$$\frac{di(t)}{dt} = \text{Re} \left\{ \frac{d}{dt} \left(\text{Im} e^{j(\omega t + \varphi)} \right) \right\}$$

$$= \text{Re} \left\{ \text{Im} j\omega e^{j(\omega t + \varphi)} \right\}$$

DE:

$$L \cdot \text{Re} \left\{ \text{Im} j\omega e^{j(\omega t + \varphi)} \right\} + R \cdot \text{Re} \left\{ \text{Im} e^{j(\omega t + \varphi)} \right\}$$

$$= \text{Re} \left\{ V_m e^{j\omega t} \right\} \cdot \text{Re} \left\{ \text{Im} e^{j(\omega t + \varphi)} \right\}$$

or: $\text{Re} \left\{ j\omega L \cdot \text{Im} e^{j(\omega t + \varphi)} + R \cdot \text{Im} e^{j(\omega t + \varphi)} \right\}$

$$= \text{Re} \left\{ V_m e^{j\omega t} \right\}$$

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$$\operatorname{Re} \{ (j\omega L \cdot I_m e^{j\varphi} + R \cdot I_m e^{j\varphi}) e^{j\omega t} \}$$

$$= \operatorname{Re} \{ V_m e^{j\omega t} \}$$

or:

$$\operatorname{Re} \{ [(j\omega L + R) \cdot I_m e^{j\varphi} - V_m] e^{j\omega t} \} = 0$$

$\forall t$ (For any t)

Only if:

$$(j\omega L + R) I_m e^{j\varphi} - V_m = 0$$

or

$$I_m e^{j\varphi} = \frac{V_m}{R + j\omega L}$$

resistor
inductance

$$I_m = \frac{V_m}{\sqrt{R^2 + (\omega L)^2}} \quad \varphi = -\arctan \frac{\omega L}{R}$$

And

$$i(t) = I_m \cos(\omega t + \varphi)$$

$$\frac{I_{\text{rms}}}{\sqrt{2}} e^{j\phi} \quad \leftarrow \text{phasor}$$

Magnitude of the phasor: $\frac{\text{Max of the sin}}{\sqrt{2}}$

< Recall \equiv root mean square value! >

angle of the phasor: angle of the sin.

Example: $x(t) = \sqrt{2} \cdot X_{\text{rms}} \cos(\omega t + \alpha)$

$$\Downarrow$$

$$\underline{X} = X_{\text{rms}} e^{j\alpha} \quad \leftarrow \text{phasor}$$

$$v(t) = 20 \sin(\omega t + \pi/3)$$

$$= 20 \cdot \cos(\omega t + \underbrace{\pi/3 - \pi/2})$$

$$\underline{V} = \frac{20}{\sqrt{2}} e^{-j\pi/6}$$

< Note: there would be nothing wrong in assuming $\underline{V} = V_{\text{max}} e^{j\phi}$ >

Phasors are a convenient way to calculate steady-state solutions for sinusoidal (periodic) inputs

Only valid for:

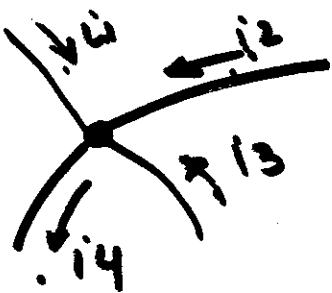
- Linear time-invariant systems

R, L, C : constants

- Sinusoidal sources
- periodic steady-state solutions
(particular solutions of DEs)

KCL and KVL revisited

$\sum \underline{I} = 0$ algebraic sum of all phasor-currents leaving (or entering) a node = 0

