

ENSC 460/895: SPECIAL TOPICS:  
THEORY, ANALYSIS, AND SIMULATION  
OF NONLINEAR CIRCUITS

CHARACTERIZING MULTIPLE DC OPERATING POINTS  
OF CIRCUITS USING DIFFERENT SPICE FLAVOURS

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FINAL PROJECT

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## Abstract

An investigation into the performance of the numerical engines of four Spice-derived circuit simulators is presented. Spice3f5, HSpice, PSpice, and NGSpice were used to solve for the multiple DC operating points of four circuits known to exhibit such characteristics: the 741 opamp input stage, the opamp feedback circuit with good common mode rejection in BJT and MOSFET implementations, the hybrid voltage reference, and Chua's circuit with nine distinct operating points. The simulators encountered convergence problems during the simulations and well known convergence techniques were employed towards a solution. We have shown that the simulators perform well and the convergence techniques are helpful for the tougher circuits.

# 1 Introduction

A great number of circuit simulators are available for use by circuit designers. While most of the commercial grade simulators are based off of Berkeley's Spice circuit simulator, they all have been improved to deal with convergence issues and to support additional compact models, to name a few. As the available distributions vary widely in price from free to several thousand dollars, the frugal engineer should ask questions about how the simulators compare, and which will provide best performance versus total cost. This paper discusses an investigation into the performance of the equation solving engines of four selected simulators: Spice3f5, HSpice, PSpice, and NGSpice.

The most difficult part of a circuit simulation is determining the prerequisite DC operating points as problems in convergence may disrupt the simulation. For this reason, this paper will focus on solving for the DC operating points of a collection of four circuits known for their difficulty and convergence issues. First, the simulators and transistor models are characterized in Sections 2 and 3, respectively. The four circuits are presented with their simulation results in Section 4. Next, Section 5 provides a discussion on the results, and conclusions are drawn after that. The appendices include descriptions of the circuits and complete listings of the results.

## 2 Characterization of Simulators

All of the selected simulators are based on the original Berkeley Spice simulator and so they share many similar features. For example, they all employ a similar syntax to describe circuit connections, use a Newton-Raphson method to numerically solve circuit equations, and provide similar continuation methods when convergence problems arise in simulating difficult circuits. But, since simulators are developed independently, unique features have also been added. Each simulator provides different implementation, optimization, and control of the numerical integration algorithms, which can affect the simulations and so it is important to discuss the differences between each simulator.

### 2.1 Simulators

In this section, each flavour of Spice used and the features that set them apart are discussed.

#### 2.1.1 Berkeley Spice3f5

The Spice circuit simulator was developed at the Electronics Research Laboratory of the University of California, Berkeley, by Larry Nagel and Donald Paderson [1]. The early version of Spice used a method for nodal analysis which limited the simulator as ideal voltage sources and inductors could not be simulated. Later versions, including Spice3f5, used a modified nodal analysis to avoid these problems. Modified nodal analysis also generates a set of equations that are easier to implement in a computer, resulting in a substantial performance improvement; however, it does also result in a larger system of equations. Table 1 compares the required steps for both the standard nodal analysis and the modified nodal analysis for a system of  $n$  nodes and  $m$  voltage sources.

**Table 1: Comparison of Nodal Analysis Methods**

<i>Standard Nodal Analysis [2]</i>	<i>Modified Nodal Analysis [3]</i>
<ol style="list-style-type: none"> <li>1. Select a reference node (ground).</li> <li>2. Name the remaining <math>n-1</math> nodes and label a current through each passive element and each current source.</li> <li>3. Apply Kirchoff's current law to each node not connected to a voltage source.</li> <li>4. Solve the resultant system of <math>n-1-m</math> unknowns voltages.</li> </ol>	<ol style="list-style-type: none"> <li>1. Select a reference node (ground).</li> <li>2. Name the remaining <math>n-1</math> nodes and label a current through each current source.</li> <li>3. Assign a name to the current through each voltage source.</li> <li>4. Apply Kirchoff's current law to each node.</li> <li>5. Write a voltage equation for each voltage source.</li> <li>6. Solve the system of <math>n-1</math> voltages.</li> </ol>

Spice3f5 also provides a handful of pre-packaged compact models for devices like MOSFETs, BJTs, diodes, capacitors, resistors, and transmission lines; however, only a limited number of models are supported and the only way to include further compact models is to directly modify the source code and recompile the simulator. This is a result of lack of further development to Berkeley Spice owing to the restrictive license it is released with.

### 2.1.2 HSpice

HSpice is widely considered within the engineering industry as one of the top commercial circuit simulation packages available, offering a range of features and simulation support for RF, IC, and signal integrity analysis. It also boasts a well developed GUI and an ability to simulate up to 100,000 transistors simultaneously.

HSpice also provides a number of `.OPTION` statements for control and optimization of the numerical computation algorithms. Of particular interest to this investigation are those that control the convergence and accuracy of the numerical solvers. The options unique to HSpice are listed in Table 2.

**Table 2: HSpice Unique Options**

<i>Option</i>	<i>Description</i>
CONVERGE	Invokes different convergence techniques
DCFOR0	Sets the number of iterations calculated after convergence in the steady state
DCHOLD	Specifies the number of iterations to hold nodes at .NODESET
DCSTEP	Convert DC model and element capacitors to a conductance to enhance DC convergence properties
DV	Max iteration to iteration voltage change for all circuit nodes in DC and transient analysis
GMAX	Conductance in parallel with current sources used for .IC and .NODESET statements
GMINDC	Conductance in parallel with pn junctions and all MOSFET nodes, use for DC analysis
GRAMP	Conductance range over which GRAMP is swept
GSHUNT	Conductance added from each node to ground
NEWTOL	Calculates one more iteration past convergence for every DC solution and time point circuit solution calculated

Like Spice, HSpice is also pre-packaged with a number of compact models for fundamental devices, and for each device there are a number of models of varying complexity. The more sophisticated models are MOSFET models, owing to the fact that the majority of IC applications use MOSFET rather than BJT devices. Plus, more models can be readily included into HSpice so that new or custom devices can be supported.

### 2.1.3 PSpice

As opposed to some other Spice flavours, PSpice provides a wide-ranging GUI environment for simulating circuits containing analog devices. Circuit designs can be captured schematically using the extensive model libraries. The capture ability converts the schematic into the familiar Spice text-based circuit descriptions, which could be edited by the user if so desired. Built-in GUI modules for editing stimuli and viewing output waveforms are also included. Because of its GUI ability, PSpice is a leading simulator standard for the MS Windows platform.

In general, however, PSpice has a weaker numerical engine than the other three simulators in this study. Convergence issues are more rampant with PSpice and greater numbers of convergence iterations are to be expected. The kinds of analyses which can be performed in PSpice are also limited. For this study, a student license for PSpice was used, restricting all simulated circuits to a maximum of ten transistors. Hence, only two of the four circuits (the hybrid voltage reference and Chua's nine distinct operating point circuits) could be tested.

## 2.1.4 NGSpice

NGSpice is a new open source simulator based on Spice, Cider, and Xspice; it seeks to become a full-feature mixed-level/mixed-signal circuit simulator. Currently this package is still in an early stage of development but as NGSpice is based on pre-existing code it already has a sufficient functionality for inclusion in this study. As well, its developers claim to have improved upon the original Berkeley Spice through bug fixes, improvements to the numerical computation algorithms, and the inclusion of newer compact models.

Another reason to include this simulator is that it may one day mature into a robust, practical, and competitive simulator if a community of open source developers and users grow around it. Berkeley Spice suffers in this regard as it is released under a restrictive license, and therefore, its continued development by the open source community never materialized.

Like the other circuit simulators, NGSpice also provides a number of `.OPTION` statements to control the numerical solving algorithms. Since NGSpice is based on Berkeley Spice, the options and models in NGSpice are identical to Berkeley Spice; however, NGSpice does not implement the `ITL3` and `ITL5` options.

## 2.2 Newton-Raphson Method

The Newton-Raphson method is a fairly simple yet powerful method for finding the roots of a real-valued function. As long as the initial guess of the solution lies close to the actual root, and the root of interest has a multiplicity of one, then this algorithm will converge quadratically. If the root has a multiplicity greater than one, the algorithm will converge linearly, except for some abnormal cases.

After an initial guess is made the algorithm will calculate the tangent of the function at that point. By extrapolating the tangent and determining where it crosses the independent axis the next guess of the solution can be found. This process is then iterated until certain convergence conditions are met, namely that the percentage change in the solution between two iterations is less than some predetermined value.

## 2.3 General Convergence Techniques

When dealing with problem circuits there are a number of tricks and techniques that can be employed to coax the numerical solvers into convergence. Some of the techniques lie in tweaking the operating parameters of the numerical solving algorithms, others involve slight modifications to the circuit to reduce the complexity of problem nodes, while even others employ alternate numerical methods outright. The following are some popular techniques.

### 2.3.1 Extra Iterations

All numerical algorithms include a limit on the number of iterations to perform; some circuits may simply not have a solution and so the algorithms will run infinitum. For some cases, the

convergence point may be just a few iterations away or the circuit may have the necessary conditions to cause slow convergence for the numerical algorithms. In these cases convergence will eventually occur given sufficient iterations.

