

State variables: v ; v_g

Constitutive relationships:

$$i = 10^{-4} \frac{dv}{dt}$$

$$i_{1u} - i = 10^{-4} \frac{dv_g}{dt}$$

KCL:

$$\text{Hence, } i_{in} = 10^{-4} \left(\frac{dv}{dt} + \frac{dv_g}{dt} \right)$$

Two-loop equations: (KVL):

$$v_{in} - 100 \times i_{1u} - 100 \cdot (i_{1u} - i) - v_g = 0$$

$$v_{in} - 100 \times i_{in} - v - A \cdot v_g = 0$$

Hence:

$$200 \times i_{in} - 100 \times i + v_g = v_{in}$$

$$100 \times i_{in} + v + A \cdot v_g = v_{in}$$

(2)

$$\left. \begin{aligned} 10^{-2} \frac{dv}{dt} + 2 \times 10^{-2} \frac{dv_s}{dt} + v_g &= v_{in} \\ 10^{-2} \frac{dv}{dt} + 10^{-2} \frac{dv_s}{dt} + v + A v_g &= v_{in} \end{aligned} \right\}$$

Or.

$$\frac{dv}{dt} + 2 \times \frac{dv_s}{dt} + 100 \cdot v_g = 100 \times v_{in} \quad (1)$$

$$\frac{dv}{dt} + \frac{dv_s}{dt} + 100 \cdot v + 100 \times A \times v_g = 100 \times v_{in} \quad (2)$$

State equations.

After subtracting (2) from (1)

$$\frac{dv_s}{dt} + 100 \times (v_g - v) - 100 \cdot A \cdot v_g = 0$$

or:

$$\frac{dv_s}{dt} + 100(1-A) \cdot v_g - 100v = 0 \quad (3)$$

Hence: $v = \frac{1}{100} \times \frac{dv_s}{dt} + (1-A) \cdot v_g$

and

$$\frac{dv}{dt} = \frac{1}{100} \times \frac{d^2 v_s}{dt^2} + (1-A) \cdot \frac{dv_g}{dt}$$

Substituting info (4) gives:

$$\frac{1}{100} \times \frac{d^2 v_s}{dt^2} + (1-A) \cdot \frac{dv_s}{dt} + 2 \cdot \frac{dv_s}{dt} + 100 \cdot v_g = 100 \times v_{in}$$

or:

$$\frac{d^2 v_g}{dt^2} + 100(1-A) \cdot \frac{dv_g}{dt} + 200 \times \frac{dv_g}{dt} + 10^4 v_g = 10^4 v_{in} \quad (3)$$

Finally:

$$\frac{d^2 v_g}{dt^2} + 100(3-A) \cdot \frac{dv_g}{dt} + 10^4 v_g = 10^4 v_{in} \quad (4)$$

2nd order equation
terms of v_g .

Characteristic equation:

$$s^2 + 100(3-A)s + 10^4 = 0 \quad (5)$$

Zeros (natural frequencies of the circuit):

$$s_{1/2} = -50(3-A) \pm \sqrt{(50(3-A))^2 - 10^4}$$

$$= 50(A-3) \pm 50 \sqrt{(3A)^2 - 4}$$

$$= 50(A-3) \pm 50 \sqrt{A^2 - 6A + 5}$$

Circuit is stable if $\text{Re}\{s_{1/2}\} < 0$

Stable system: $0 < A < 3$ (approximate solution)

Consider the expression:

(4)

$$\frac{D}{s^2} = A - 3 \pm \sqrt{A^2 - 6A + 5}$$

$$\frac{D}{s^2} = A - 3 \pm \sqrt{(A-5)(A-1)}$$

There are four cases to consider:

- Overdamped: all zeros real

$$(A-5)(A-1) > 0$$

$A > 5$ (unstable)
 $A < 1$

→ Hence: $A < 1$

- Underdamped: complex-conjugate zeros

$$A < 5$$

$$A > 1$$

with stability condition:

$$\rightarrow 1 < A < 3$$

- Critically damped: two real zeros

$$A = 1$$

$$A = 5$$

with stability condition:

$$\rightarrow A = 5$$

- Underdamped: complex-conjugate (imaginary)

$$\rightarrow A = 3$$

Critically damped case: $A=1$

Equation (4) becomes:

$$\frac{d^2 v_g}{dt^2} + 100 \times 2 \times \frac{dv_g}{dt} + 10^4 v_g = 10^4 v_{in}$$

$$\frac{d^2 v_g}{dt^2} + 200 \times \frac{dv_g}{dt} + 10^4 v_g = 10^4 v_{in}$$

characteristic equation:

$$s^2 + 200s + 10^4 = 0$$

$$s/2 = 100$$

$v_g = (k_1 + k_2 t) e^{-100t} u(t) + \text{particular solution that depends on } v_{in}.$

$$v_{out} = A \cdot v_g$$

For $A=1$: $v_{out} = v_g$

Addendum:

6

Matrix form of the state equation:

From (1) and (2):

$$\begin{pmatrix} 1 & 2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} dv/dt \\ di_g/dt \end{pmatrix} + \begin{pmatrix} 0 & 1 \\ 100 & 100A \end{pmatrix} \begin{pmatrix} v \\ i_g \end{pmatrix} = 100 \times \begin{pmatrix} 1 \\ 1 \end{pmatrix} v_{in}$$

$$\text{Since: } \begin{pmatrix} 1 & 2 \\ 1 & 1 \end{pmatrix}^{-1} = \frac{1}{1-2} \begin{pmatrix} 1 & -2 \\ -1 & 1 \end{pmatrix} \\ = \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix}$$

$$\begin{pmatrix} dv/dt \\ di_g/dt \end{pmatrix} + \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} \times 100 \times \begin{pmatrix} 0 & 1 \\ 1 & A \end{pmatrix} \begin{pmatrix} v \\ i_g \end{pmatrix} = 100 \times \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} v_{in}$$

$$\text{Let } x = \begin{pmatrix} dv/dt \\ di_g/dt \end{pmatrix}$$

$$\frac{dx}{dt} + 100 \begin{pmatrix} 2 & -1+2A \\ -1 & 1-A \end{pmatrix} \cdot x = 100 \begin{pmatrix} 1 \\ 0 \end{pmatrix} v_{in}$$

$$\det(sI + A) = 0$$

$$s \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + 100 \begin{pmatrix} 2 & -1+2A \\ -1 & 1-A \end{pmatrix} = 0$$

$$\det \begin{pmatrix} s+200 & 100(2A-1) \\ -100 & s+100(1-A) \end{pmatrix} = 0$$

$$(s+200)(s+100(1-A)) + 10^4 \cdot (2A-1) = 0$$

$$s^2 + 200s + 100s(1-A) + 2 \times 10^4(1-A) + 10^4(2A-1) = 0$$

Or, finally;

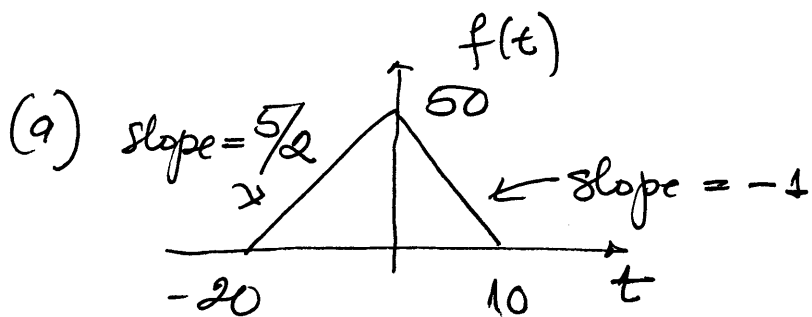
$$s^2 + 100(3-A)s + 10^4 = 0$$

Equivalent to the
character equation (5).