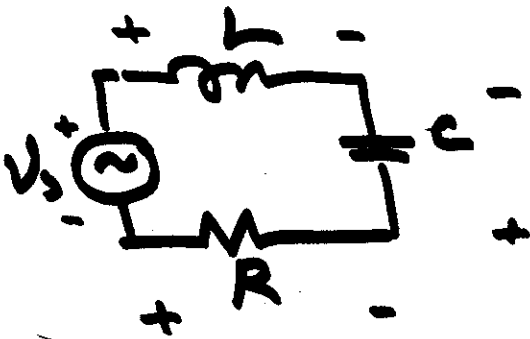


$$\underline{I}_1 + \underline{I}_2 + \underline{I}_3 - \underline{I}_4 = 0 \leftarrow$$

phasor corresponds to $i_i(t)$

Same for RVL

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$$\underline{V}_s - \underline{V}_L + \underline{V}_C + \underline{V}_R = 0$$

phasor associated
with $v_s(t) = V_{s_m} \cos \omega t$

Ohm's law:

$$v(t) = R \cdot i(t)$$

$$R_0 \{ \underline{V} e^{j\omega t} \} = R \cdot R_0 \{ \underline{I} e^{j\omega t} \}$$

$$\underline{V} = R \cdot \underline{I}$$

Recall: $\underline{V} = V_{rms} e^{j\varphi}$

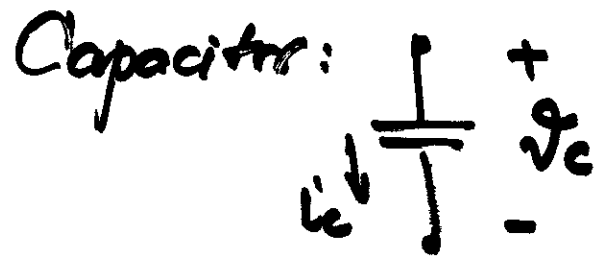
$$\rightarrow v(t) = \text{Re} \{ \sqrt{2} \cdot \underline{V} e^{j\omega t} \}$$

$$\downarrow$$

$$\sqrt{2} \cdot V_{rms} \cdot \underbrace{e^{j\varphi} e^{j\omega t}}$$

$$\cos(\omega t + \varphi) + j \sin(\omega t + \varphi)$$

$$v(t) = \sqrt{2} \cdot V_{rms} \cos(\omega t + \varphi)$$



$$\rightarrow i_c = C \frac{dv_c}{dt}$$

$$i_c = \text{Re} \{ \sqrt{2} \cdot \underline{I}_c \cdot e^{j\omega t} \} \leftarrow \text{Function of time}$$

$$i_c(t) = \sqrt{2} \cdot I_c \cos(\omega t + \phi)$$

$$\underline{I}_c = I_c \cdot e^{j\phi}$$

$$\text{Re} \{ \sqrt{2} \cdot \underline{I}_c \cdot e^{j\omega t} \} = C \cdot \frac{d}{dt} \{ \text{Re} \{ \sqrt{2} \cdot \underline{V}_c \cdot e^{j\omega t} \} \}$$

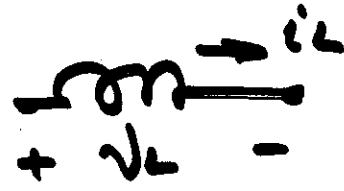
↖ exchange

$\sqrt{2}$ gets canceled:

$$\text{Re} \{ \underline{I}_c \cdot e^{j\omega t} - C \cdot \underline{V}_c \cdot j\omega \cdot e^{j\omega t} \} = 0$$

$$\underline{I}_c = j\omega C \cdot \underline{V}_c \quad ; \quad \underline{V}_c = \frac{\underline{I}_c}{j\omega C}$$

Inductor:



$$v_L = L \frac{di_L}{dt}$$

$$\text{Re} \left\{ \underline{v}_L \cdot e^{j\omega t} \right\} = L \frac{d}{dt} \text{Re} \left\{ \underline{i}_L \cdot e^{j\omega t} \right\} \\ \equiv \text{Re} \frac{d}{dt}$$

Hence:

$$\text{Re} \left\{ \underline{v}_L \cdot e^{j\omega t} - L \cdot j\omega \cdot \underline{i}_L \cdot e^{j\omega t} \right\} = 0$$

$$\underline{v}_L = j\omega L \cdot \underline{i}_L$$

General:

$$\underline{v} = \underline{z} \cdot \underline{i}$$

\underline{z} impedance
complex number

$$\underline{z} = R + jX$$

R resistance

X reactance

$$\underline{Y} = \frac{1}{\underline{z}}$$

\underline{Y} admittance

$$\underline{Y} = G + jB$$

G conductance

B susceptance

Resistor: $V = R \cdot I$

Capacitor: $V = \frac{1}{j\omega C} \cdot I$

impedance

$$Z = -j \frac{1}{\omega C}$$

reactance: $-\frac{1}{\omega C}$

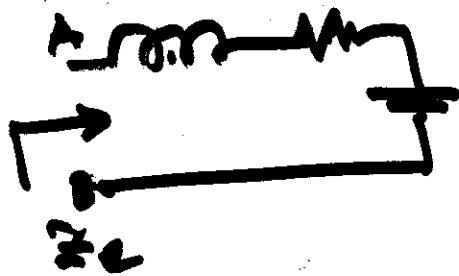
Inductor: $V = j\omega L \cdot I$

impedance

$$Z = j\omega L$$

reactance: ωL

Phasor calculus:



$$Z_e = j\omega L + R + \frac{1}{j\omega C}$$

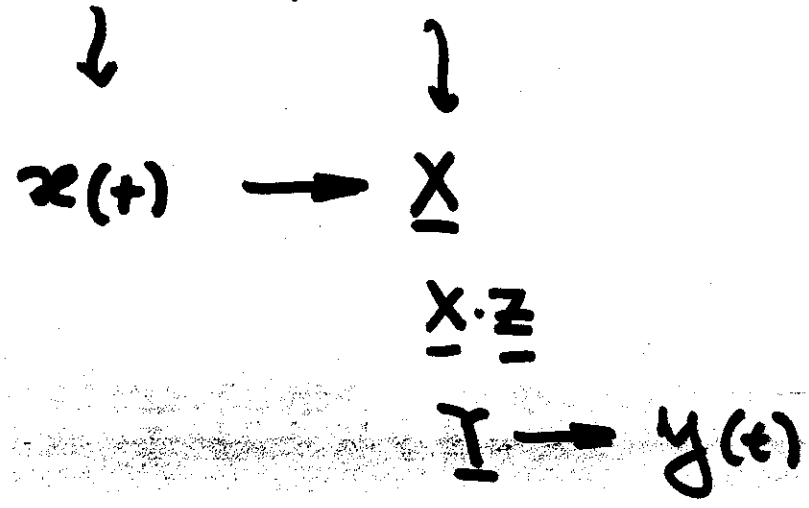
$$Z = R + j\left(\omega L - \frac{1}{\omega C}\right)$$

$$\underline{V} = \underline{Z}_e \cdot \underline{I}$$

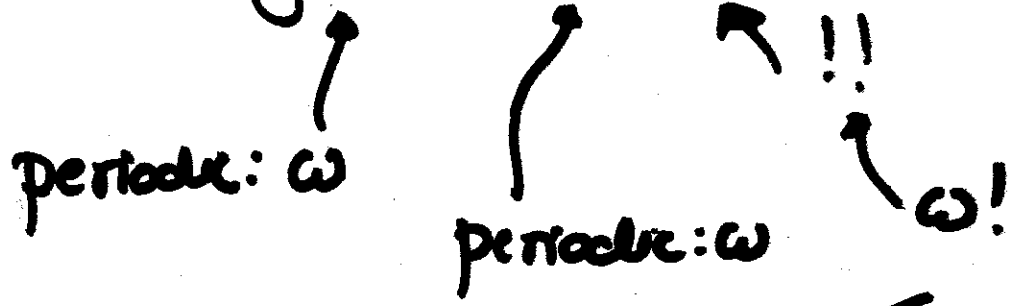
Resonance: $\omega_0 = \frac{1}{\sqrt{LC}}$

$$Z_{at \omega_0} = R!$$

Time - Phasors - Time transform



Incorrect: $y(t) = x(t) \cdot z(t)$



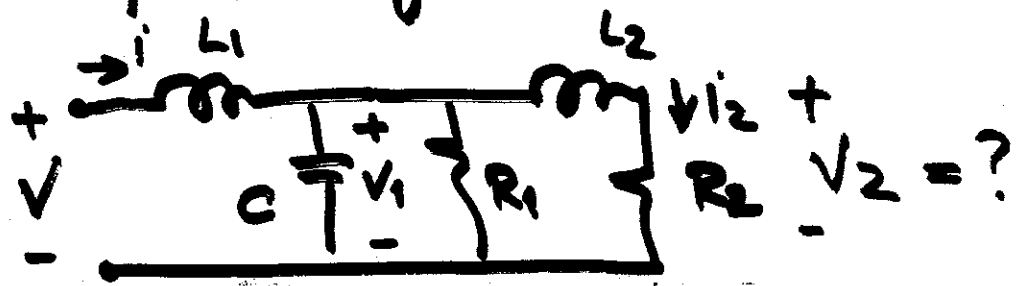
product of two periodic function with radian frequ $\omega \Rightarrow$ p.f. : 2ω