### 2.3.2 Initial Guesses

One of the conditions for quadratic convergence in the Newton-Raphson algorithm is that an initial guess must lie close to the actual solution. While this may be trivial for simple one solution circuits, it is an important consideration when simulating circuits with multiple operating points. The Newton-Raphson algorithm will provide its own guesses but can only find one solution during each run. By providing guesses as to where other solutions may lie, the user can coax the simulators to converge to the other solutions of interest.

### 2.3.3 Homotopy Methods

An alternative is to use methods such as parameter variation, known as homotopy. By embedding a parameter, or varying an existing one such as the power supply voltage, the circuit can be reduced to a simpler solution that is easily solved. Then by iteratively varying this parameter and using the previous solution as an initial guess for the next, it is possible to eventually solve the original problem. The simulators evaluated in this paper all automatically invoke some form of homotopy methods when confronted with a difficult circuit to simulate. The methods used are GMIN stepping, source stepping, and a type of natural parameter homotopy.

GMIN stepping places shunt resistors from each node to ground. For a sufficiently large shunting conductance the circuit problem will degenerate to a simpler and solvable problem. By then iteratively reducing the shunting conductance and solving the circuit problem with the previous solution used as an initial conductance, a solution for the original circuit may be found. Source stepping is similar except all voltage and current sources are initially set to zero. They are then iteratively brought to full power with each solution used as an initial guess for the subsequent iteration, leading to a full circuit solution.

While these methods are quite powerful they will still fail in certain cases, such as at a branch, or bifurcation, in the path followed by the homotopy method. Bifurcation points arise as the circuit is able to produce multiple solutions. In these cases a more robust method is required to generate a solution, or the simulator must be tricked into solving for one solution only.

### 2.3.4 Circuit Modifications

Another class of options available to the designer when dealing with difficult circuits is to modify the circuit in a manner that will produce useful results comparable to the original problem. This may include such things as shunting problem nodes to ground through a sufficiently large resistance, turning various elements on/off, and building two-port equivalent models of selected sections. Often times the modified circuit may be useful in generating a solution that can be used as an initial condition in simulating the original problem circuit.

The problem may also lie in the device models chosen, including MOSFETs, BJTs, and ICs. Many ideal models may possess regions of discontinuity or “infinities” that are very unfriendly to the circuit simulator. Often the simulator will fail inexplicitly at various points due to these discontinuities in the models and can be avoided by either swapping for an alternate model or by adjusting the simulation sweep points to jump over trouble spots.

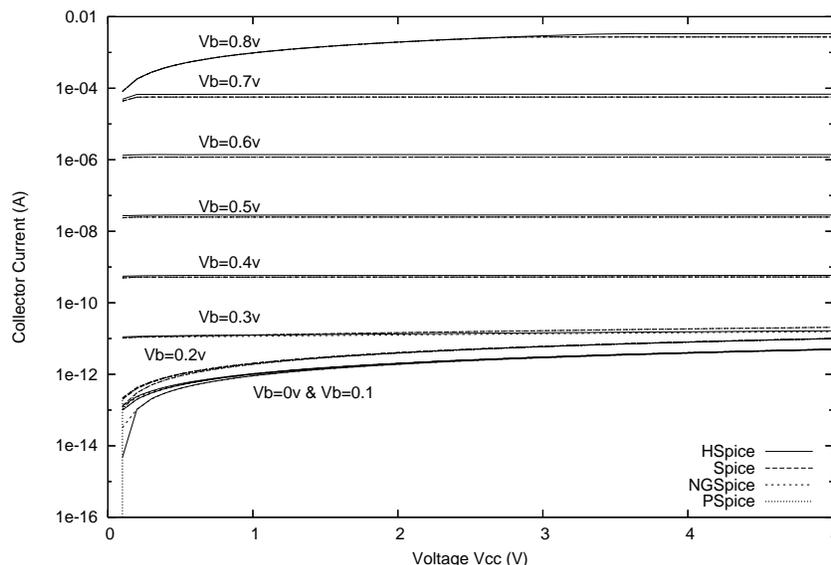
The designer must take care in evaluating the appropriate modifications and interpreting their results as they may be wildly different than expected. As is readily the case, a simulation tool is most useful when the solution is already known to the designer.

### 3 Characterization of Transistor Models

The transistor device is modeled by adjusting various real world parameters from their nonlinear equations. As such, the range of models vary from the very simple, often ideal but less accurate, to the very complicated, but more practical. To frustrate even further, the various Spice flavours may implement models differently. In this experiment, three standard models of the bipolar junction transistor (BJT) and the metal-oxide semiconductor field effect transistor (MOSFET) are used: the Ebers-Moll BJT, Shichman-Hodges MOSFET, and BSIM3 MOSFET. This section characterizes and compares their behaviour in Spice.

#### 3.1 Ebers-Moll BJT Model

The Ebers-Moll model is the most basic fundamental and ideal BJT model and is appropriately numbered as Level 1 in the simulators. Figure 1 characterizes its behaviour.

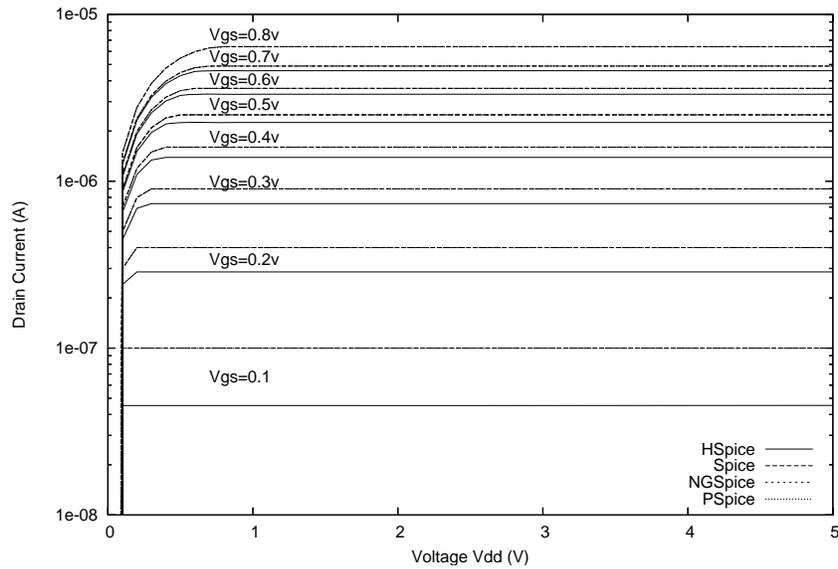


**Figure 1: Ebers-Moll BJT Model Characterization**

The characterization is fairly consistent across the four simulators. The notable difference is in the “elbow,” at the transistor turn-on voltage, when the base voltage,  $V_b$ , is 0.2V or less.

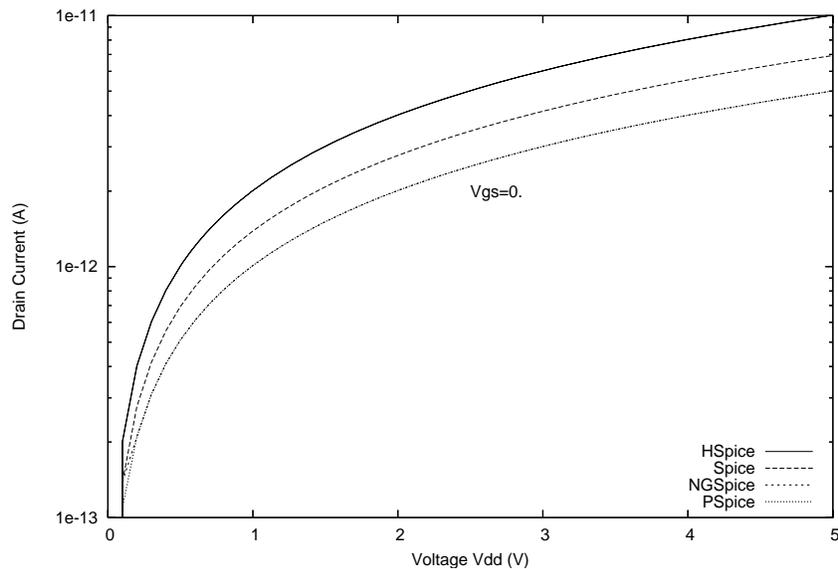
### 3.2 Shichman-Hodges MOSFET Model

The Shichman-Hodges model is also the most basic of the MOSFET and is also numbered as Level 1. Its simulator characteristics are shown in Figure 2.



**Figure 2: Shichman-Hodges MOSFET Model Characterization**

Figure 3 shows the model characterization for the region where the gate-source voltage,  $V_{gs} = 0$ .