7

2

8



$$f(t) = \frac{5}{2} \cdot (t+20) [u(t+20) - u(t)] - 5(t-10) [u(t) - u(t-10)]$$

$$f(t) = \frac{5}{2} \cdot (t+20) u(t+20) - \frac{5}{2} \cdot (t+20) u(t) - 5(t-10) u(t) + 5(t-10) u(t-10)$$

$$f(t) = \frac{5}{2} (t+20) u(t+20) - \frac{5}{2} t u(t) - \cancel{50} u(t) - 5t u(t) + \cancel{50} u(t) + 5(t-10) u(t-10)$$

$$f(t) = \frac{5}{2} \cdot (t+20) u(t+20) - \frac{15}{2} t u(t) + 5(t-10) u(t-10)$$

Laplace transform:

$$F(s) = \frac{5}{2} \times \frac{1}{s^2} \times e^{20s} - \frac{15}{2} \cdot \frac{1}{s^2} + \frac{5}{s^2} e^{-10s}$$

9

$$(b) F(s) = \frac{4s^2 + 7s + 1}{s(s+1)^2}$$

Partial fractions expansion leads to:

$$F(s) = \frac{k_0}{s} + \frac{k_1}{(s+1)^2} + \frac{k_2}{s+1}$$

Calculati of residues:

$$\rightarrow k_0 = \lim_{s \rightarrow 0} s \cdot F(s)$$

$$\begin{aligned} & s \rightarrow 0 \\ & = \lim_{s \rightarrow 0} \frac{4s^2 + 7s + 1}{(s+1)^2} \end{aligned}$$

$$k_0 = 1$$

$$\rightarrow k_1 = \lim_{s \rightarrow -1} (s+1)^2 \cdot F(s)$$

$$= \lim_{s \rightarrow -1} \frac{4s^2 + 7s + 1}{s}$$

$$s \rightarrow -1$$

$$= \frac{4 \times (-1)^2 + 7(-1) + 1}{-1}$$

$$k_1 = 2$$

$$\rightarrow K_2 = \lim_{s \rightarrow -1} \frac{d}{ds} \cdot (s+1)^2 \cdot F(s)$$

$$= \lim_{s \rightarrow -1} \frac{d}{ds} \cdot \frac{4s^2 + 7s + 1}{s}$$

$$= \lim_{s \rightarrow -1} \frac{(8s+7)s - (4s^2 + 7s + 1)}{1}$$

$$= \lim_{s \rightarrow -1} (4s^2 - 1)$$

$$K_2 = 3$$

Answer:

$$F(s) = \frac{1}{s} + \frac{2}{(s+1)^2} + \frac{3}{s+1}$$

inverse Laplace transform:

$$f(t) = u(t) + 2te^{-t}u(t) + 3e^{-t}u(t)$$

or

$$f(t) = (1 + 2te^{-t} + 3e^{-t})u(t)$$

Initial-value Theorem:

$$\lim_{s \rightarrow \infty} s \cdot F(s) = \lim_{t \rightarrow 0^+} f(t)$$

$$\lim_{s \rightarrow \infty} s \cdot F(s) = \lim_{s \rightarrow \infty} \frac{4s^2 + 7s + 1}{(s+1)^2}$$

$$\text{Note that } f(0) = 4 \quad \checkmark$$

Final Value Theorem:

$$\lim_{s \rightarrow 0} s \cdot F(s) = \lim_{t \rightarrow \infty} f(t)$$

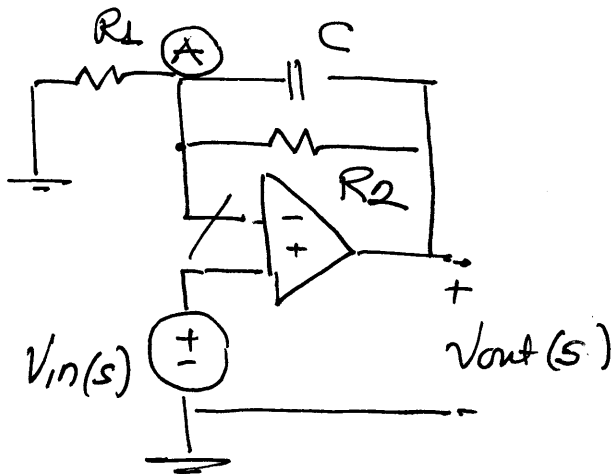
$$\lim_{s \rightarrow 0} s \cdot F(s) = \lim_{s \rightarrow 0} \frac{4s^2 + 7s + 1}{(s+1)^2}$$

$$= 1$$

$$\text{Again: } f(\infty) = 1 \quad \checkmark$$

#3

12



$$V_A = V_{in}(s)$$

Nodal equation in "s" domain:

$$\frac{V_{in}(s)}{R_1} + \frac{V_{in}(s) - V_{out}(s)}{R_2} + \frac{V_{in}(s) - V_{out}(s)}{1/sC} = 0$$