Recall:

$$\cos x \cdot \cos y \rightarrow \cos(x+y) + \cos(x-y)$$

$x=y:$

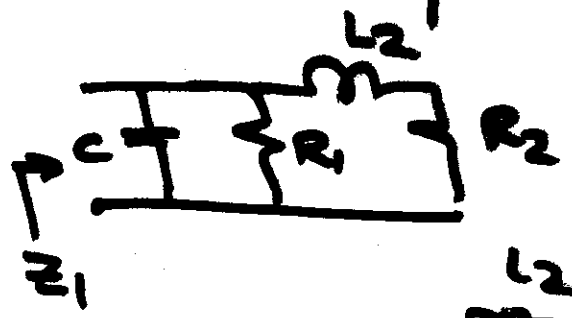
All the rules we learned when dealing with Resistor circuits, now apply to phasor quantities:



Assumption: \bar{V} ← sinusoidal input

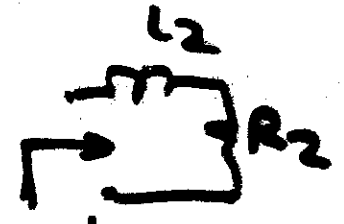
We are only interested in the steady-state solution:

$$\bar{Z} = j\omega L_1 + \bar{Z}_1$$



$$Y_1 = \frac{1}{\bar{Z}_1}$$

$$Y_1 = j\omega C + G_1 + \frac{1}{R_2 + j\omega L_2}$$



$$\bar{Z} = j\omega L_1 + \frac{1}{j\omega C + \frac{1}{R_1} + \frac{1}{R_2 + j\omega L_2}}$$

$$I = \frac{V}{Z_1}$$

$$\rightarrow V_1 = I \cdot Z_1$$

$$\rightarrow i_2 = \frac{V_1}{R_2 + j\omega L_2}$$

$$V_2 = R_2 i_2$$

Then:

$$V_2 = R_2 \cdot \frac{V_1}{R_2 + j\omega L_2}$$

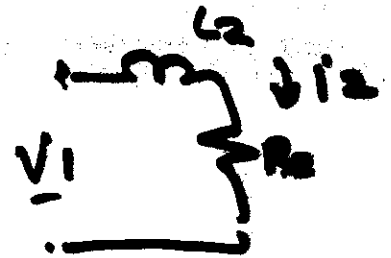
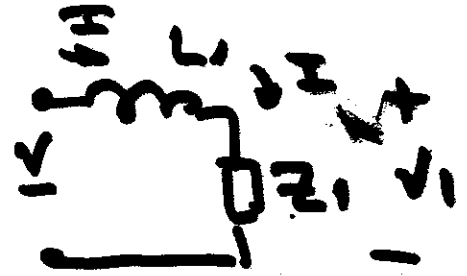
$$V_2 = \frac{R_2}{R_2 + j\omega L_2} \cdot Z_1 \cdot I$$

$$V_2 = \frac{R_2}{R_2 + j\omega L_2} \cdot Z_1 \cdot \frac{V}{j\omega L_1 + Z_1}$$

$$\frac{V_2}{V} = \frac{R_2}{R_2 + j\omega L_2} \cdot \frac{1}{j\omega L_1 Y_1 + 1}$$