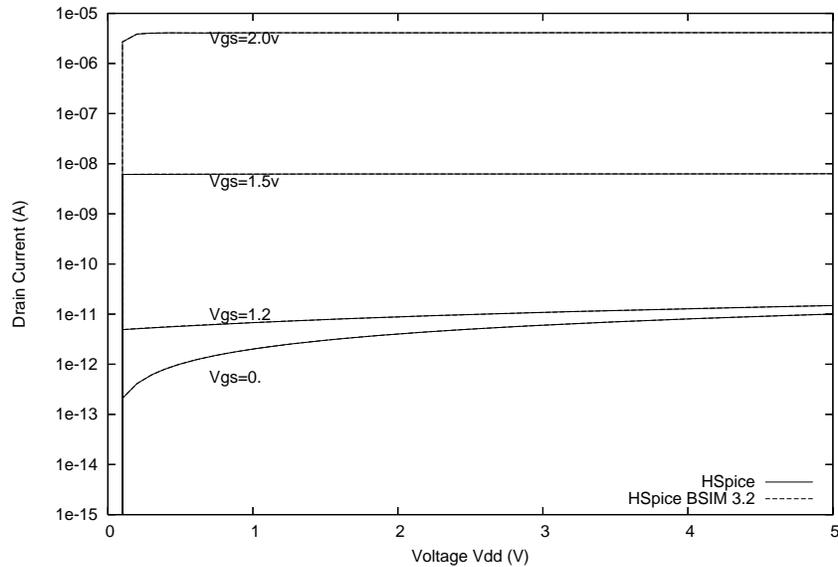


**Figure 3: Shichman-Hodges MOSFET Model Characterization**

For this model, the characterization shows that the implementations carried in the different Spice flavours can deviate quite a bit from each other.

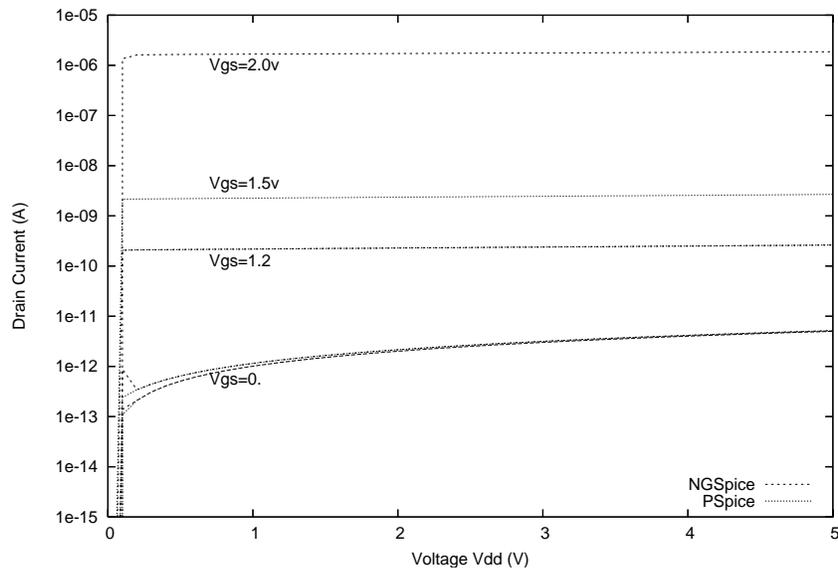
### 3.3 BSIM3 MOSFET Model

The BSIM3 model was developed at Berkeley and has become an industry standard for modeling the MOSFET. Spice3f5 includes a fairly obsolete version of the BSIM3 model and so that flavour is not considered for this MOSFET model. HSpice provides compatibility with past versions of the BSIM3 and Figure 4 shows the characteristics of the two most recent, versions 3.3 (default) and 3.2.



**Figure 4: HSpice BSIM3 Default v3.3 and v3.2 MOSFET Model Characterization**

The PSpice and NGSpice model characteristics are shown in Figure 5.



**Figure 5: NGSpice and PSpice BSIM3 MOSFT Model Characterization**



The performance of the 741 opamp input stage is susceptible to the Early voltage effect on transistors  $Q_5$  and  $Q_6$ , which we manually model by very large resistors  $RVA_5$  and  $RVA_6$ , in parallel between the collectors and emitters of the two transistors, respectively. As suggested in [5], it is a worthwhile experiment to see how great the resistances could be increased to until the circuit behaviour is unexpected.

The circuit was simulated with the Ebers-Moll BJT model at various  $RVA$  resistances, with  $RVA_5 = RVA_6$ . A negligible input signal  $v_{iNEG}$  was applied at the negative terminal, with the positive held at zero. The output was initially conditioned to 6.0V. The operating points we obtained are summarized in Table 3.

**Table 3: 741 Opamp Input Stage Operating Points**

$RVA$ ( $\Omega$ )	Spice		HSpice		NGSpice	
	Output (V)	Iterations	Output (V)	Iterations	Output (V)	Iterations
1e12	-5.70	28	-5.81	51	-5.88	30
1e14	-6.34	28	-4.03	52	-6.46	29
1e16	-6.18	42	-4.01	52	-5.82	41
1e17	-5.99	83	-4.01	52	-6.18	87
1e18	-	-	-4.01	52	-6.81	979

At  $RVA = 1e18\Omega$  and above, Spice fails to converge to a solution. While NGSpice does converge at this point, it requires nearly a thousand iterations to do so, and only after GMIN stepping has failed and source stepping has completed 32 iterations. HSpice does converge to an output above  $1e18\Omega$  even without use of GMIN stepping; however, given the exact match of the operating points found, and referring to the varying results from Spice and NGSpice, it is highly unlikely that these results can be confirmed. In general then,  $1e17\Omega$  is the largest  $RVA$  for nominal operation of the circuit, when the resistance models the Early effect.

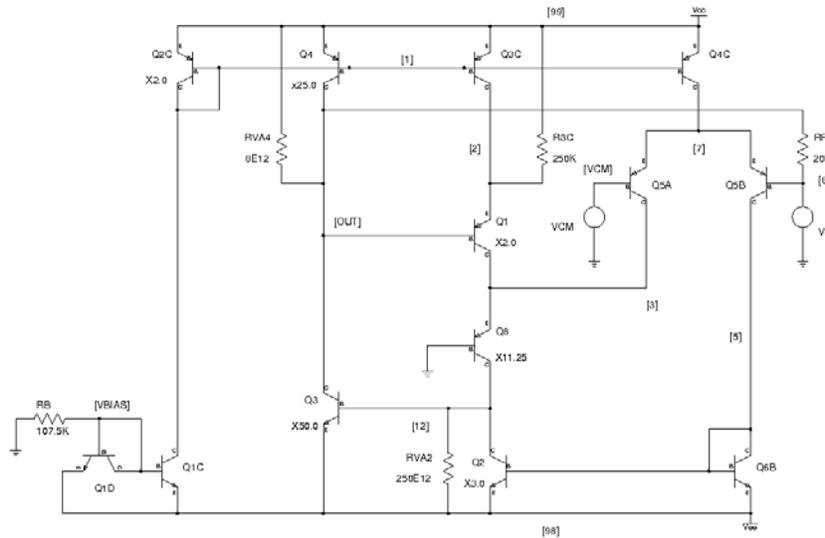
## 4.2 Feedback Circuit with Good Common Mode Rejection

The opamp feedback circuit with good common mode rejection was originally presented by Banu *et al.* using MOSFETs [6], and later adapted into a BJT implementation by Melville *et al.* [5]. The circuit was also simplified to focus solely on the common mode feedback structure; the differential inputs were assumed to be null and the differential common mode feedback was collapsed into a single-ended feedback structure. Section 4.2.1 illustrates this circuit. For adequate comparison the original MOSFET version was simplified and reduced to the same architecture as the BJT implementation and is detailed in Section 4.2.2. As BJTs and MOSFETs exhibit similar behaviour we can expect similar behaviour between the BJT and MOSFET implementations of the common mode feedback circuit.