Hence:

$$V_{in}(s) \cdot \left(\frac{1}{R_1} + \frac{1}{R_2} + Cs \right) = V_{out}(s) \cdot \left(\frac{1}{R_2} + Cs \right)$$

Transfer function is:

$$H(s) = \frac{V_{out}(s)}{V_{in}(s)}$$

$$H(s) = \frac{\frac{1}{R_1} + \frac{1}{R_2} + Cs}{\frac{1}{R_2} + Cs}$$

$$H(s) = \frac{s + \frac{1}{C} \left(\frac{1}{R_1} + \frac{1}{R_2} \right)}{s + \frac{1}{CR_2}}$$

$$If H(s) = \frac{s+4}{s+2}$$

By comparison: $\frac{1}{C} \cdot (\frac{1}{R_1} + \frac{1}{R_2}) = 4$ (1)

$$\frac{1}{CR_2} = 2 \quad (2)$$

Since $C = 1 \mu F$ $R_2 = \frac{1}{2C}$ From (2)

$$R_2 = 500 k\Omega$$

From (1): $\frac{1}{CR_1} = 2$; $R_1 = 500 k\Omega$

Step response of the circuit:

$$H(s) = \frac{s+4}{s+2}$$

$$V_{out}(t) = \mathcal{L}^{-1} \{ H(s) \cdot V_{in}(s) \}$$

$$V_{in}(s) = 1/s \text{ (Step funct)}$$

$$V_{out}(t) = \mathcal{L}^{-1} \left\{ \frac{s+4}{s(s+2)} \right\}$$

Since: $\frac{s+4}{s(s+2)} = \frac{A}{s} + \frac{B}{s+2}$

$$= \frac{2}{s} - \frac{1}{s+2}$$

$$V_{out}(t) = (2 - e^{-2t}) u(t)$$

$$A = \lim_{s \rightarrow 0} s \cdot \frac{s+4}{s(s+2)}$$

$$A = 2$$

$$B = \lim_{s \rightarrow -2} (s+2) \cdot \frac{s+4}{s(s+2)}$$

$$s \rightarrow -2$$

$$B = -1$$

#4

$$H(s) = \frac{2s+4}{s^2+5s+6}$$

14

Zeros and Poles:

$$\text{Zeros (2): } s_1 = \infty \\ s_2 = -2$$

$$\text{Poles (2): } s^2+5s+6=0 \quad s_1 = -2 \\ (s+2)(s+3)=0 \quad s_2 = -3$$

$$V_{in}(t) = 4 \cos(2t + \pi/4) \quad \omega = 2 \text{ rad/s} \\ \varphi = \pi/4 \text{ rad}$$

$$H(zj) = \frac{2(zj+4)}{(zj)^2+5zj+6} \\ = \frac{4+4j}{-4+10j+6} \\ = 2 \cdot \frac{2+2j}{2+5j} \quad ; \quad H(zj) = \frac{2+2j}{1+5j}$$

$$V_{out}(j\omega) = H(j\omega) \times V_{in}(j\omega) \quad \omega = 2$$

$$V_{out}(j\omega) = \frac{2+2j}{1+5j} \times 4 \times e^{j\pi/4} \\ = \frac{2\sqrt{2}}{\sqrt{26}} \cdot \frac{e^{j\pi/4}}{e^{j \arctan 5}} \times 4 \times e^{j\pi/4} \\ = \frac{8}{\sqrt{13}} e^{j(\pi/2 - \arctan 5)}$$

$$\text{Hence, } V_{out}(t) = \frac{8}{\sqrt{13}} \cdot \cos(2t + \pi/2 - \arctan 5)$$

Or, equivalently:

$$V_{out}(t) = -\frac{8}{\sqrt{13}} \sin(2t - \arctan 5)$$

(15)