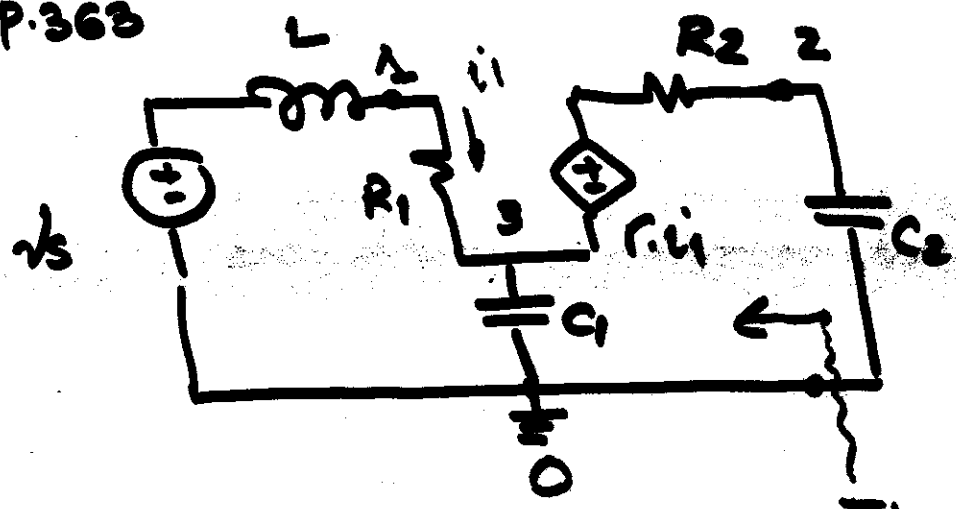
$$\frac{V_2}{V} = \frac{R_2}{R_2 + j\omega L_2} \cdot \frac{1}{j\omega L_1 \left(g\omega C + G_1 + \frac{1}{R_2 + j\omega L_2} \right) + 1}$$

$$\frac{V_2}{V} = \frac{R_2}{j\omega L_1 \left[(g\omega C + G_1)(R_2 + j\omega L_2) \right] + R_2 + j\omega L_2}$$



in terms of phasors, we can also write nodal mesh eq. or find Thevenin's eq. Norton's eq.

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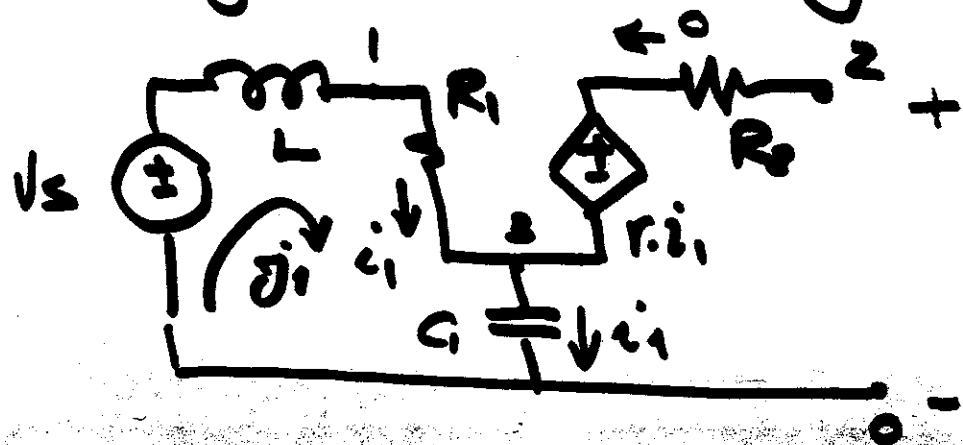


Find Thevenin's equivalent between 2 and 0:

1. Thevenin's voltage (phasor): V_{th}
2. Impedance: Z_{th}

Find the circuits from which you can determine V_{th} Z_{th}

1) Findy Thevenin's voltage.



2-0 : open circuited: $\underline{V_{Th}}$ (phase)

$$\underline{V_{Th}} = r \cdot \underline{i_1} + \frac{1}{j\omega C} \cdot \underline{I_1}$$

$$\underline{V_{Th}} = \left(r + \frac{1}{j\omega C} \right) \cdot \underline{I_1}$$

Mesh: $j\omega L \cdot \underline{I_1} + R_1 \cdot \underline{I_1} + \frac{1}{j\omega C} \cdot \underline{I_1} = \underline{V_s}$

$$\underline{I_1} = \frac{\underline{V_s}}{R_1 + j\omega L + \frac{1}{j\omega C}}$$