### 4.2.1 BJT Implementation

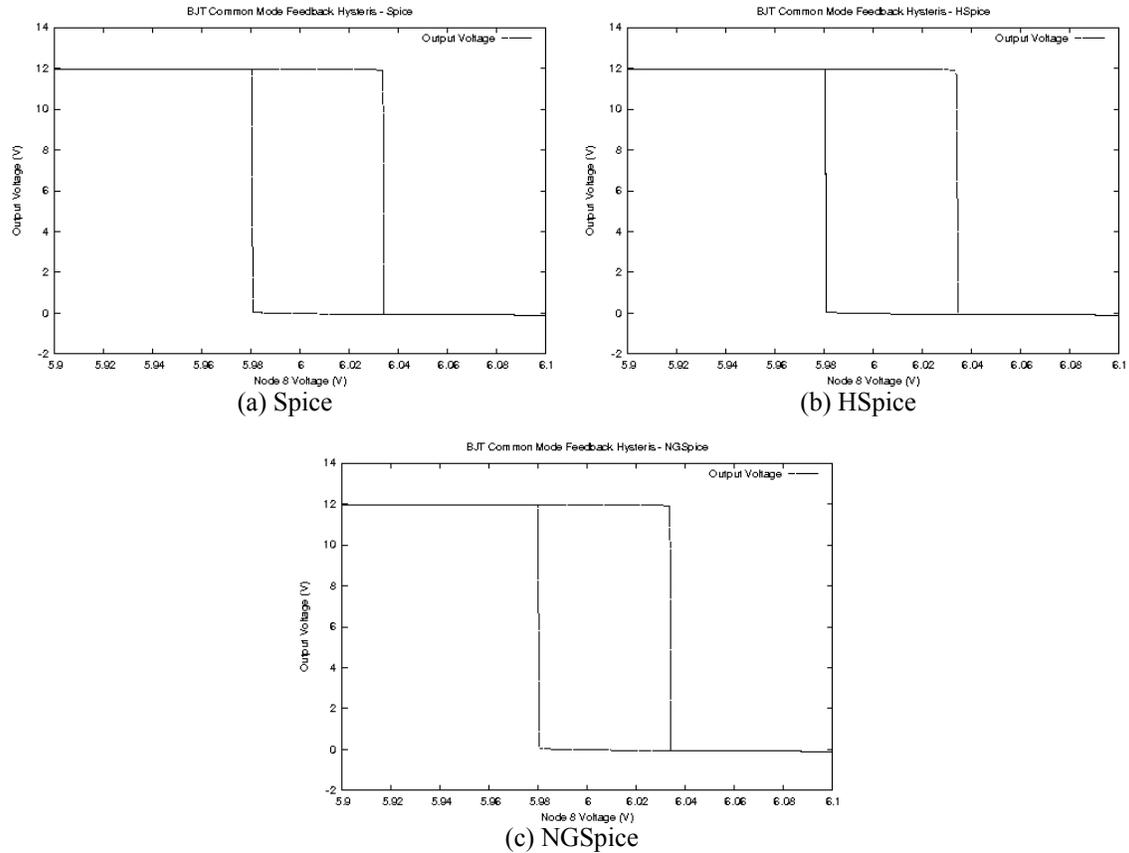
Figure 7 illustrates the BJT implementation of the common mode feedback circuit. Transistors  $Q_{1C}$ ,  $Q_{1D}$ ,  $Q_{2C}$ ,  $Q_{3C}$ ,  $Q_4$ , and  $Q_{4C}$  bias the output load transistor  $Q_3$ , the cascode transistor  $Q_8$ , and the differential pair  $Q_{5A}$  and  $Q_{5B}$ . The differential pair compares the output voltage against the desired common mode voltage  $V_{CM}$  and steer current provided by  $Q_{4C}$  in proportion to the

difference between the output voltage and  $V_{CM}$ . Transistors  $Q_2$  and  $Q_{6B}$  mirror the current output from  $Q_{5B}$ , drawing current through the cascode transistor  $Q_8$ . This current sinks the current sourced by the differential transistor  $Q_{5A}$  and any excess current will flow into or out of the bias current through  $Q_1$ . A feedback path is thus created that will adjust the output voltage until the differential current flowing through  $Q_1$  balances to zero, such that both  $Q_{5A}$  and  $Q_{5B}$  source equal currents, and with matched transistor properties, this will occur when the output voltage equals  $V_{CM}$ .



**Figure 7: Common Mode Feedback Circuit BJT Implementation**

The above analysis makes use of a simple linear approximation of the transistor’s behaviour. Due to nonlinearities, the actual operation of the circuit does indeed exhibit some unexpected and interesting properties. By disconnecting the output voltage feedback to node 8 and instead sweeping this voltage around  $V_{CM}$ , a small hysteresis is found, as shown in Figure 8. An Ebers-Moll BJT model was used and  $V_{CM}$  was set to 6V. Interestingly all three simulators produced very similar results.



**Figure 8: BJT Common Mode Feedback Hysteresis**

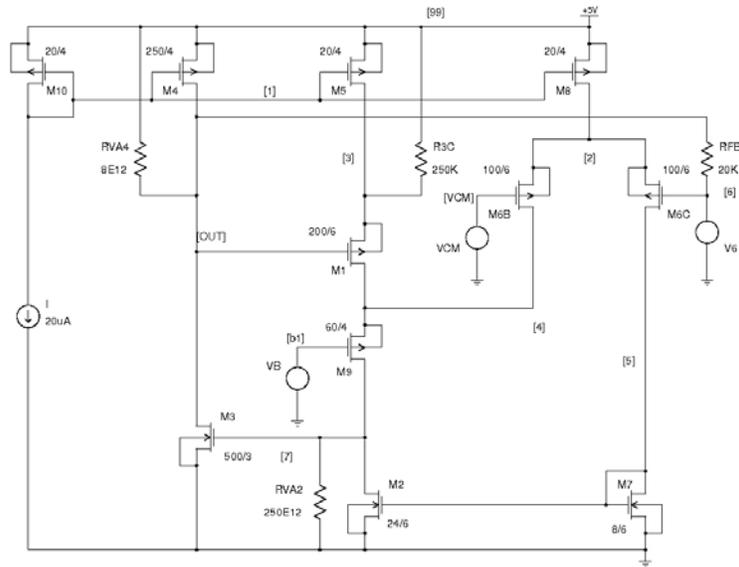
According to [5] at points inside the hysteresis, the circuit is capable of supporting three operating points: two of which are stable and are traced by the hysteresis curves while the third is unstable and lies somewhere in the middle of the hysteresis. To find the unstable point the circuit was biased to operate in the hysteresis region and provided with the appropriate initial condition. All three simulators converged to the same third operating point given in Table 4.

**Table 4: Common Mode Feedback Circuit Operating Points**

Operating Point (V)	OP1	OP2	OP3
Spice	11.95	-0.02	9.37
HSpice	11.94	-0.02	9.37
NGSpice	11.95	-0.02	9.37

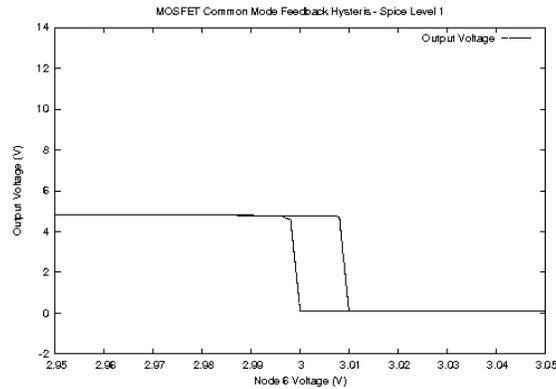
#### 4.2.2 MOSFET Implementation

The simplified version of Banu’s *et al.* [6] common mode feedback circuit is shown in Figure 9. The simplification follows the same procedures and operates in the same manner as is outlined in the previous section.

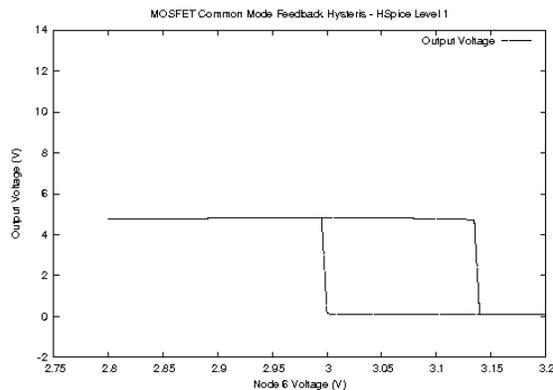


**Figure 9: Common Mode Feedback Circuit MOSFET Implementation**

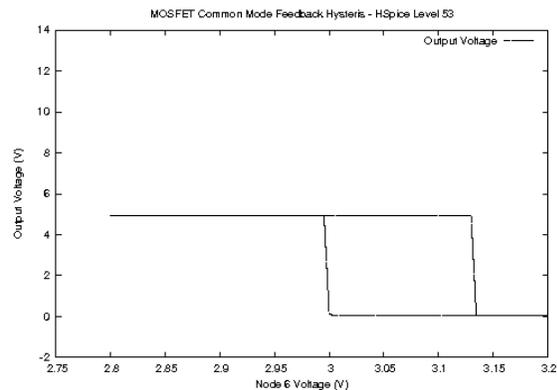
The MOSFET version was powered with a 5V supply and set to operate at a common mode voltage of 3V. Again, as with the BJT implementation, the input common mode voltage,  $V_6$ , was swept about 3V and a hysteresis was noticed as illustrated in Figure 10. Where available, higher order models were also used for comparison.



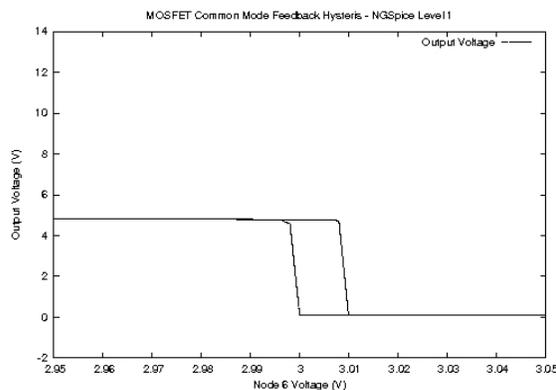
(a) Spice Shichman-Hodges



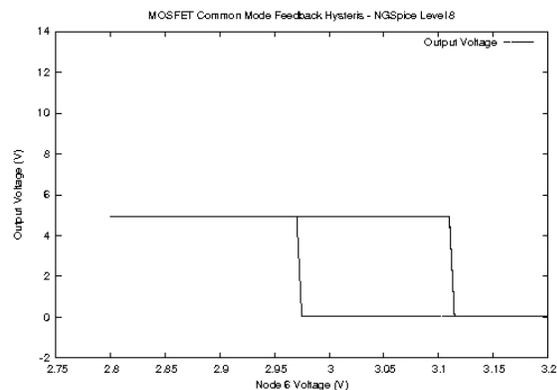
(b) HSpice Shichman-Hodges



(c) HSpice BSIM3



(d) NGSpice Shichman-Hodges



(e) NGSpice BSIM3

**Figure 10: MOSFET Common Mode Feedback Hysteresis**

Results for the MOSFET implementation varied considerably more than in the BJT case. As expected, the Spice and NGSpice Shichman-Hodges results were nearly identical, while results from the same model in HSpice were strikingly different. In the case of Spice and NGSpice, the hysteresis occurred in a much narrower region, between approximately 3.00V and 3.01V, while in HSpice this region stretched out considerably, from 3.0V to 3.15V.

Interestingly, though, the HSpice Shichman-Hodges results agree fairly well with the higher order HSpice and NGSpice BSIM3 model results. The hysteresis region for NGSpice's BSIM3

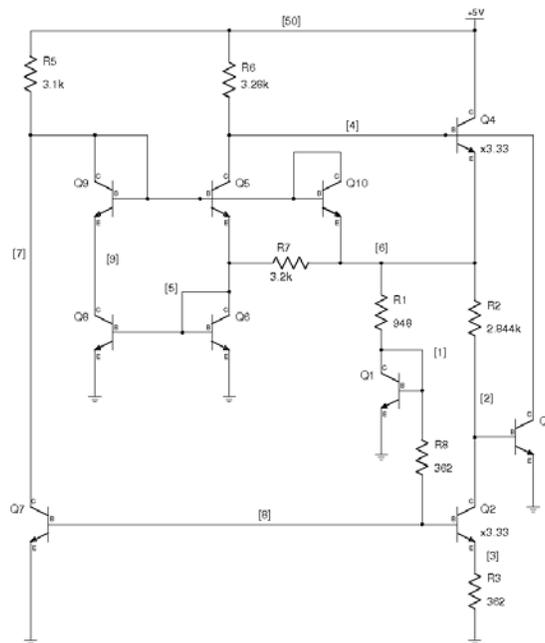
falls within approximately 2.97V to 3.12V, which compares with HSpice's Shichman-Hodges and BSIM3 hysteresis regions of roughly 3.0V to 3.15V.

Extrapolating from the BJT implementation, it is expected that a similar number of operating points should be found inside the hysteresis region for the MOSFET case. However, it proved difficult to find this third operating point in all simulators except for HSpice. As well, a close examination reveals some discrepancies between each simulator and model levels.

Nearly identical results were produced except in the number of iterations required to reach convergence, and strangely at node 1 for HSpice. Interestingly, the BSIM3 simulations produced very comparable results; however, considerable effort was required to converge with HSpice when simulating both the unstable and one of the stable operating points – more than 10,000 iterations were required to converge.

### 4.3 Hybrid Voltage Reference

The hybrid voltage reference circuit was examined by Banwell [7] and is shown in Figure 11. As a line regulator, its performance is best when the current through transistors  $Q_3$  and  $Q_6$  are equal. If transistors  $Q_6$  and  $Q_8$  and resistors  $R_5$  and  $R_6$  are matched, the line regulation is 0.7mV/V. As suggested by [5], a slight mismatch in  $R_5$  and  $R_6$  can improve the performance, but it could also lead to multiple operating points, which Banwell calls the circuit's "primary liability." A startup diode  $Q_{10}$  is then introduced to drive the circuit towards the desired stable DC operating point.



**Figure 11: Hybrid Voltage Reference Circuit**

To determine the operating points, this experiment mismatched  $R_5$  and  $R_6$ , which were set to 3.1k $\Omega$  and 3.28k $\Omega$ , respectively. The startup diode  $Q_{10}$  was not included and three operating points were found, as summarized in Table 5.

**Table 5: Hybrid Voltage Reference Operating Points without Startup Diode**

Operating Point (V)	OP1		OP2		OP3	
	Output	Iterations	Output	Iterations	Output	Iterations
Spice	0.67	23	0.71	23	1.20	24
HSpice	0.66	27	0.71	22	1.19	10
PSpice	0.67	35	0.71	17	1.20	26
NGSpice	0.67	30	0.71	20	1.20	9

As a test of the effectiveness of the startup diode, the circuit was simulated again but with the diode included. Only one operating point was found by each of the four simulators in this case, that of “OP3.” However, as shown in Table 6, the number of iterations to reach the stable operating point differs from the runs without the diode.

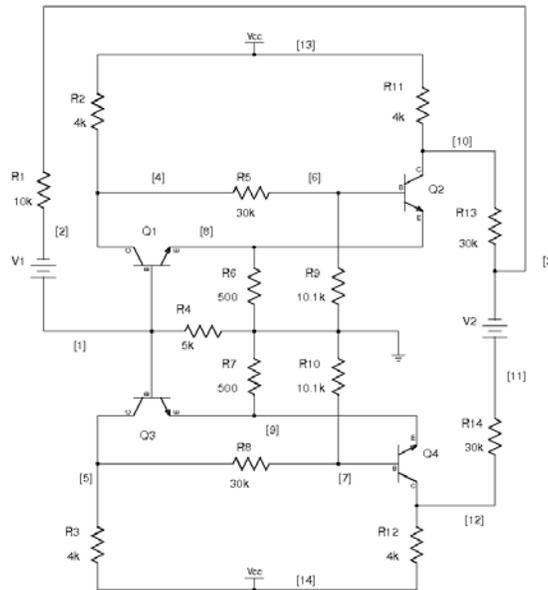
**Table 6: Hybrid Voltage Reference Operating Point with Startup Diode**

	Operating Point (V)	Iterations
Spice	1.20	20
HSpice	1.19	17
PSpice	1.20	15
NGSpice	1.20	13

While the iterations required to converge vary according to simulator, their resultant operating points are agreeable.

#### 4.4 Chua’s Circuit with Nine Distinct Operating Points

In a paper by Chua and Ushida [8], a circuit with nine distinct operating points was developed as a measure of the ability for circuit simulators and algorithms to solve difficult circuit problems. This circuit has since been used as a benchmark for various simulators and numerical techniques and as a result, its operating points are well known and understood. Figure 12 illustrates this circuit.



**Figure 12: Chua's Circuit with Nine Distinct Operating Points**

Results between all the simulators were again quite agreeable. No major discrepancies were found and in fact all the results were similar to within 1%. As well, there were no significant differences in the effort required by each simulator to reach convergence.

## 5 Discussion

Overall, the simulators performed well when faced with the difficult multiple operating point problem that the four test circuits present. The results gathered from Spice, HSpice, PSpice, and NGSpice agree to within some minute error, and in some cases, agree completely. However, HSpice provides a few curious examples which set it apart from the other flavours.

For the 741 opamp input stage, the operating points found from HSpice deviate quite a bit especially as the *RVA* resistance simulating the Early effect was increased. Also, HSpice exhibited a greater sensitivity to the switching effects even if the differential input was negligibly unbalanced. For the MOSFET implementation of the common mode feedback circuit, HSpice showed disagreement in the hysteresis region for an assumed equal model level, while the other flavours agreed within themselves. Also for this circuit, while the other flavours could not find the third unstable operating point, HSpice was able to do so.

From these results, it is clear that HSpice is set apart from its simulator brethren. We attribute this to its unique development as we described in Section 2. HSpice is generally regarded as an industry standard and thus, its numerical engine and features are well rounded and powerful. However, we cannot adequately claim that because of the attention given to HSpice, it is the better of the Spice flavours we have tested here. Instead, we have shed light on the argument that the simulators may provide conflicting results since their construction is also different.

Two circuits experienced notable convergence issues. NGSpice automatically invoked GMIN and source stepping for the 741 opamp input stage. For the more difficult operating points, GMIN stepping fails, and source stepping takes over. Interestingly, it should also be noted that for the 741 circuit, GMIN stepping in Spice does not yield the same solutions.

The BSIM3 implementation of the common mode feedback circuit in HSpice had convergence problems when solving for the unstable and surprisingly, one of the stable operating points. To compensate in these cases, the simulator itself enabled DCON, an “autoconvergence” feature that adjusted the DV, GRAMP, and ITL1 options. On the autoconvergence try, solutions were found for both problem operating points, but only after 10,000 iterations.

As mentioned, Chua’s nine operating point circuit is used as a benchmark to test simulators. All four of our Spice flavours performed well with this circuit and all nine operating points were found with relative ease. An interesting note here, however, is that when NGSpice invoked GMIN and source stepping after reaching its iteration limits, only one operating point was reached regardless of the starting conditions.