Note: $\underline{I_1} = \underline{I_1}$

$$\underline{I_1} = \frac{\underline{V_s}}{R_1 + j\omega L + \frac{1}{j\omega C}}$$

Hence:

$$\underline{V_{Th}} = \left(r + \frac{1}{j\omega C_1} \right) \cdot \frac{\underline{V_s}}{R_1 + j\omega L + \frac{1}{j\omega C_1}}$$

$$\underline{V_{Th}} = \frac{1 + j\omega r \cdot C_1}{1 - \omega^2 L C_1 + j\omega R_1 C_1} \cdot \underline{V_s}$$

We often assume $v_s(t) = V_s \cdot \cos(\omega t)$

$$\underline{V_s} = V_s \quad \begin{array}{l} \uparrow \\ \text{phase} = 0 \\ \text{real number} \end{array}$$

then:

$$\underline{V_{Th}} = \frac{1 + j\omega r \cdot C_1}{1 - \omega^2 L C_1 + j\omega R_1 C_1} \cdot V_s \quad \leftarrow **$$

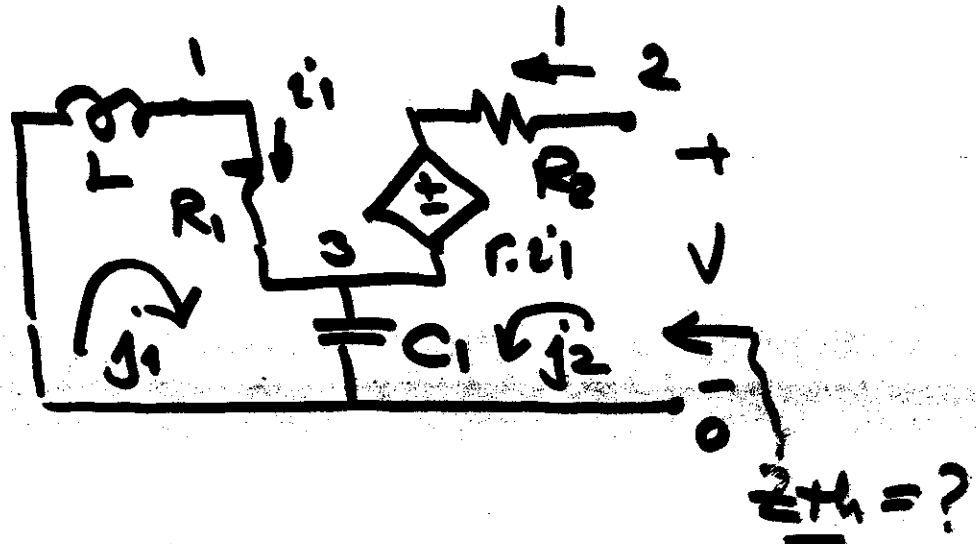
complex #

$$v_{Th}(t) = \text{Re} \left\{ \underline{V_{Th}} \cdot \sqrt{2} \cdot e^{j\omega t} \right\}$$

\uparrow if V_s^* was rms.

2. What is Z_{th}

Circuit:



Dependent source: hence we need to write equation to find V/i

imagine V to be a voltage source connect between 2 and 0:

Write mesh equations:

$$j\omega L \cdot j_1 + R_1 \cdot j_1 + \frac{1}{j\omega C_1} \cdot (j_1 + j_2) = 0$$

$$R_2 \cdot j_2 + r_i i_1 + \frac{1}{j\omega C_1} \cdot (j_2 + j_1) = \underline{V}$$

Note: $\underline{I}_1 = \underline{J}_1$

Then: $(R_1 + j\omega L + \frac{1}{j\omega C_1}) \underline{J}_1 + \frac{1}{j\omega C_1} \underline{J}_2 = 0$

$$(r + \frac{1}{j\omega C_1}) \cdot \underline{J}_1 + (R_2 + \frac{1}{j\omega C_1}) \underline{J}_2 = \underline{V}$$

Find \underline{J}_2

Then $\underline{I} = \underline{J}_2$

And $\frac{\underline{V}}{\underline{I}} = \underline{Z}_{th}$ ← complex #

From: $\underline{V}_{th} \leftarrow \underline{V}_{th}(t)$

$$\underline{Z}_{th} = R_{th} + j \cdot X_{th}$$