## 6 Conclusions

Our goal was to compare the performance of the numerical abilities of Spice3f5, HSpice, PSpice, and NGSpice by having them solve circuits known to possess multiple DC operating points. It was expected that the simulators would encounter convergence issues and techniques designed to overcome those problems were employed. While simpler techniques, such as the use of extra iterations and initial conditions, were used liberally by us, the simulators themselves invoked GMIN and source stepping on a couple of occasions.

The Spice-derived simulators have evolved considerably since the original Berkeley Spice was developed. More enhanced numerical solver engines and new features such as the convergence techniques, are built in so that even the more difficult circuits can be solved. In terms of performance, we have shown that the four simulators used in this investigation would be sufficient in solving circuits similar to those used here, provided that the user is willing to deal with convergence strategies. In terms of price, we have accessed both Spice3f5 and NGSpice free of charge. However, technical support is inconsistent when compared to the commercial versions of HSpice and PSpice.

While each simulator has its own advantages, it is hard for us to determine which is the best. In closing, we acknowledge that every situation will demand which simulator is required, and not discounting user preference, there are diverse simulators available to meet the needs of all.

## 7 References

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## Appendix A: Spice Descriptions of Circuits

opamp741.cir 741 opamp input stage circuit

```
*****
* signal sources
vpos  1      vcm  0  ac
vneg  2      vcm -753.28u  dc
vcm   vcm    0    0

*****
* power supplies
vcc   99     0      dc    +12v
vee   98     0      dc    -12v

*****
* bjts
* qxxx nc      nb      ne  <ns>  mname
q1    4        1      13  13    ntype
q2    4        2      12  12    ntype
q3    21       5      13  13    ptype
q4    22       5      12  12    ptype
q5    21       3      61  61    ntype
q6    22       3      62  62    ntype
q7    99       21     3    3     ntype
q8    4        4      99  99    ptype
q9    5        4      99  99    ptype
q10   5        11     7    7     ntype
q11   11       11     98  98    ntype

*****
* resistors
* rxxx n1      n2      value
r1    61       98      1k
r2    3        98      50k
r3    62       98      1k
r4    7        98      5k
r5    99       11      39k
rva5  21       61      1e12
rva6  22       62      1e12

*****
* models
.model ntype npn
.model ptype pnp

*****
* analysis
.op
.options gmin=1e-22 abstol=1e-15 chgtol=1e-18 vntol=1e-9 itl1=50

.end
```

cmbias-bjt.cir difficult common mode bias circuit BJT

```

*****
* signal sources
vcomm vcm      0          6.0 dc
v8      8      0          6.0 dc

*****
* power supplies
vcc     99      0          dc      +12v
vee     98      0          dc      -12v

*****
* bjts
* qxxx nc      nb      ne <ns> mname  area
q1      3      out     2  2  ptype  2
q1c     1      vbias   98 98  ntype  1
q1d     vbias  vbias   98 98  ntype  1
q2      12     5       98 98  ntype  3
q2c     1      1       99 99  ptype  2
q3      out    12     98 98  ntype  50
q3c     2      1       99 99  ptype  1
q4      out    1       99 99  ptype  25
q4c     7      1       99 99  ptype  1
q5a     3      vcm     7  7  ptype  1
q5b     5      8       7  7  ptype  1
q6b     5      5       98 98  ntype  1
q8      12     0       3  3  ptype  11.15

*****
* resistors
* rxxx n1      n2      value
rva2    12     98     250e12
rva4    99     out    8e12
r3c     99     2      250k
rb      vbias  0      107.5k
rfb     out    8      20k
*rva7   7      0      250e12

*****
* models
.model ntype npn *level=8 *vers=503 avl=100
.model ptype pnp *level=8 *vers=503 avl=100

*****
* analysis
.nodeset v(out)=1.19e+01
.op
.options post gmin=1e-24 *converge=3 *dchold=10 dcfor=10 *dcon=-1

.end

```

```
cmbias-mosfet.cir difficult common mode bias circuit MOSFET

*****
* signal sources
vcomm cm 0 3.0
v6 6 0 3.0
vb1 b1 0 2.0

*****
* power supplies
vdd 99 0 dc 5
ibias 1 0 dc 20u

*****
* mosfets
*mx d g s b mname l w
m1 4 ou 3 3 pt l=6u w=200u
m2 7 5 0 0 nt l=6u w=24u
m3 ou 7 0 0 nt l=6u w=500u
m4 ou 1 99 99 pt l=4u w=250u
m5 3 1 99 99 pt l=4u w=20u
m6b 4 cm 2 2 pt l=6u w=100u
m6c 5 6 2 2 pt l=6u w=100u
m7 5 5 0 0 nt l=6u w=8u
m8 2 1 99 99 pt l=4u w=20u
m9 7 b1 4 4 nt l=4u w=60u
m10 1 1 99 99 pt l=4u w=20u

*****
* resistors
* rxxx n1 n2 value
*rva2 7 0 250e12
*rva4 99 ou 8e12
*r3c 99 3 250e6
*rb vbias 0 107.5k
rf ou 6 20k

*****
* models
.model nt nmos level=1
.model pt pmos level=1

*****
* analysis
.nodeset v(ou)=4.75
.op
.options gmin=1e-24 abstol=1e-24 chgtol=1e-18 reltol=0.000001 itl1=10000

.end
```

hybridref.cir hybrid voltage reference circuit

```
*****
* power supplies
vcc 50 0 dc +5V

*****
* bjts
* qxxx nc nb ne <ns> mname
q1 1 1 0 ntype
q2 2 8 3 ntype
q3 4 2 0 ntype
q4 50 4 6 ntype
q5 4 7 5 ntype
q6 5 5 0 ntype
q7 7 8 0 ntype
q8 9 5 0 ntype
q9 7 7 9 ntype
q10 7 7 6 ntype

*****
* resistors
* rxxx n1 n2 value
r1 6 1 948
r2 6 2 2.844k
r3 3 0 362
r5 50 7 3.1k
r6 50 4 3.28k
r7 5 6 3.2k
r8 1 8 362
*rload 6 0 1k

*****
* models
.model ntype npn

*****
* analysis
.nodeset v(6)=1.1
.op
.options post *converge=3

.end
```

nineop.cir Chua's circuit with nine operating points

```
*****
* power supplies
vcc1 13 0 12
vcc2 14 0 12
v1 1 2 10
v2 11 3 2

*****
* bjts
* qxxx nc nb ne <ns> mname area
q1 4 1 8 ntype
q2 10 6 8 ntype
q3 5 1 9 ntype
q4 12 7 9 ntype

*****
* resistors
* rx n1 n2 value
r1 3 2 10k
r2 13 4 4k
r3 5 14 4k
r4 1 0 5k
r5 4 6 30k
r6 8 0 0.5k
r7 9 0 0.5k
r8 5 7 30k
r9 6 0 10.1k
r10 7 0 10.1k
r11 13 10 4k
r12 14 12 4k
r13 10 3 30k
r14 11 12 30k

*****
* models
.model ntype npn is=1e-9 bf=100 br=1 temp=299

*****
* analysis

* OP1
*.nodeset v(1)=1.77 v(2)=-8.22 v(3)=-1.10 v(4)=1.46 v(5)=1.46 v(6)=0.36
+v(7)=0.36 v(8)=1.38 v(9)=1.38 v(10)=10.45 v(11)=0.89 v(12)=10.69
* OP2
*.nodeset v(1)=1.78 v(2)=-8.21 v(3)=-2.55 v(4)=7.75 v(5)=1.47 v(6)=1.80
+v(7)=0.37 v(8)=1.42 v(9)=1.39 v(10)=3.34 v(11)=-0.55 v(12)=10.52
* OP3
*.nodeset v(1)=1.76 v(2)=-8.23 v(3)=-2.93 v(4)=1.46 v(5)=9.85 v(6)=0.36
+v(7)=1.82 v(8)=1.38 v(9)=1.44 v(10)=10.23 v(11)=-0.93 v(12)=1.57
* OP4
*.nodeset v(1)=1.81 v(2)=-8.18 v(3)=-4.41 v(4)=9.03 v(5)=7.95 v(6)=1.86
+v(7)=1.84 v(8)=1.48 v(9)=1.46 v(10)=1.59 v(11)=-2.41 v(12)=2.89
* OP5
*.nodeset v(1)=1.84 v(2)=-8.15 v(3)=-4.30 v(4)=8.09 v(5)=8.09 v(6)=1.87
+v(7)=1.87 v(8)=1.49 v(9)=1.49 v(10)=2.34 v(11)=-2.30 v(12)=2.57
```

```
* OP6
*.nodeset v(1)=1.78 v(2)=-8.21 v(3)=-2.55 v(4)=1.47 v(5)=7.75 v(6)=0.37
+v(7)=1.80 v(8)=1.39 v(9)=1.42 v(10)=10.28 v(11)=-0.55 v(12)=3.57
* OP7
*.nodeset v(1)=1.76 v(2)=-8.23 v(3)=-2.93 v(4)=9.62 v(5)=1.46 v(6)=1.82
+v(7)=0.36 v(8)=1.44 v(9)=1.38 v(10)=1.54 v(11)=-0.935 v(12)=10.47
* OP8
*.nodeset v(1)=1.81 v(2)=-8.18 v(3)=-4.44 v(4)=7.90 v(5)=9.34 v(6)=1.83
+v(7)=1.85 v(8)=1.45 v(9)=1.47 v(10)=2.76 v(11)=-2.44 v(12)=1.58
* OP9
*.nodeset v(1)=1.72 v(2)=-8.27 v(3)=-4.76 v(4)=9.74 v(5)=9.96 v(6)=1.78
+v(7)=1.78 v(8)=1.40 v(9)=1.40 v(10)=1.49 v(11)=-2.76 v(12)=1.50

.op
.options itll=5

.end
```

## Appendix B: Listings of Operating Point Results

### B.1 741 Opamp Input Stage

	RVA = 1e12			RVA = 1e14		
	SPICE	HSPICE	NGSPICE	SPICE	HSPICE	NGSPICE
V(1)	0.00	0.00	0.00	0.00	0.00	0.00
V(2)	0.00	0.00	0.00	0.00	0.00	0.00
V(3)	-11.34	-11.34	-11.34	-11.34	-11.34	-11.34
V(4)	11.33	11.33	11.33	11.33	11.33	11.33
V(5)	-1.31	-1.30	-1.31	-1.31	-1.30	-1.31
V(7)	-11.91	-11.91	-11.91	-11.91	-11.91	-11.91
V(11)	-11.24	-11.24	-11.24	-11.24	-11.24	-11.24
V(12)	-0.65	-0.65	-0.65	-0.65	-0.65	-0.65
V(13)	-0.65	-0.65	-0.65	-0.65	-0.65	-0.65
V(21)	-10.68	-10.68	-10.68	-10.68	-10.68	-10.68
V(22) = OUT	-5.70	-5.81	-5.88	-6.34	-4.03	-6.46
V(61)	-11.99	-11.99	-11.99	-11.99	-11.99	-11.99
V(62)	-11.99	-11.99	-11.99	-11.99	-11.99	-11.99
V(98)	-12.00	-12.00	-12.00	-12.00	-12.00	-12.00
V(99)	12.00	12.00	12.00	12.00	12.00	12.00
Vcm	0.00	0.00	0.00	0.00	0.00	0.00
Iterations	28	51	30	28	52	29
GMIN	-	-	23	-	-	23
Source Step	-	-	-	-	-	-

	RVA = 1e16			RVA = 1e17		
	SPICE	HSPICE	NGSPICE	SPICE	HSPICE	NGSPICE
V(1)	0.00	0.00	0.00	0.00	0.00	0.00
V(2)	0.00	0.00	0.00	0.00	0.00	0.00
V(3)	-11.34	-11.34	-11.34	-11.34	-11.34	-11.34
V(4)	11.33	11.33	11.33	11.33	11.33	11.33
V(5)	-1.31	-1.30	-1.31	-1.31	-1.30	-1.31
V(7)	-11.91	-11.91	-11.91	-11.91	-11.91	-11.91
V(11)	-11.24	-11.24	-11.24	-11.24	-11.24	-11.24
V(12)	-0.65	-0.65	-0.65	-0.65	-0.65	-0.65
V(13)	-0.65	-0.65	-0.65	-0.65	-0.65	-0.65
V(21)	-10.68	-10.68	-10.68	-10.68	-10.68	-10.68
V(22) = OUT	-6.18	-4.01	-5.82	-5.99	-4.01	-6.18
V(61)	-11.99	-11.99	-11.99	-11.99	-11.99	-11.99
V(62)	-11.99	-11.99	-11.99	-11.99	-11.99	-11.99
V(98)	-12.00	-12.00	-12.00	-12.00	-12.00	-12.00
V(99)	12.00	12.00	12.00	12.00	12.00	12.00
Vcm	0.00	0.00	0.00	0.00	0.00	0.00
Iterations	42	52	41	83	52	87
GMIN	-	-	23	-	-	fail
Source Step	-	-	-	-	-	-

RVA = 1e18

	<b>SPICE</b>	<b>HSPICE</b>	<b>NGSPICE</b>
V(1)	-	0.00	0.00
V(2)	-	0.00	0.00
V(3)	-	-11.34	-11.34
V(4)	-	11.33	11.33
V(5)	-	-1.30	-1.31
V(7)	-	-11.91	-11.91
V(11)	-	-11.24	-11.24
V(12)	-	-0.65	-0.65
V(13)	-	-0.65	-0.65
V(21)	-	-10.68	-10.68
V(22) = OUT	-	-4.01	-6.81
V(61)	-	-11.99	-11.99
V(62)	-	-11.99	-11.99
V(98)	-	-12.00	-12.00
V(99)	-	12.00	12.00
Vcm	-	0.00	0.00
Iterations	-	52	979
GMIN	-	-	<i>fail</i>
Source Step	-	-	32

Notes:

- 1) NGSpice automatically invokes GMIN and source stepping.

## B.2 Common Mode Feedback Circuit BJT Implementation

	OP1			OP2		
	SPICE	HSPICE	NGSPICE	SPICE	HSPICE	NGSPICE
V(1)	11.33	11.33	11.33	11.31	11.31	11.31
V(2)	11.98	11.98	11.98	0.68	0.68	0.68
V(3)	0.59	0.58	0.59	0.65	0.64	0.65
V(5)	-11.36	-11.36	-11.36	-11.33	-11.33	-11.33
V(7)	6.65	6.65	6.65	6.68	6.67	6.68
V(8)	6.00	6.00	6.00	6.00	6.00	6.00
V(12)	-11.96	-11.96	-11.96	-11.32	-11.32	-11.32
V(98)	-12.00	-12.00	-12.00	-12.00	-12.00	-12.00
V(99)	12.00	12.00	12.00	12.00	12.00	12.00
Vbias	-11.28	-11.28	-11.28	-11.28	-11.28	-11.28
Vcm	6.00	6.00	6.00	6.00	6.00	6.00
Vout	11.95	11.94	11.95	-0.02	-0.02	-0.02
Iterations	11	23	22	8	12	17

	OP3		
	SPICE	HSPICE	NGSPICE
V(1)	11.31	11.31	11.31
V(2)	10.05	10.04	10.05
V(3)	0.64	0.64	0.64
V(5)	-11.33	-11.33	-11.33
V(7)	6.68	6.67	6.68
V(8)	6.00	6.00	6.00
V(12)	-11.33	-11.33	-11.33
V(98)	-12.00	-12.00	-12.00
V(99)	12.00	12.00	12.00
Vbias	-11.28	-11.28	-11.28
Vcm	6.00	6.00	6.00
Vout	9.37	9.37	9.37
Iterations	6	44	12

### B.3 Common Mode Feedback Circuit MOSFET Implementation

OP1	Basic -- Shichman-Hodges			BSIM3	
	SPICE	HSPICE	NGSPICE	HSPICE	NGSPICE
V(1)	4.37	3.90	4.37	2.68	2.75
V(2)	3.28	3.51	3.25	4.85	4.84
V(3)	3.16	3.22	3.06	4.76	4.79
V(4)	3.15	3.20	3.05	4.76	4.78
V(5)	0.87	0.98	0.87	2.12	2.06
V(6)	3.04	3.01	3.01	3.04	3.04
V(7)	2.58	2.63	2.49	4.20	4.22
V(99)	5.00	5.00	5.00	5.00	5.00
Vb1	2.00	2.00	2.00	2.00	2.00
Vcm	3.00	3.00	3.00	3.00	3.00
Vout	0.09	0.09	0.10	0.03	0.02
Iterations	7	19	23	10085	17

OP2	Basic -- Shichman-Hodges			BSIM3	
	SPICE	HSPICE	NGSPICE	HSPICE	NGSPICE
V(1)	4.37	3.90	4.37	2.68	2.75
V(2)	3.25	3.51	3.25	4.84	4.82
V(3)	4.89	4.99	4.89	5.00	5.00
V(4)	0.32	0.19	0.32	0.08	0.09
V(5)	0.86	0.98	0.86	2.10	2.01
V(6)	3.01	3.01	3.01	3.04	3.04
V(7)	0.29	0.17	0.29	0.06	0.07
V(99)	5.00	5.00	5.00	5.00	5.00
Vb1	2.00	2.00	2.00	2.00	2.00
Vcm	3.00	3.00	3.00	3.00	3.00
Vout	4.75	4.81	4.75	4.93	4.92
Iterations	9	14	30	25	27

OP3	Basic -- Shichman-Hodges			BSIM3	
	SPICE	HSPICE	NGSPICE	HSPICE	NGSPICE
V(1)	-	3.90	-	2.68	-
V(2)	-	3.51	-	4.84	-
V(3)	-	4.39	-	4.84	-
V(4)	-	0.69	-	2.52	-
V(5)	-	0.98	-	2.10	-
V(6)	-	3.01	-	3.04	-
V(7)	-	0.62	-	1.97	-
V(99)	-	5.00	-	5.00	-
Vb1	-	2.00	-	2.00	-
Vcm	-	3.00	-	3.00	-
Vout	-	3.90	-	3.02	-
Iterations	-	19	-	10094	-

Notes:

1) For HSpice trials over 10,000 iterations, autoconvergence was invoked.

### B.4 Hybrid Voltage Reference without Startup Diode

OP1

	SPICE	HSPICE	PSPICE	NGSPICE
V(1)	0.66	0.65	0.66	0.66
V(2)	0.59	0.59	0.59	0.59
V(3)	0.01	0.01	0.01	0.01
V(4)	1.28	1.27	1.28	1.28
V(5)	0.78	0.77	0.78	0.78
V(6) = OUT	0.67	0.67	0.67	0.67
V(7)	1.55	1.54	1.55	1.55
V(8)	0.66	0.65	0.66	0.66
V(9)	0.78	0.77	0.78	0.78
V(50)	5.00	5.00	5.00	5.00
Iterations	23	27	35	30

OP2

	SPICE	HSPICE	PSPICE	NGSPICE
V(1)	0.68	0.68	0.68	0.68
V(2)	0.57	0.57	0.57	0.57
V(3)	0.02	0.02	0.02	0.02
V(4)	1.38	1.38	1.38	1.38
V(5)	0.78	0.77	0.78	0.78
V(6) = OUT	0.71	0.71	0.71	0.71
V(7)	1.55	1.54	1.55	1.55
V(8)	0.68	0.68	0.68	0.68
V(9)	0.78	0.77	0.78	0.78
V(50)	5.00	5.00	5.00	5.00
Iterations	23	22	17	20

OP3

	SPICE	HSPICE	PSPICE	NGSPICE
V(1)	0.75	0.75	0.75	0.75
V(2)	0.75	0.74	0.75	0.75
V(3)	0.06	0.06	0.06	0.06
V(4)	1.94	1.93	1.94	1.94
V(5)	0.76	0.76	0.76	0.76
V(6) = OUT	1.20	1.19	1.20	1.20
V(7)	1.52	1.51	1.52	1.52
V(8)	0.75	0.75	0.75	0.75
V(9)	0.76	0.75	0.76	0.76
V(50)	5.00	5.00	5.00	5.00
Iterations	24	10	26	9

### B.5 Hybrid Voltage Reference with Startup Diode

	<b>SPICE</b>	<b>HSPICE</b>	<b>PSPICE</b>	<b>NGSPICE</b>
V(1)	0.75	0.75	0.75	0.75
V(2)	0.75	0.74	0.75	0.75
V(3)	0.06	0.06	0.06	0.06
V(4)	1.94	1.93	1.94	1.94
V(5)	0.76	0.76	0.76	0.76
V(6) = OUT	1.20	1.19	1.20	1.20
V(7)	1.52	1.51	1.52	1.52
V(8)	0.75	0.75	0.75	0.75
V(9)	0.76	0.75	0.76	0.76
V(50)	5.00	5.00	5.00	5.00
Iterations	20	17	15	13

### B.6 Chua's Nine Operating Point Circuit

<b>SPICE</b>	<b>OP1</b>	<b>OP2</b>	<b>OP3</b>	<b>OP4</b>	<b>OP5</b>	<b>OP6</b>	<b>OP7</b>	<b>OP8</b>	<b>OP9</b>
V(1)	1.77	1.78	1.77	1.82	1.85	1.78	1.77	1.81	1.73
V(2)	-8.23	-8.22	-8.23	-8.18	-8.15	-8.22	-8.23	-8.19	-8.27
V(3)	-1.11	-2.56	-2.98	-4.41	-4.31	-2.56	-2.93	-4.44	-4.76
V(4)	1.46	7.75	1.46	9.05	8.09	1.47	9.63	7.91	9.76
V(5)	1.46	1.47	9.85	7.95	8.09	7.75	1.46	9.35	9.97
V(6)	0.37	1.80	0.37	1.86	1.87	0.37	1.82	1.83	1.78
V(7)	0.37	0.37	1.83	1.84	1.87	1.80	0.37	1.86	1.79
V(8)	1.39	1.43	1.38	1.48	1.50	1.40	1.44	1.46	1.40
V(9)	1.39	1.40	1.44	1.47	1.50	1.43	1.39	1.48	1.41
V(10)	10.46	3.34	10.24	1.59	2.34	10.29	1.54	2.77	1.50
V(11)	0.89	-0.56	-0.98	-2.41	-2.31	-0.56	-0.93	-2.44	-2.76
V(12)	10.69	10.52	1.54	2.90	2.58	3.58	10.48	1.58	1.50
V(13)	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00
V(14)	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00
Iterations	5	5	7	4	4	5	4	5	5

<b>HSPICE</b>	OP1	OP2	OP3	OP4	OP5	OP6	OP7	OP8	OP9
V(1)	1.77	1.78	1.77	1.82	1.85	1.78	1.77	1.81	1.73
V(2)	-8.23	-8.22	-8.23	-8.18	-8.15	-8.22	-8.23	-8.19	-8.27
V(3)	-1.11	-2.56	-2.98	-4.41	-4.31	-2.56	-2.94	-4.45	-4.76
V(4)	1.46	7.74	1.46	9.03	8.09	1.47	9.63	7.90	9.74
V(5)	1.46	1.47	9.85	7.95	8.09	7.74	1.46	9.34	9.95
V(6)	0.37	1.80	0.37	1.86	1.87	0.37	1.82	1.83	1.78
V(7)	0.37	0.37	1.82	1.84	1.87	1.80	0.37	1.86	1.79
V(8)	1.39	1.43	1.38	1.48	1.50	1.40	1.44	1.46	1.40
V(9)	1.39	1.40	1.44	1.47	1.50	1.43	1.39	1.48	1.41
V(10)	10.46	3.35	10.24	1.59	2.34	10.29	1.54	2.76	1.50
V(11)	0.89	-0.56	-0.98	-2.41	-2.31	-0.56	-0.94	-2.45	-2.76
V(12)	10.69	10.52	1.54	2.89	2.57	3.59	10.48	1.58	1.50
V(13)	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00
V(14)	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00
Iterations	6	6	8	5	6	6	5	6	6

<b>PSPICE</b>	OP1	OP2	OP3	OP4	OP5	OP6	OP7	OP8	OP9
V(1)	1.78	1.79	1.77	1.82	1.85	1.79	1.77	1.81	1.73
V(2)	-8.22	-8.21	-8.23	-8.18	-8.15	-8.21	-8.23	-8.19	-8.27
V(3)	-1.10	-2.56	-2.98	-4.41	-4.30	-2.56	-2.93	-4.44	-4.76
V(4)	1.46	7.77	1.46	9.06	8.10	1.47	9.63	7.91	9.78
V(5)	1.46	1.47	9.85	7.96	8.10	7.77	1.46	9.36	9.99
V(6)	0.37	1.81	0.37	1.86	1.87	0.37	1.83	1.84	1.78
V(7)	0.37	0.37	1.83	1.85	1.87	1.81	0.37	1.86	1.79
V(8)	1.39	1.43	1.38	1.48	1.49	1.40	1.44	1.46	1.40
V(9)	1.39	1.40	1.44	1.47	1.49	1.43	1.38	1.48	1.41
V(10)	10.46	3.33	10.24	1.59	2.35	10.29	1.54	2.78	1.49
V(11)	0.90	-0.56	-0.98	-2.41	-2.30	-0.56	-0.93	-2.44	-2.76
V(12)	10.69	10.52	1.54	2.91	2.59	3.57	10.48	1.58	1.50
V(13)	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00
V(14)	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00
Iterations	7	8	11	6	6	8	7	7	7

<b>NGSPICE</b>	OP1	OP2	OP3	OP4	OP5	OP6	OP7	OP8	OP9
V(1)	1.77	1.78	1.77	1.82	1.85	1.78	1.77	1.81	1.73
V(2)	-8.23	-8.22	-8.23	-8.18	-8.15	-8.22	-8.23	-8.19	-8.27
V(3)	-1.11	-2.56	-2.98	-4.41	-4.31	-2.56	-2.93	-4.44	-4.76
V(4)	1.46	7.75	1.46	9.05	8.09	1.47	9.63	7.91	9.76
V(5)	1.46	1.47	9.85	7.95	8.09	7.75	1.46	9.35	9.97
V(6)	0.37	1.80	0.37	1.86	1.87	0.37	1.82	1.83	1.78
V(7)	0.37	0.37	1.83	1.84	1.87	1.80	0.37	1.86	1.79
V(8)	1.39	1.43	1.38	1.48	1.50	1.40	1.44	1.46	1.40
V(9)	1.39	1.40	1.44	1.47	1.50	1.43	1.39	1.48	1.41
V(10)	10.46	3.34	10.24	1.59	2.34	10.29	1.54	2.77	1.50
V(11)	0.89	-0.56	-0.98	-2.41	-2.31	-0.56	-0.93	-2.44	-2.76
V(12)	10.69	10.52	1.54	2.90	2.58	3.58	10.48	1.58	1.50
V(13)	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00
V(14)	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00
Iterations	8	8	10	7	6	8	7	8	8